

Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity

Authors: Srinivas Nudurupati, Jim Trudeau

Associated Part Family: CY8C63BL

Software Version: PSoC Creator™ 4.2

Associated Application Notes and Code Examples: [Click here.](#)

More code examples? We heard you.

To access an ever-growing list of hundreds of PSoC code examples, please visit our [code examples web page](#). You can also explore the PSoC video library [here](#).

AN210781 introduces you to PSoC® 6 MCU with Bluetooth Low Energy (BLE) Connectivity, a dual-CPU Arm® Cortex®-M4 and Cortex-M0+ based programmable system-on-chip that integrates a BLE 5.0 system, the latest-generation of CapSense® technology, and a host of security features. This application note helps you explore the PSoC 6 MCU with BLE architecture and development tools and shows you how to create your first project using PSoC Creator, export the project to a third-party integrated development environment (IDE), and continue your firmware development. It also guides you to more resources available online to accelerate your learning about PSoC 6 MCU with BLE Connectivity. To get started with the PSoC 6 MCU device family, see [AN221774](#) – Getting Started with PSoC 6 MCU.

Contents

1	Introduction.....	2	5.5	Part 2: Implement the Design	20
1.1	Prerequisites	4	5.6	Part 3: Generate Source Code	36
2	Development Ecosystem.....	4	5.7	Part 4: Write the Firmware	38
2.1	PSoC Resources	4	5.8	Part 5: Build the Project, Program the Device...46	
2.2	Firmware/Application Development	5	5.9	Part 6: Test Your Design.....	49
2.3	Support for Other IDEs	7	6	Summary	54
2.4	RTOS Support	9	7	Related Application Notes and Code Examples	54
2.5	Debugging.....	9	Appendix A.	Glossary.....	56
2.6	CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit	9	Appendix B.	BLE Protocol	57
2.7	CySmart Host Emulation Tool and Mobile Applications	9	Appendix C.	Device Features.....	66
3	Device Features	10	Appendix D.	Cypress IoT Development Tools.....	73
4	Development Setup	12	Document History.....		77
5	My First PSoC 6 MCU Design With BLE	14	Worldwide Sales and Design Support.....		78
5.1	Using These Instructions.....	14	Products		78
5.2	Before You Begin.....	14	PSoC® Solutions		78
5.3	About the Design	15	Cypress Developer Community.....		78
5.4	Part 1: Create a New Project from Scratch	16	Technical Support		78

1 Introduction

PSoC 6 MCU with BLE Connectivity, hereafter called as PSoC 6 BLE, is Cypress' ultra-low-power PSoC device specifically designed for wearables and Internet of Things (IoT) products. It establishes a new low-power standard for today's "always-on" applications. The Cypress PSoC 6 BLE device is a programmable embedded system-on-chip that integrates the following on a single chip:

- Dual-CPU microcontroller: CM4 and CM0+
- BLE 5.0 subsystem
- Programmable analog and digital peripherals
- Up to 1 MB of flash and 288 KB of SRAM
- Fourth-generation CapSense technology

PSoC 6 BLE is suitable for a variety of power-sensitive connected applications such as:

- Smart watches and fitness trackers
- Connected medical devices
- Smart home sensors and controllers
- Smart home appliances
- Gaming controllers
- Sports, smart phone, and virtual reality (VR) accessories
- Industrial sensor nodes
- Industrial logic controllers
- Advanced remote controllers

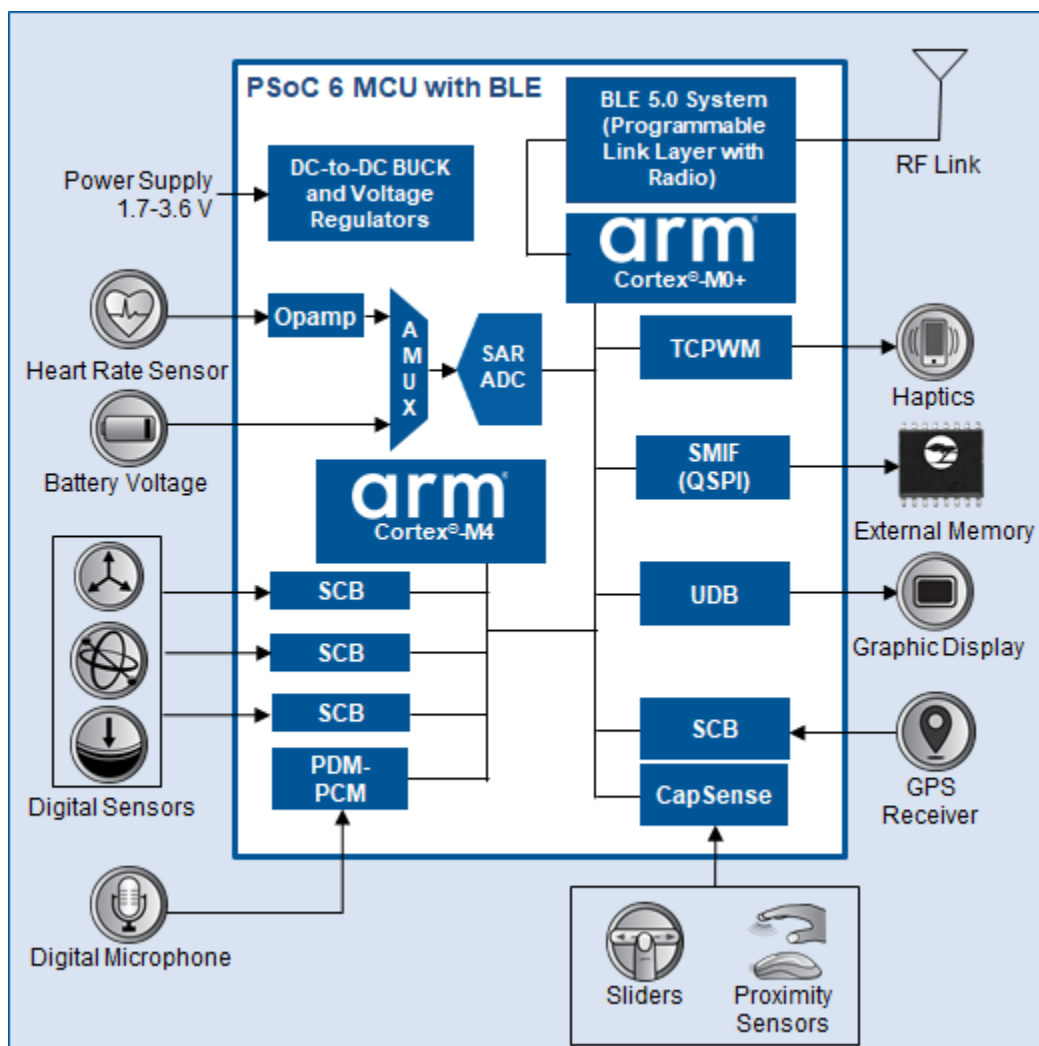
PSoC 6 BLE provides a cost-effective and small-footprint alternative to the combination of an MCU and a BLE radio. The programmable analog and digital subsystems allow flexibility and dynamic fine-tuning of the design using [PSoC Creator](#) the schematic-based design tool for developing PSoC 6 BLE applications. To develop a BLE application, you do not need a working knowledge of the complex BLE protocol stack. Cypress provides an easy-to-configure, no-cost GUI-based BLE Component in PSoC Creator that abstracts the protocol complexity.

BLE is an ultra-low-power wireless standard defined by the Bluetooth Special Interest Group (SIG) for short-range communication. PSoC 6 BLE integrates a BLE 4.2 radio and a royalty-free protocol stack with enhanced security, privacy, and throughput compliant with the BLE 5.0 specification.

Cypress' fourth-generation capacitive touch-sensing feature in PSoC 6 BLE devices, known as CapSense, offers unprecedented signal-to-noise ratio (SNR); best-in-class waterproofing; and a wide variety of sensor types such as buttons, sliders, track pads, and proximity sensors. CapSense user interfaces are gaining popularity in wearable electronic devices such as activity monitors and health and fitness equipment. The CapSense solution works in noisy environments and in the presence of liquids.

PSoC 6 BLE enables ultra-low-power connected applications with an integrated solution. Figure 1 shows the application-level block diagram of a fitness tracker based on PSoC 6 BLE.

Figure 1. Fitness Tracker Application Block Diagram



The device provides a one-chip solution and includes:

- A low-power BLE 5.0 system that can sustain up to four simultaneous connections
- A buck converter for ultra-low-power operation
- An analog front end (AFE) within the device to condition and measure heart rate sensor outputs and to monitor battery voltage
- Serial communication blocks (SCBs) to interface with multiple digital sensors including a global positioning system (GPS) module
- A Pulse-Density Modulation (PDM) Pulse Code Modulation (PCM) hardware engine and digital microphone interface for voice
- CapSense technology for reliable touch and proximity sensing
- A serial memory interface (SMIF) that supports an interface to Quad-Serial Peripheral Interface (QSPI)-enabled external memory
- Digital logic (UDB) and peripherals (TCPWM) to drive the display and haptics

See Device Features and [Appendix C](#) for more details on device features.

This application note introduces you to the capabilities of PSoC 6 BLE, gives an overview of the development ecosystem, and gets you started with a simple design: a Bluetooth SIG standard [Find Me Profile \(FMP\)](#) with an [Immediate Alert Service \(IAS\)](#). This design is available as code example CE212736 for Cypress kit [CY8CKIT-062-BLE](#). This application note uses the code example extensively.

For hardware design considerations, see [AN218241 – PSoC 6 MCU Hardware Design Considerations](#).

For advanced application development, refer to the application note [AN215796 – Designing PSoC 6 BLE Applications](#).

1.1 Prerequisites

Before you get started, make sure you have the development kit and have installed the required software, including the code example.

1.1.1 Hardware

- [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#)
- PC with Windows 7 or later (if using the [CySmart™ Host Emulation Tool](#) application)
- Mobile phone with Android 5/iOS 8 or later (if using the [CySmart iOS/Android](#) app)

1.1.2 Software

- [PSoC Creator 4.2](#) with PSoC Programmer 3.27
- CE212736 – the BLE Find Me code example for the CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit
- CySmart Host Emulation Tool PC application or CySmart iOS/Android app

Scan the following QR codes from your mobile phone to download the CySmart app.

iOS



Android



2 Development Ecosystem

2.1 PSoC Resources

Cypress provides a wealth of data at www.cypress.com to help you to select the right PSoC device and quickly and effectively integrate it into your design. The following is an abbreviated list of resources for PSoC 6 MCU:

- **Overview:** [PSoC Portfolio](#), [PSoC Roadmap](#)
- **Product Selectors** [PSoC 6 MCU](#).
- **Datasheets** describe and provide electrical specifications for each device family.
- **Application Notes and Code Examples** cover a broad range of topics, from basic to advanced level. Many of the application notes include code examples. You can also browse our collection of code examples from directly inside PSoC Creator —see [Code Examples](#).
- **Technical Reference Manuals (TRMs)** provide detailed descriptions of the architecture and registers in each device family.
- **PSoC 6 Programming Specification** provide the information necessary to program the nonvolatile memory of the PSoC 6 MCU devices.
- **CapSense Design Guides:** Learn how to design capacitive touch-sensing applications with PSoC devices.
- **Development Tools**
 - [CY8CKIT-062-WiFi-BT PSoC 6 WiFi-BT Pioneer Kit](#) is a development kit that supports the PSoC 62 series MCU along with WiFi and BT connectivity.
 - [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#) is an easy-to-use and inexpensive development platform for PSoC 6 BLE.
- **Training Videos:** Cypress provides [video training](#) on our products and tools, including a dedicated series on [PSoC 6 MCU](#).

For a comprehensive list of PSoC 6 MCU resources, see [KBA223067](#) in the Cypress community.

2.2 Firmware/Application Development

Cypress PSoC Creator and the Peripheral Driver Library (PDL) are at the heart of the development process.

PSoC Creator brings together several digital/analog/system Components and firmware to build an application. Using PSoC Creator, you can select, place, and configure Components on a schematic; write C/assembly source code; and program and debug the device.

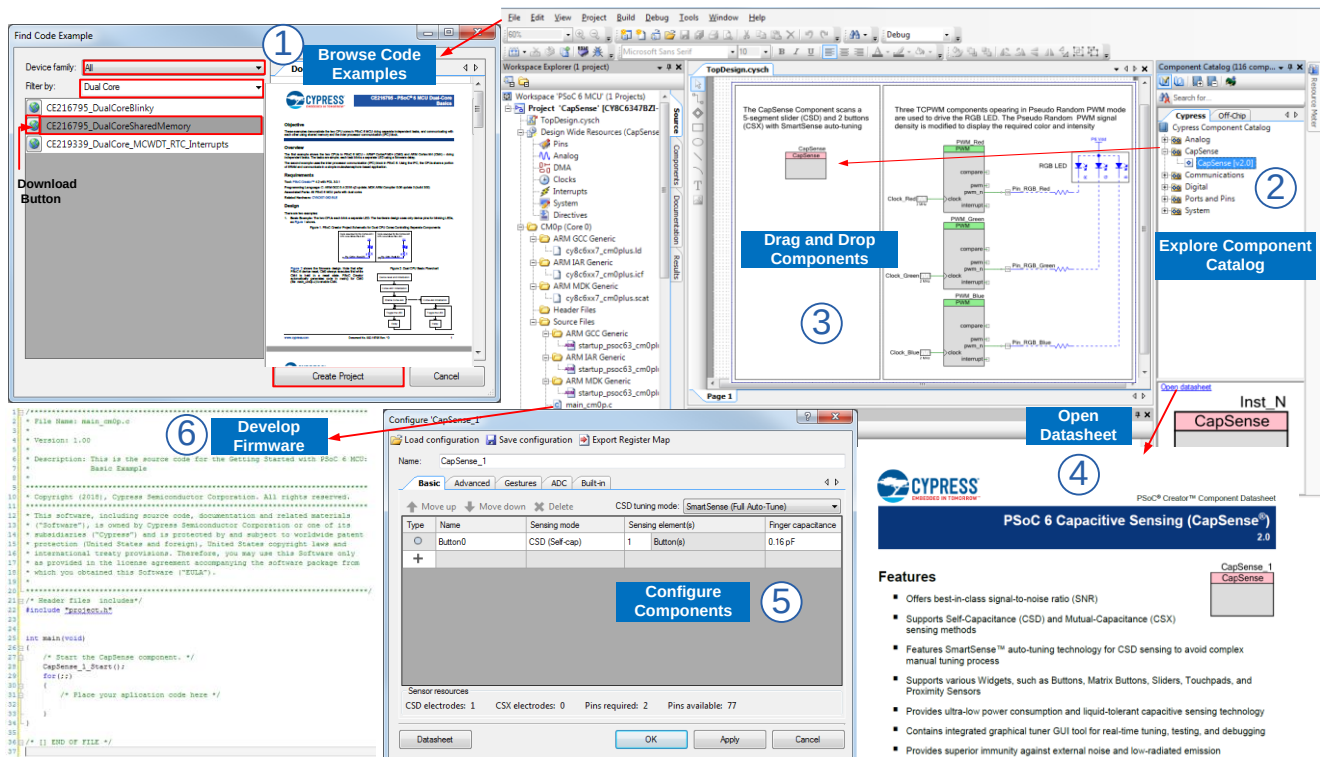
The PDL is the software development kit for the PSoC 6 MCU family. The PDL, provided as source code, makes it easier to develop the firmware for supported devices. It helps you quickly customize and build firmware without the need to understand the register set. The PDL supports both PSoC Creator and third-party IDEs.

2.2.1 PSoC Creator

PSoC Creator is a free Windows-based Integrated Design Environment (IDE). It enables you to design hardware and firmware systems concurrently, based on PSoC 6 MCU. As **Figure 2** shows, with PSoC Creator, you can:

1. Browse collection of code examples from the **File > Code Example...** menu.
 - a. Filter for examples based on Device Family.
 - b. Select from the menu of examples offered based on the **Filter by** options.
 - c. Download the code example using the download button.
 - d. Create a new project based on the selection.
2. Explore the library of more than 100 Components.
3. Drag and drop Components to build your hardware system design in the main design workspace.
4. Review the Component datasheets.
5. Configure the Components using configuration tools.
6. Co-design your application firmware with the PSoC hardware.

Figure 2. PSoC Creator Schematic Entry and Components



2.2.1.1 PSoC Creator Help

Visit the [PSoC Creator](#) home page to download and install the latest version of PSoC Creator. Then launch PSoC Creator and navigate to the following items:

- **Quick Start Guide:** Choose **Help > Documentation > Quick Start Guide**. This guide gives you the basics for developing PSoC Creator projects.
- **Code Examples:** Choose **File > Code Example** or click the **Find Code Example...** link on the **Start Page** tab. These code examples demonstrate how to configure and use PSoC resources.
- **Component Datasheets:** Right-click a Component and select **Open Datasheet**. Visit the [PSoC 6 MCU Component Datasheets](#) page for a list of all Component datasheets

2.2.2 Peripheral Driver Library (PDL)

The PDL is the software development kit for PSoC 6 MCU devices. If you have experience working with PSoC devices but are new to PSoC 6 MCU, you will notice that PDL is the major addition to the development ecosystem.

Firmware developers who wish to work at the register level should also install the PDL. The PDL includes all the device-specific header files and startup code you need for your project. It also serves as a reference for each driver. Because the PDL is provided as source code, you can see how it accesses the hardware at the register level.

Some devices do not support particular peripherals. The PDL is a superset of all drivers for any supported device. This superset design means:

- All APIs needed to initialize, configure, and use a peripheral are available.
- The PDL is useful across all PSoC 6 MCU devices, regardless of available peripherals.
- The PDL includes error checking to ensure that the targeted peripheral is present on the selected device.

This enables the code to maintain compatibility across platform as long as the peripherals are available. A device header file specifies the peripherals that are available for a device. If you write code that attempts to use an unsupported peripheral, you will get an error at compile time. Before writing code to use a peripheral, consult the datasheet for the particular device to confirm support for the peripheral.

PSoC Creator provides Components that are based on PDL for your use with PSoC 6 MCU devices. This retains the essence of PSoC Creator in utilizing Cypress or community-developed and pre-validated Components. However, the PDL is a source code library that you can use with any development environment.

The PDL includes the following key software resources:

- Header and source files for each peripheral driver
- Header and source files for middleware libraries.
- Device-specific header, startup, and configuration files
- Template projects for supported third-party IDEs
- Full documentation

The location for the documentation is `<PDL install directory>\doc\`. There are two key documents.

The *PDL v3.x User Guide* covers the fundamentals of working with the PDL, such as:

- Creating a custom project using the PDL (including third-party IDEs)
- Configuring a peripheral
- Managing pins in firmware
- Using the PDL as a learning tool for register-based programming
- Using the PDL API Reference documentation

The second key document is the *PDL 3.x API Reference Manual.html*. This reference has complete information on every driver in the PDL, including overview, configuration considerations, and details on every function, macro, data structure, and enumerated type.

2.3 Support for Other IDEs

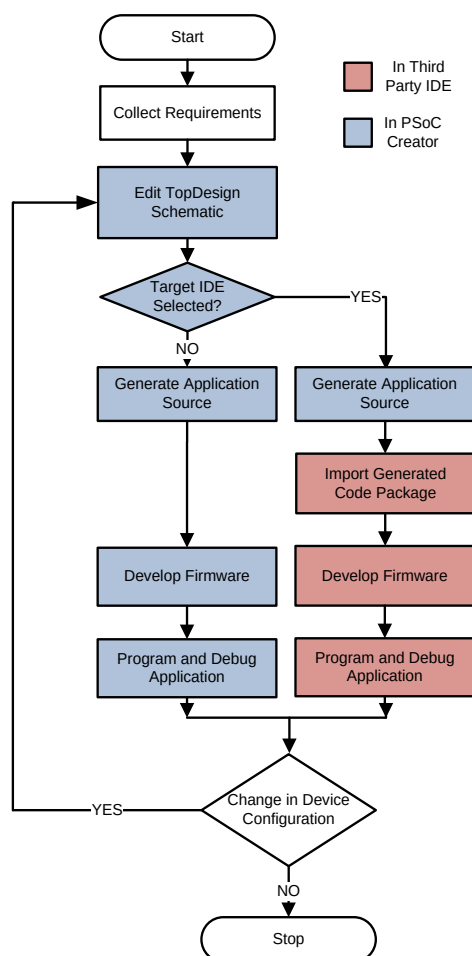
You can also develop firmware for PSoC 6 MCU using your favorite IDE such as IAR Embedded Workbench. You can use the PDL with another IDE by using PSoC Creator to design the system and generate configuration code and then export to a target IDE.

See the [AN219434 – PSoC 6 MCU Importing Generated Code into an IDE](#) for details.

2.3.1 Using PSoC Creator to Target Another IDE

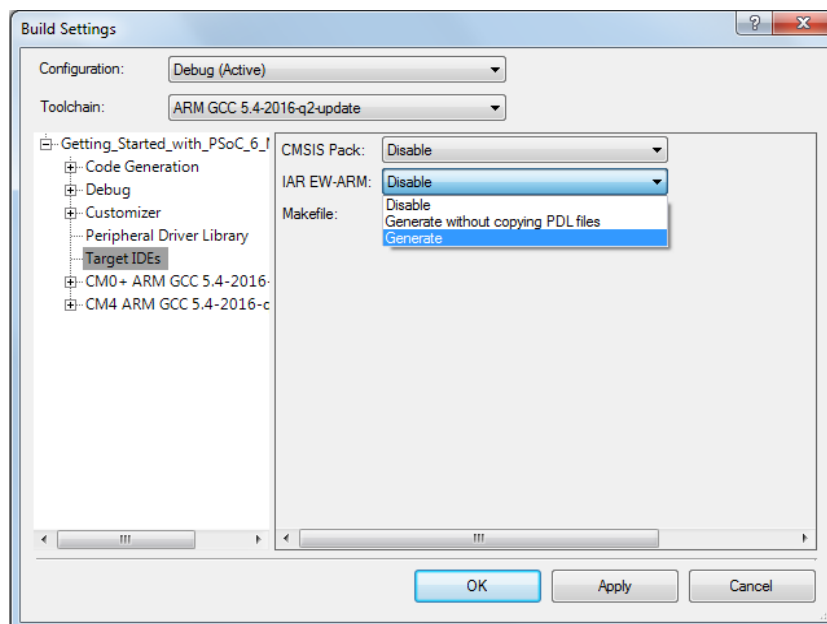
Cypress recommends that you use PSoC Creator to set up and configure PSoC 6 MCU system resources and peripherals. You then export the project to your IDE, and continue developing firmware in your IDE. If there is a change in the device configuration, you edit the TopDesign schematic in PSoC Creator and regenerate the code for the target IDE. [Figure 3](#) shows the workflow.

Figure 3. PSoC 6 MCU Application Development Flowchart Using PSoC Creator



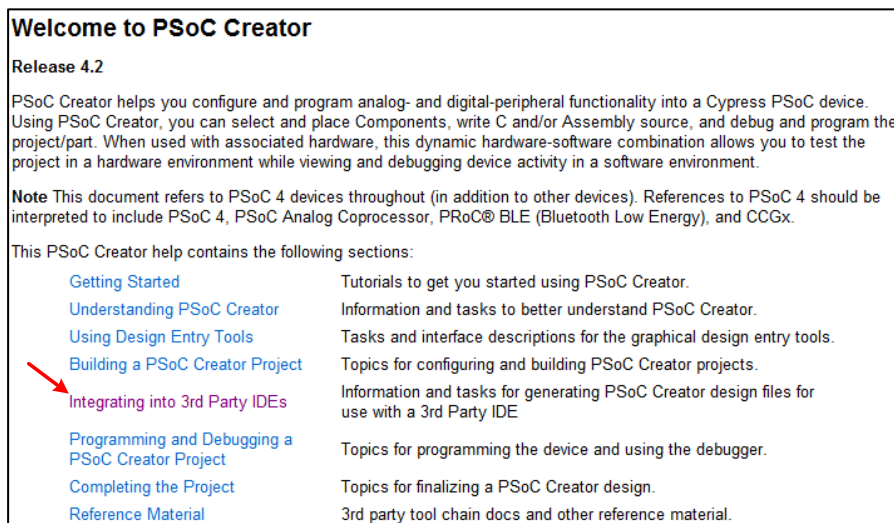
Code generated from PSoC Creator includes all required header, startup, and PDL files based on your design. Exporting the code generated from PSoC Creator is supported for Keil μ Vision, IAR Embedded Workbench, Eclipse-based IDEs, and for GNU-based command-line tools. You select your target IDE using the **Project > Build Settings > Target IDEs** panel. Enable the export package for your target IDE as shown in [Figure 4](#). When you generate code, PSoC Creator also creates the corresponding export package.

Figure 4. Target IDE Selection in Project > Build Settings



You then import the package into your IDE. The import details vary significantly per IDE. Consult the PSoC Creator Help to learn the process you must follow. Choose **Help > PSoC Creator Help Topics**. See Figure 5. The *Integrating into 3rd Party IDEs* topic points you to specific help files for each PSoC device family, and each supported IDE.

Figure 5. PSoC Creator Help

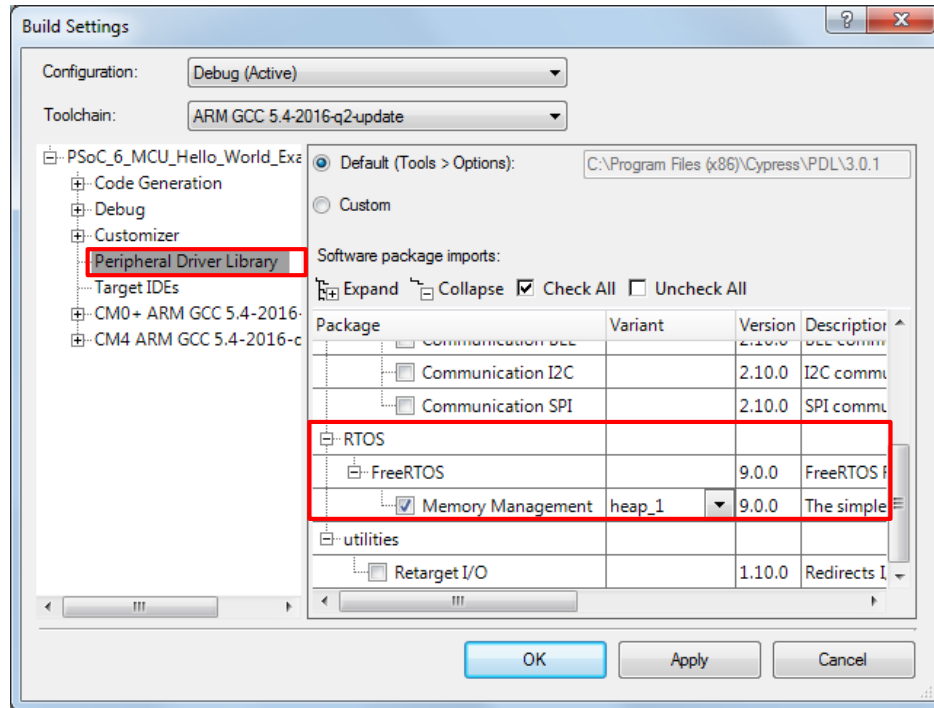


You can work effectively in most if not all IDEs. If your IDE is not supported in the Target IDEs panel, you can still use PSoC Creator. After you generate code, add the necessary files directly to your IDE's project. [AN219434 – PSoC 6 MCU Importing Generated Code into an IDE](#) provide detailed steps for manually importing the generated code into another IDE.

2.4 RTOS Support

The PDL includes RTOS support for PSoC 6 MCU development: FreeRTOS source code is fully integrated and included with the PDL. You can import the FreeRTOS software package into your project by using the PSoC Creator RTOS import option. Navigate to **Project > Build Settings** menu and select FreeRTOS from the Software package imports option under **Peripheral Driver Library > FreeRTOS** as shown in Figure 6.

Figure 6. Import FreeRTOS in PSoC Creator Project



If you have a preferred RTOS, use the resources provided as examples on how to integrate such code with the PDL.

2.5 Debugging

The **CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit** has the KitProg2 onboard programmer/debugger. It supports Cortex Microcontroller Software Interface Standard - Debug Access Port (CMSIS-DAP) and custom modes of operations, as well as the KitProg2 connection. This makes debugging the PSoC 6 MCU Pioneer Kit extremely flexible. See the [KitProg2 User Guide](#) for details.

PSoC Creator supports debugging a single CPU (either CM4 or CM0+) at a time. Some third-party IDEs support multi-CPU debugging. For more information on debugging PSoC devices with PSoC Creator, see the PSoC Creator Help.

2.6 CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit

The CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit is a BLE development kit from Cypress that supports the PSoC 63BL family of devices. See [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#) in [Cypress IoT Development Tools](#) for more information.

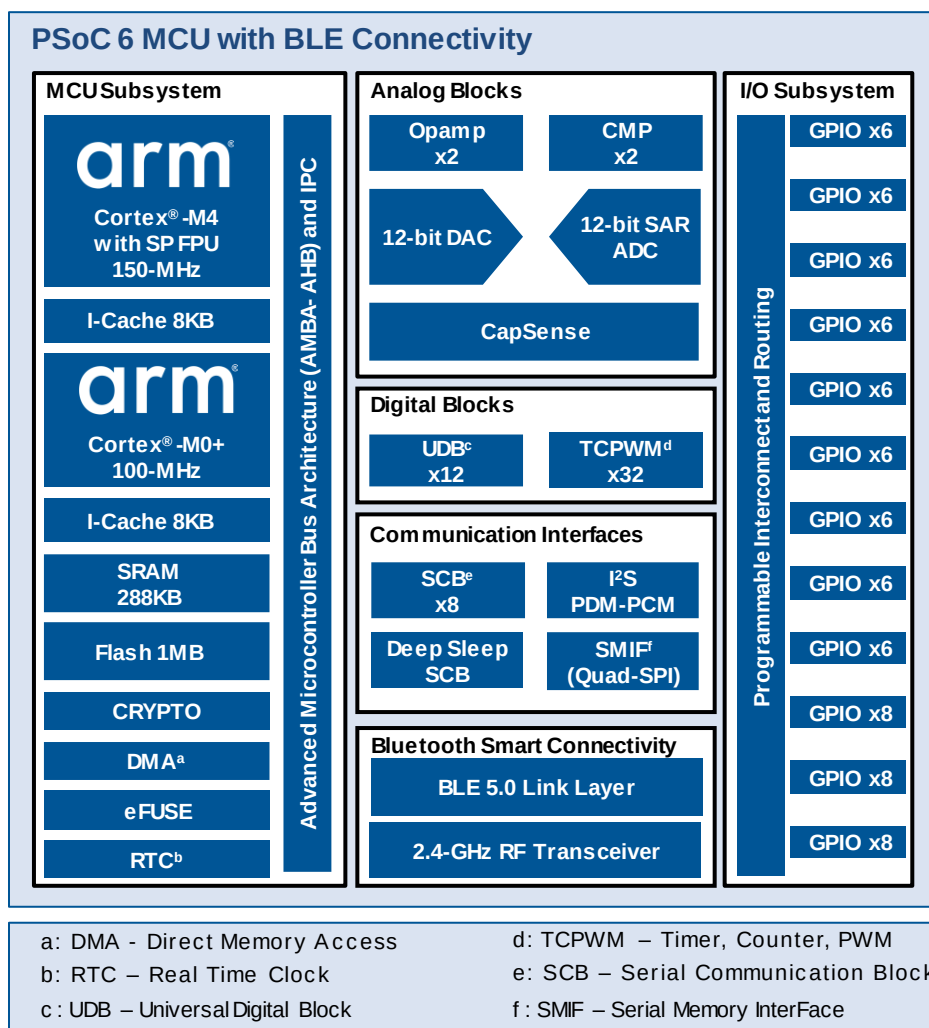
2.7 CySmart Host Emulation Tool and Mobile Applications

The CySmart Host Emulation Tool is a Windows application that emulates a BLE Central device using the PSoC 6 BLE Pioneer Kit's BLE dongle. See [CySmart Host Emulation Tool](#) in [Appendix D](#) for more information. Similar functionality is available in the [CySmart Mobile App](#) for the iOS and Android devices. This tool is extremely useful in testing your BLE application.

3 Device Features

The PSoC 6 BLE device has an extensive feature set as shown in Figure 7. The following is a list of its major features. For more information, see the device [datasheet](#), the [Technical Reference Manual \(TRM\)](#), and the section on [Related Application Notes and Code Examples](#).

Figure 7. PSoC 6 MCU with BLE Connectivity Block Diagram



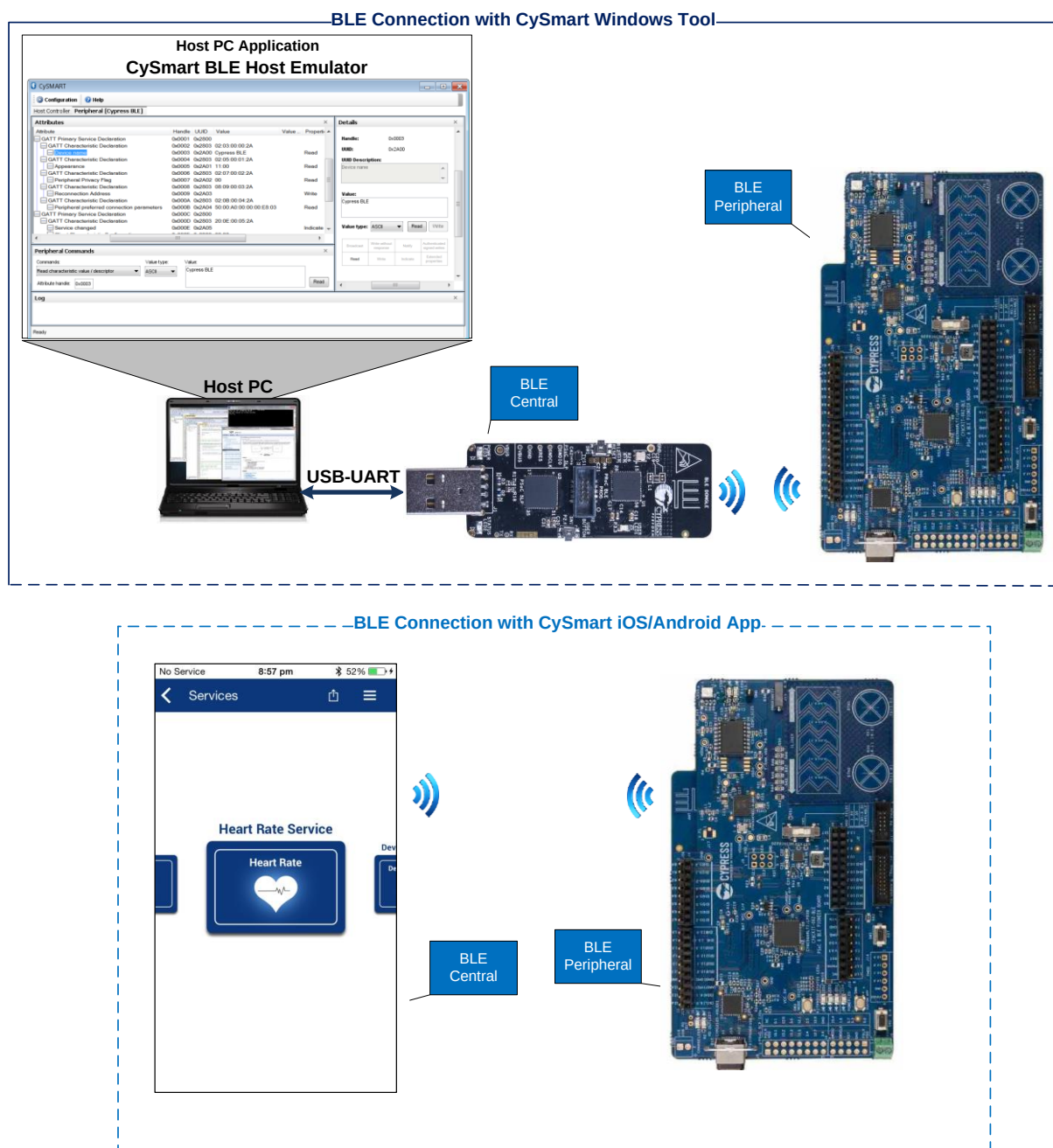
- 32-bit dual-CPU MCU subsystem
 - 150-MHz CM4 CPU with single-precision floating-point unit 100-MHz CM0+ CPU
 - Up to 1 MB of user flash, with additional 32 KB for EEPROM emulation and 32 KB supervisory
 - Up to 288 KB of SRAM with selectable Deep Sleep retention granularity at 32-KB retention boundaries
 - Inter-processor communication supported in hardware
 - Cryptography accelerators with support for hardware acceleration and true random number generator function
 - Two 32-channel DMA controllers
 - eFUSE: one-time programmable bits
 - Uninterruptible secure boot with hardware hash-based authentication
- I/O subsystem
 - Up to 78 GPIOs that can be used for analog, digital, CapSense, or segment LCD functions
 - Programmable drive modes, drive strength, and slew rates

- Two ports with smart I/Os that can implement Boolean operations
- Programmable Analog Blocks
 - Two opamps of 6-MHz gain bandwidth (GBW), configurable as programmable gain amplifiers (PGA), comparators, or filters
 - Two low-power comparators with less than 300 nA current consumption that are operational in Deep Sleep and Hibernate modes
 - One 12-bit, 1-Msps SAR ADC with 16-channel sequencer
 - One 12-bit voltage mode DAC
- CapSense with SmartSense™ auto-tuning
 - Supports CapSense Sigma-Delta (CSD) and CapSense Transmit/Receive (CSX)
 - Provides best-in-class SNR, liquid tolerance, and proximity sensing
- Programmable Digital Blocks, Communication Interfaces
 - 12 UDBs for custom digital peripherals
 - 32 TCPWM blocks configurable as 16-bit/32-bit timer, counter, PWM, or quadrature decoder
 - Nine SCBs configurable as I²C master or slave, SPI master or slave, or UART
 - Audio subsystem with one I²S interface and two PDM channels
 - SMIF interface with support for execute-in-place from external quad SPI flash memory and on-the-fly encryption and decryption
- Bluetooth connectivity with Bluetooth Low Energy 4.2
 - 2.4-GHz BLE radio with integrated balun
 - Bluetooth 4.2 specification-compliant controller and host implementation
 - Link layer engine that supports master/slave modes and up to four simultaneous connections
 - Support for 2-Mbps LE data rate
- Operating voltage range, power domains, and low-power modes
 - Device operating voltage: 1.71 V to 3.6 V
 - User-selectable core logic operation at either 1.1 V or 0.9 V
 - Multiple on-chip regulators: low-drop out (LDO for Active, Deep Sleep modes), single input multiple output (SIMO) buck converter
 - Active, Low-Power Active, Sleep, Low-Power Sleep, Deep Sleep, and Hibernate modes for fine power management
 - Deep Sleep mode with operational BLE link: 4.5-μA typical current at 3.3 V with 64-KB SRAM retention
 - An “always on” backup power domain with built-in RTC, power management integrated circuit (PMIC) control, and limited SRAM backup

4 Development Setup

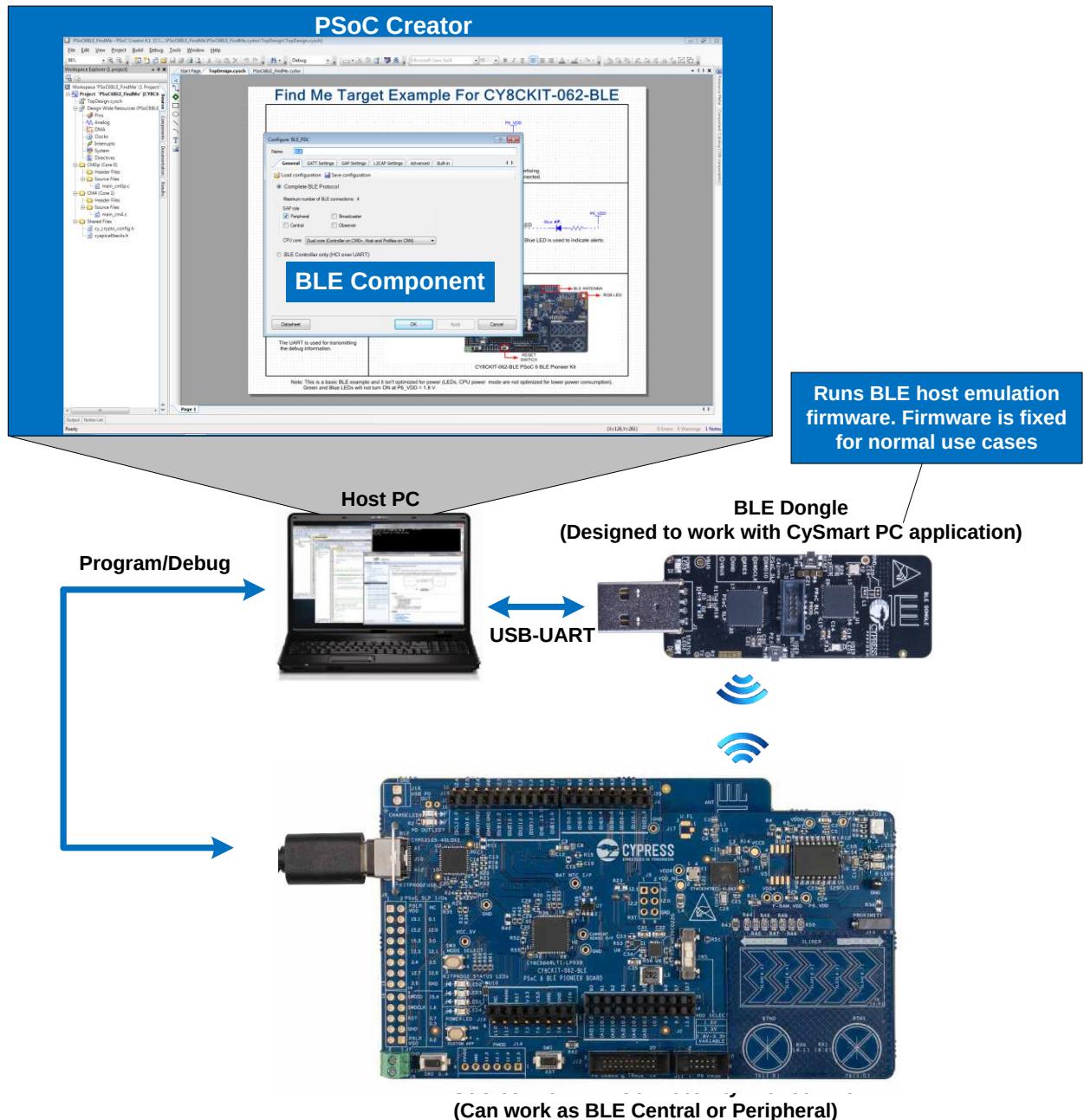
Figure 8 shows the hardware and software tools required for evaluating BLE Peripheral designs using the PSoC 6 BLE device. In a typical use case, the PSoC 6 BLE Pioneer Kit (blue board in Figure 8) is configured as a Peripheral that can communicate with a Central device such as the CySmart iOS/Android app or CySmart Host Emulation Tool. The CySmart Host Emulation Tool also requires a BLE dongle (black board in Figure 8) for its operation. The PSoC 6 BLE Pioneer Kit includes a dongle.

Figure 8. BLE Functional Setup



As shown in Figure 9, the BLE dongle is preprogrammed to work with the Windows CySmart Host Emulation Tool. The PSoC 6 BLE Pioneer Kit has an onboard USB programmer that works with PSoC Creator for programming or debugging your BLE design. The BLE Pioneer Kit can be powered over the USB interface. Both the BLE dongle and the BLE Pioneer Kit can be connected simultaneously to a common host PC for development and testing.

Figure 9. BLE Development Setup



5 My First PSoC 6 MCU Design With BLE

This section provides step-by-step instructions to build a simple design for the PSoC 6 BLE Pioneer kit. A simple Bluetooth SIG-defined standard profile called [Find Me Profile \(FMP\)](#) is implemented in the design.

While the PSoC 6 BLE Pioneer Kit is intended to simplify and streamline design for BLE-based applications, you can also use this setup to develop applications that do not use BLE.

5.1 Using These Instructions

These instructions are grouped into several sections. Each section is devoted to a phase of the application development workflow. The major sections are:

- [Part 1: Create a New Project from Scratch](#)
- [Part 2: Implement the Design](#)
- [Part 3: Generate Source Code](#)
- [Part 4: Write the Firmware](#)
- [Part 5: Build the Project, Program the Device](#)
- [Part 6: Test Your Design](#)

These instructions require that you use a particular code example. However, the extent to which you use the code example depends on the path you choose to follow through these instructions.

We have defined three paths through these instructions:

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Best For	Someone who wants hands-on experience to learn about PSoC Creator and/or BLE	Someone who is new to the tool or technology, and wants to see how it all works	Someone who knows the tools and technology, and wants to see it work on the PSoC 6 platform

What you need to do for each path is clearly defined at the start of each part of the instructions.

If you start from scratch and follow all instructions in this application note, you use the code example as a reference while following the instructions. Working from scratch teaches you the most about the PSoC Creator design process, and how BLE works. This path also takes the most time.

You can also use the code example directly. It is a complete design, with all firmware written. You can walk through the instructions and observe how the steps are implemented in the code example. This is a particularly useful approach if you are already familiar with PSoC Creator, and want to see how the BLE Component is configured, for example. If you use the code example directly, you will be able to skip some steps.

In all cases, you should start by reading [Before You Begin](#) and [About the Design](#).

5.2 Before You Begin

Ensure that you have the following items installed on your host computer.

- [PSoC Creator 4.2](#)
- [PDL v3.0.1](#)
- The [CySmart Host Emulation Tool](#) or the [CySmart iOS/Android](#) app
- [CE217236](#) – the code example used for this application note and
- The [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#) on which the code example is executed

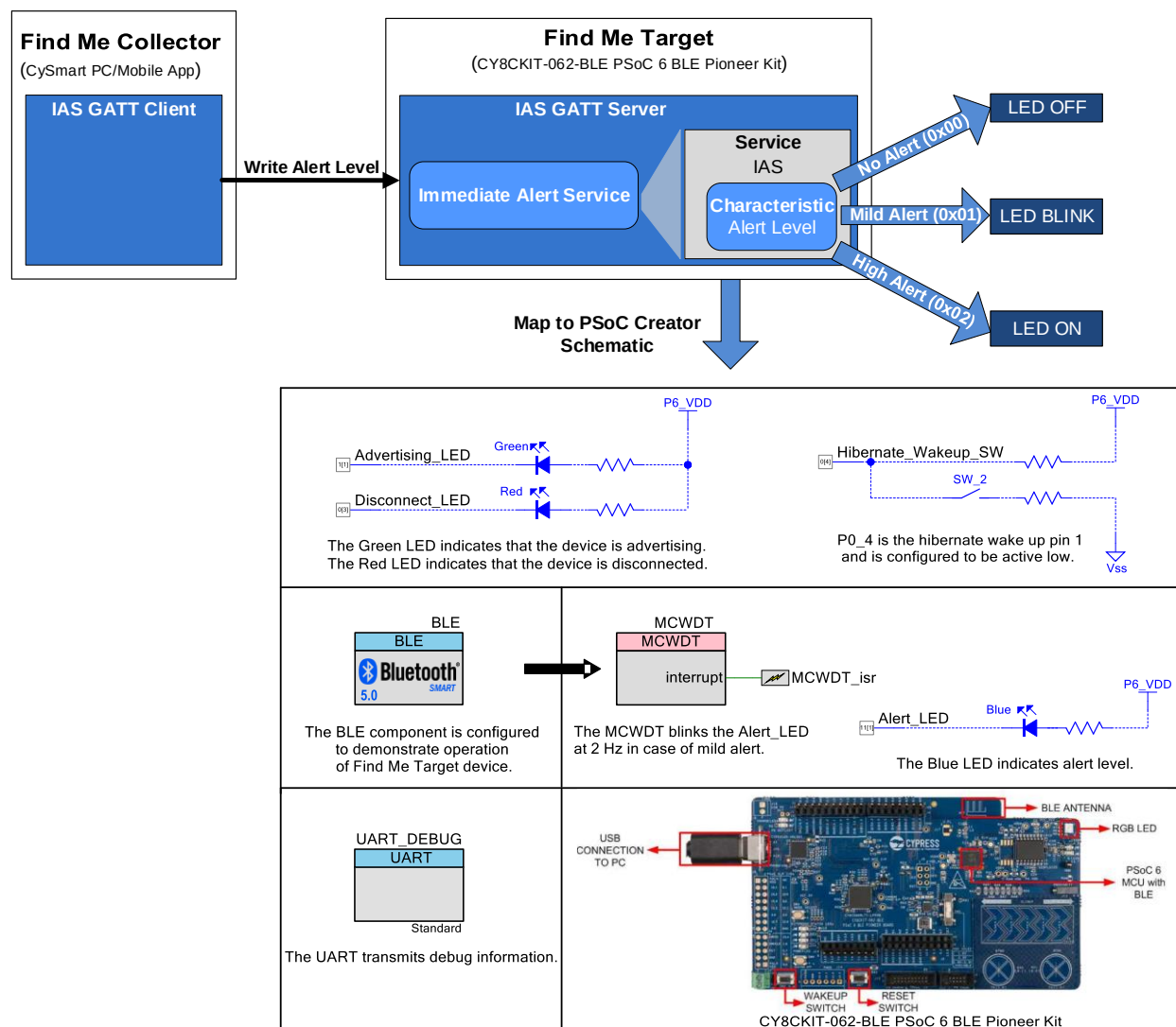
You can download the code example from the Cypress website by clicking the link above. You can also use the PSoC Creator **File > Code Example** command. Set the **Device family** to PSoC 63. Then set the **Filter by** option to **Find Me**. The [CE217236_PSoC6BLE_FindMe](#) code example appears. Select the code example, download by clicking on the download icon adjacent to the example. After installation is complete, click **Create Project**, and follow the on-screen instructions.

This design is developed for the [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#). If you wish to use other hardware, you must adapt the instructions to your needs.

5.3 About the Design

This design implements a BLE [Find Me Profile \(FMP\)](#) in the Target role that consists of an Immediate Alert Service (IAS). FMP and IAS are a BLE standard profile and service defined by the Bluetooth SIG. Alert levels triggered by the Find Me Locator are indicated by varying the state of an LED on the BLE Pioneer Kit, as [Figure 10](#) shows. In addition, two status LEDs indicate the state of the BLE interface. There is also an optional UART Component to print debug messages to a terminal window.

Figure 10. My First PSoC 6 BLE Design



5.4 Part 1: Create a New Project from Scratch

This part takes you step-by-step through the process of creating a project file from scratch.

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform all steps	Do Step 1 Read the rest of the steps	Do Step 1, then jump to Part 2

Note: These instructions assume that you are using PSoC Creator 4.2 or higher. The overall development process is the same for subsequent versions of PSoC Creator; but the user interface may change over time.

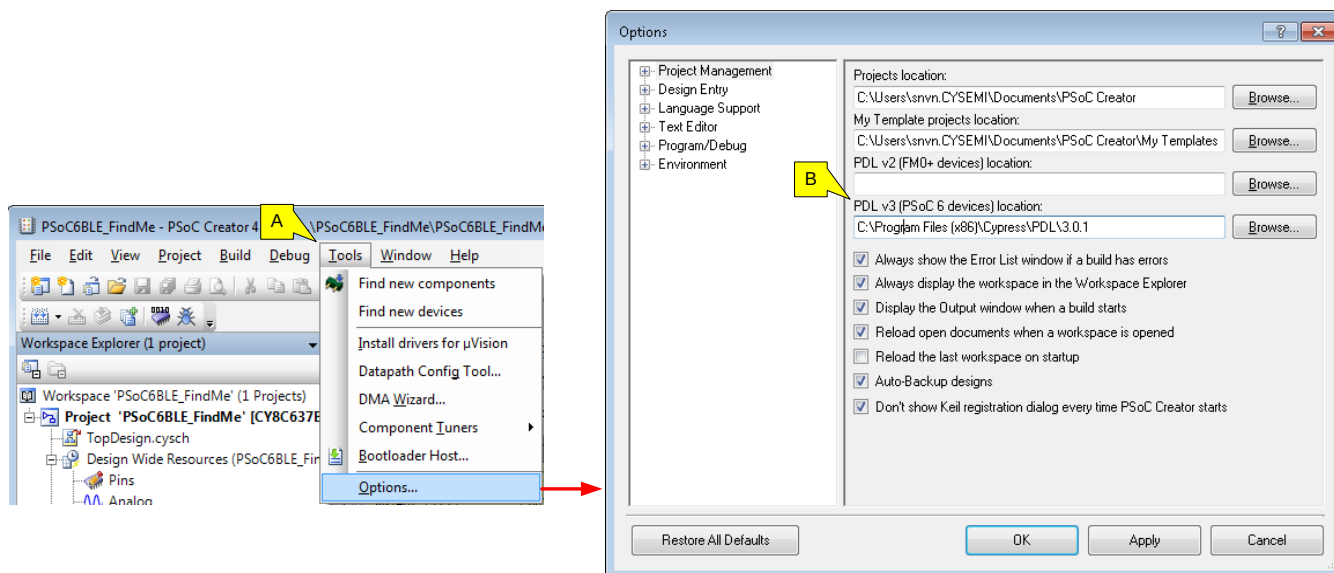
Launch PSoC Creator and get started.

1. Ensure that PSoC Creator can find the PDL.

This should be set correctly automatically during installation, but nothing works if this isn't set up right. See [Figure 11](#) for help with this step.

- A. Choose menu item **Tools > Options**
- B. On the Project Management panel, check the path in the PDL v3 (PSoC 6 Devices) location field.
- C. Ensure that it is correct. If it is not, click **Browse** and locate the installed directory of the PDL. The default location is *C:\Program Files (x86)\Cypress\PDL\3.0.1*.

Figure 11. Peripheral Driver Library (PDL) Location

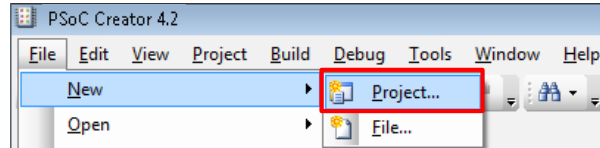


Optional: Jump to [Part 2: Implement the Design](#).

2. Create a new PSoC Creator project.

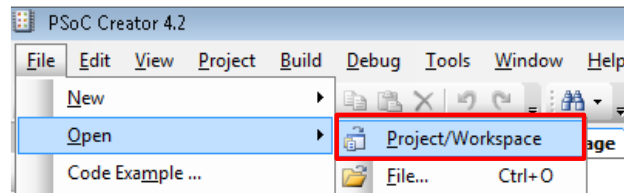
Choose **File > New > Project**, as Figure 12 shows. The **Create Project** window appears.

Figure 12. Create a New PSoC Creator Project



Note: If you are using the code example choose **File > Open > Project/Workspace**, as Figure 13 shows. The **Open** window appears. Point to the location of the Code Example workspace and open the workspace.

Figure 13. Open Existing Code Example Workspace



3. Select PSoC 6 BLE as the target device.

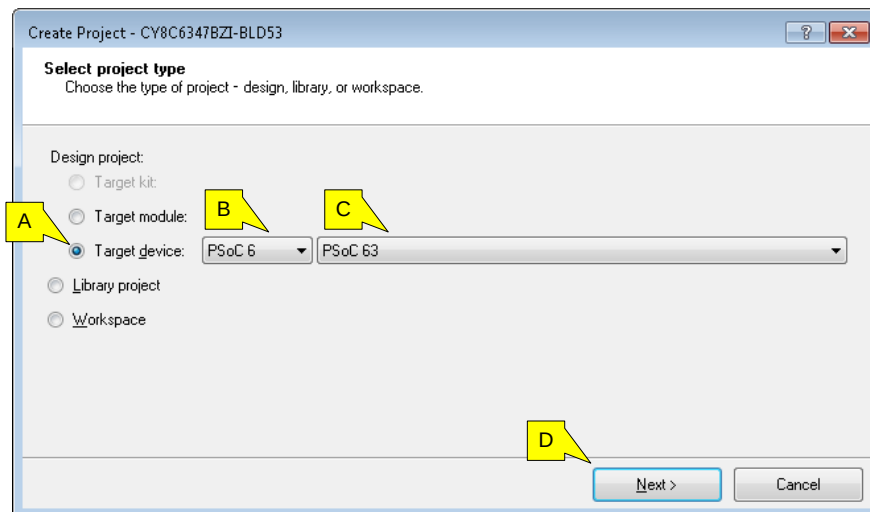
PSoC Creator speeds up the development process by automatically setting various project options for specified development kits or target devices. See Figure 14 for help with this step.

- A. Select **Target device**.
- B. From the family drop-down list, select **PSoC 6**.
- C. From the device drop-down menu, list **PSoC 63**.
- D. Click **Next**. The Select project template panel appears.

PSoC Creator uses CY8C6347BZI-BLD53 as the default device in the PSoC 6 MCU with BLE family. This device is mounted on the CY8CKIT-062-BLE PSoC 6 BLE Connectivity Pioneer Kit.

If you are intending to use custom hardware based on PSoC 6 BLE, or a different PSoC 6 BLE part number, this is the place you choose to **Launch Device Selector** option in **Target device** and select the appropriate part number.

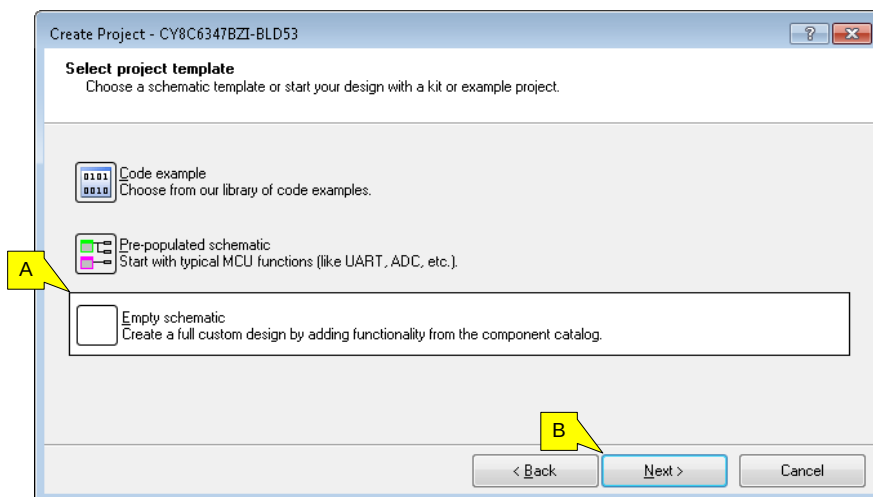
Figure 14. Selecting Target Device



4. Pick a project template.

- A. Choose **Empty schematic**.
- B. Click **Next**.

Figure 15. Pick a Project Template

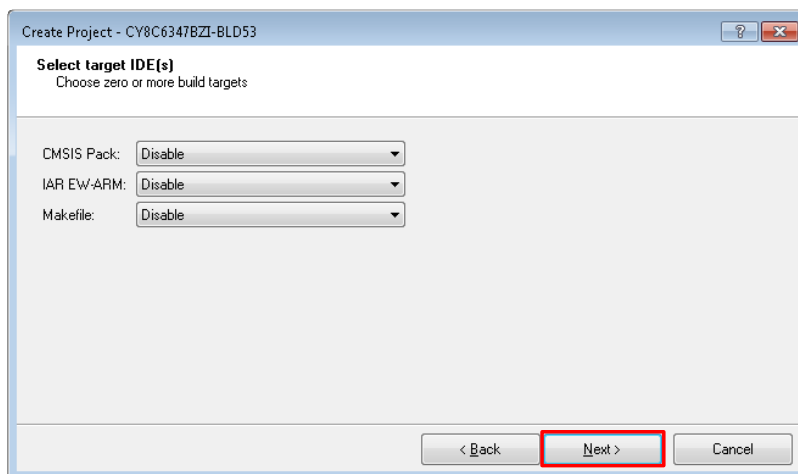


5. Select target IDE(s).

If you expect to export the code from the project, specify the target IDE. By default, all export options are disabled. You can modify this setting later if circumstances change.

Click **Next** to accept the default options.

Figure 16. Select Target IDEs (All Disabled)

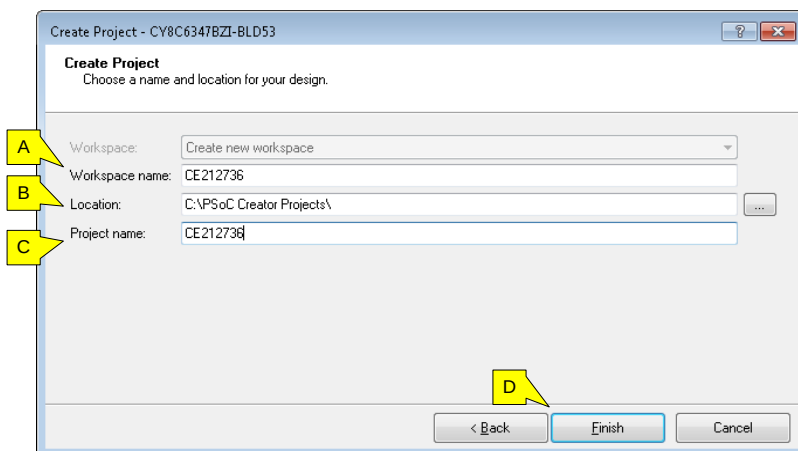


6. Create the project.

In this step, you set the name and location for your workplace, and a name for the project. See [Figure 17](#) for help with this step. A workspace is a container for one or more projects.

- A. Set the **Workspace name**.
- B. Specify the **Location** of your workspace.
- C. Set a **Project name**. The project and workspace names can be the same or different.
- D. Click **Finish**.

Figure 17. Project Naming and Location



You have successfully created a new PSoC Creator project.

5.5 Part 2: Implement the Design

Now that you have a project file, it is time to implement the hardware design using PSoC Creator Components. If you are using the code example directly, you already have a complete design. Perform the actions recommended based on your chosen path through this exercise.

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform all steps	Read and understand all steps	You can skip this part if you wish. Jump to Part 3: Generate Source Code

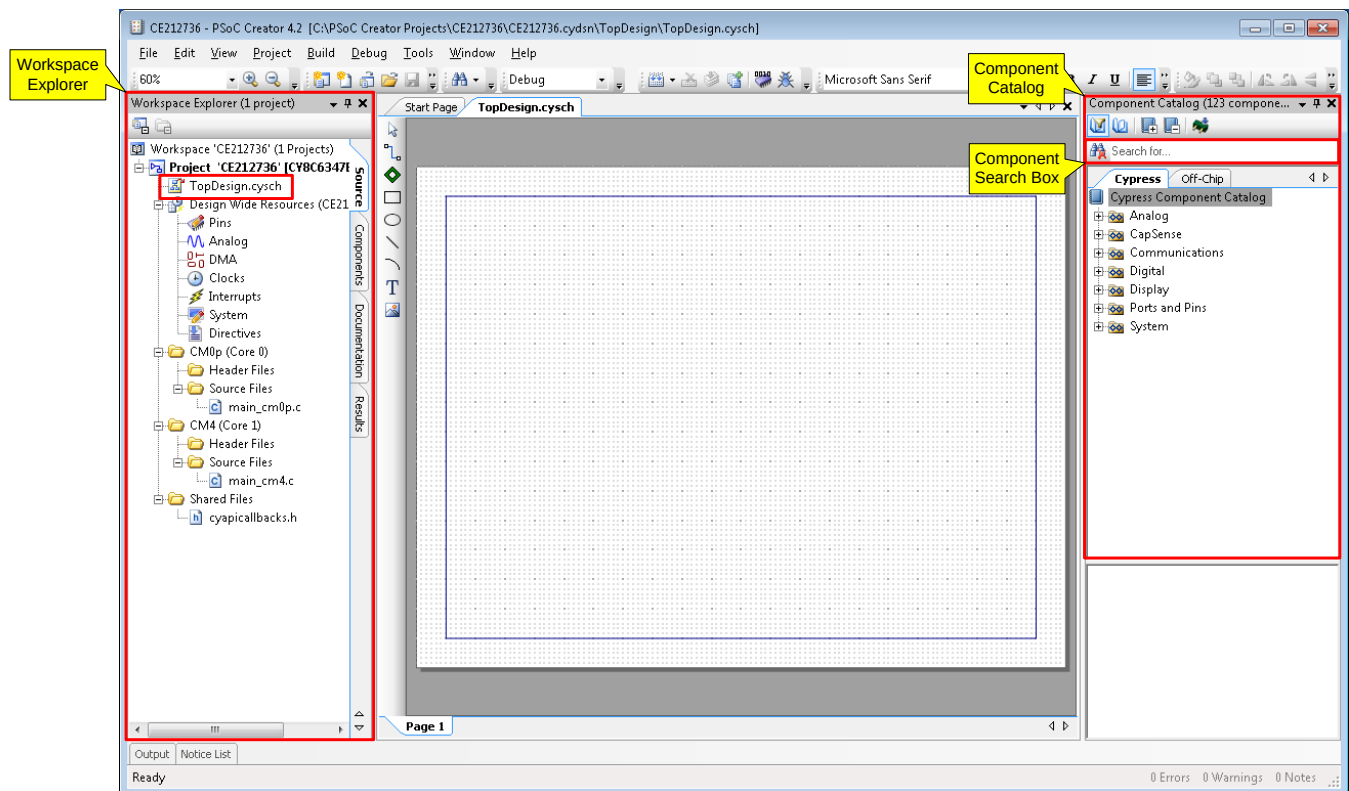
Before you implement the design, a quick tour of the PSoC Creator interface is in order.

Figure 18 shows the PSoC Creator application displaying an empty design schematic.

The project includes a project folder with a base set of files. You view these files in the **Workspace Explorer** pane to the left. The project schematic opens by default. This is the *TopDesign.cysch* file. Double-click the file name in the explorer pane to open the schematic at any time. In a new project, the schematic is empty. If you are using the code example, this is the schematic for the Find Me BLE application.

The Component catalog is on the right side of the window. You can open it with the **View > Component Catalog** menu item. You can search for a Component by typing the name of the Component in the **Search for...** text box and then pressing the enter key. See Figure 18.

Figure 18. Schematic and Component Catalog

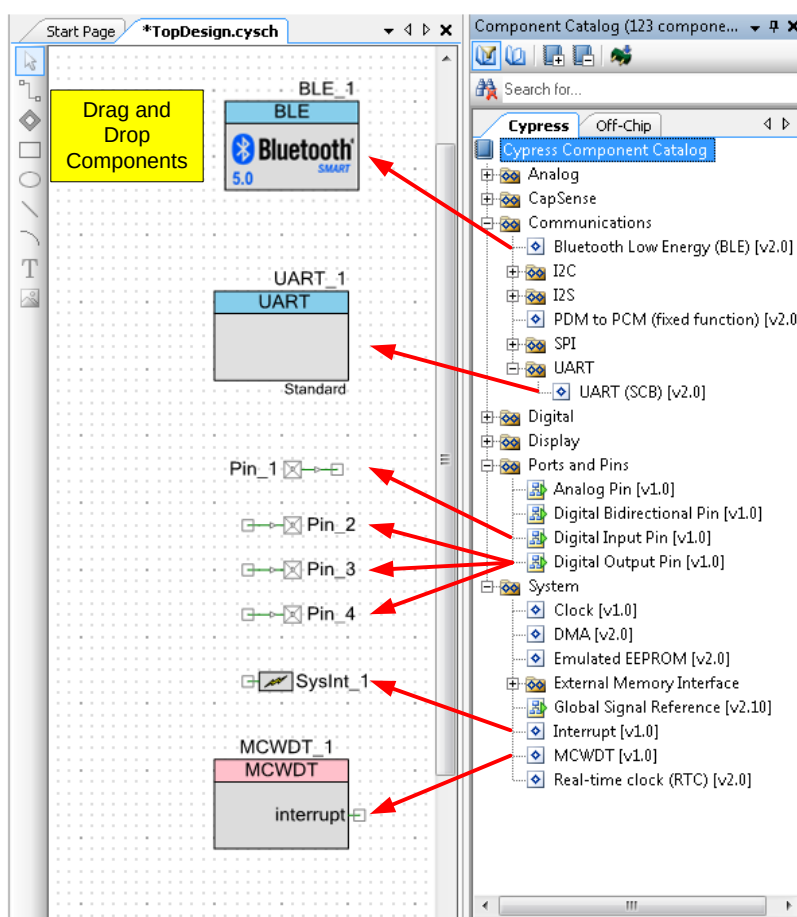


1. Place Components in the design.

This design uses several Components: the BLE Component, three digital output pins, a UART, a Watchdog Timer, and an Interrupt. In this step, you add them to the design. You configure them in subsequent steps. [Figure 19](#) shows the result.

- In the **Component Catalog**, expand the **Communications** group, drag a **BLE** Component into the schematic, and drop it. It doesn't matter where you put a Component. Alternatively, you can search the BLE Component by typing BLE in the Component Catalog search box.
- Also in the **Communications** group, expand UART and drag a **UART (SCB)** Component into the design.
- Expand the **Ports and Pins** group, drag a **Digital Output Pin** into the design. Repeat this twice, for a total of three pins.
- Expand the **System** group, drag an **Interrupt** Component and a MCWDT Component into the design.

Figure 19. Place Components in the Design



PSoC Creator gives each Component a default name and properties. Default values may or may not be suitable for any given design. In subsequent steps you modify the name and some of the properties.

2. Configure the three LED pins.

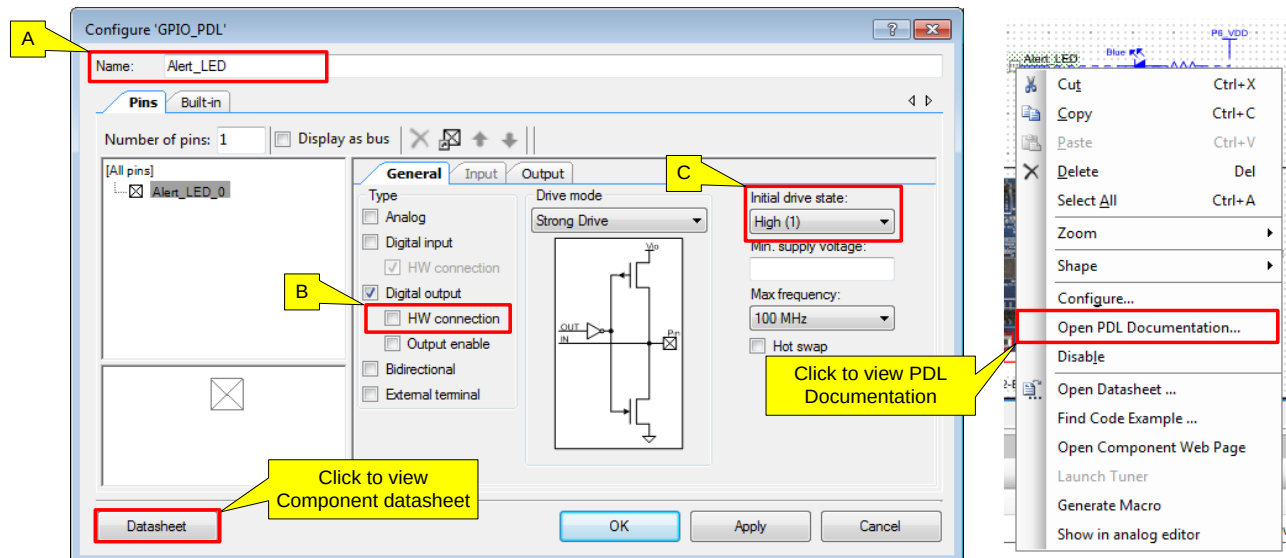
One pin drives the alert status LED. The other two drive the BLE advertising and disconnection indicator LEDs. An LED on the BLE Pioneer Kit is active LOW; that is, the logic high pin-drive state turns OFF the LED, and the logic low pin-drive state turns it ON.

All three pins are configured identically, except for the name. Repeat these instructions three times, once for each pin. [Figure 20](#) shows the configuration.

Double-click the Component placed on the schematic to open the configuration dialog. Then perform the following steps.

- Change the name of the Component instance for each pin. The three names are **Alert_LED**, **Advertising_LED** and **Disconnect_LED**.
- For each pin, deselect **HW connection**. The firmware will drive the pin.
- For each pin, set **Initial drive state** to **High (1)**. Hence, by default the LEDs will be OFF.

Figure 20. Configuring an Output Pin Component



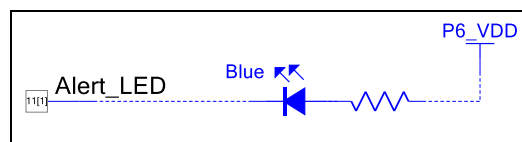
Make sure you configure all three pins.

Tip: Each Component has an associated datasheet that can be accessed from the configuration window. The Component datasheet provides more information on the Component configuration, the application programming interface (API), and the electrical specifications.

Tip: You can open the API reference document of associated PDL driver of a Component by right-clicking the Component and clicking the **Open PDL Documentation...** link. See [Figure 20](#).

Tip: For a pin, if you enable **External terminal** you can add external “off-chip” Components to a design. External Components on the schematic are included for descriptive purposes only; they have no effect on the generated code. Off-chip Components are optional, but can assist the hardware design team understanding how the design works. You can also add text boxes to a design with descriptions. [Figure 21](#) shows how you could enhance the design for the Alert LED. In this case, the off-chip components were configured with **Instance_Name_Visible** unchecked. The resistors were configured with the **Value** field left blank. The power terminal was configured with the **Supply_Name** set to P6_VDD.

Figure 21. An Output Pin with Off-Chip Components



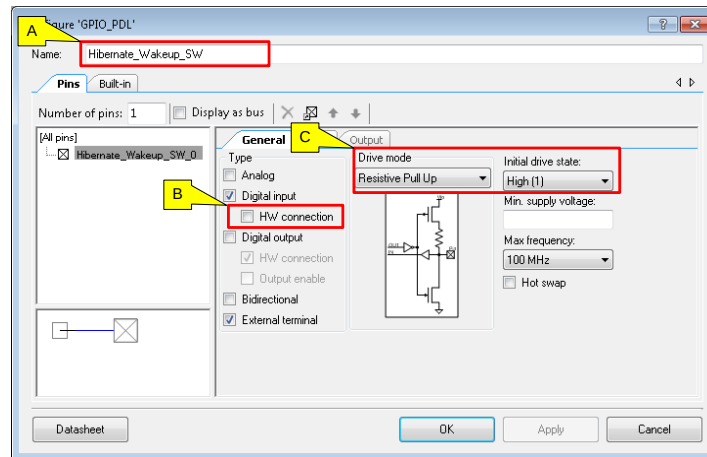
3. Configure the Hibernate wakeup pin.

Switch SW2 on the Pioneer Kit is connected to one of the Hibernate wakeup pins, P0[4] and when pressed pulls the port pin LOW. To configure this pin as the Hibernate wakeup switch, it must be configured as resistive pull up.

Figure 22 shows the configuration. Double-click the Component placed on the schematic to open the configuration dialog, and then do the following:

- Change the name of the Component instance to **Hibernate_Wakeup_SW**.
- Deselect **HW connection**. The firmware application firmware does not drive this pin. However, the pin is hard-wired to the Hibernate system. In the firmware, wakeup will be configured as active LOW.
- Set **Drive mode** to **Resistive Pull Up** and **Initial drive state** to **High (1)**. This will configure the device to detect the HIGH to LOW transition and wake up the device from Hibernate.

Figure 22. Configuring an Input Pin Component



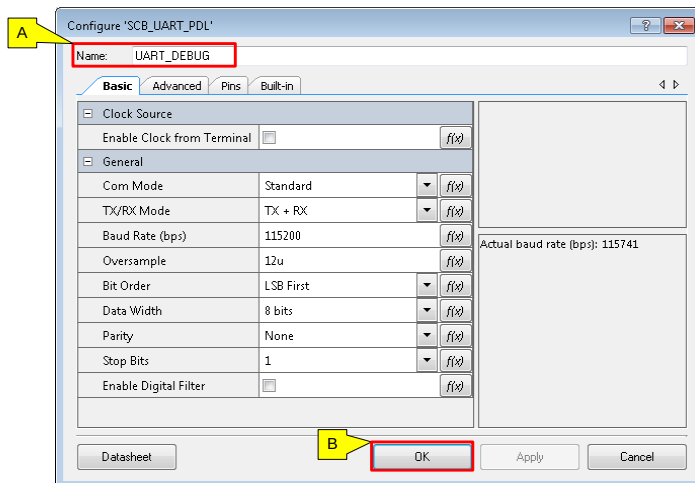
4. Configure the UART Component.

Double-click the Component placed on the schematic to open the configuration window. The design uses this Component to display debug messages in a terminal window at a baud rate of 115200 bps. It is not related to BLE functionality.

- Change the **Name** of the Component instance to **"UART_DEBUG"**.
- Click **OK**.

The design uses default values for all other settings.

Figure 23. Configuring the SCB-Based UART Component

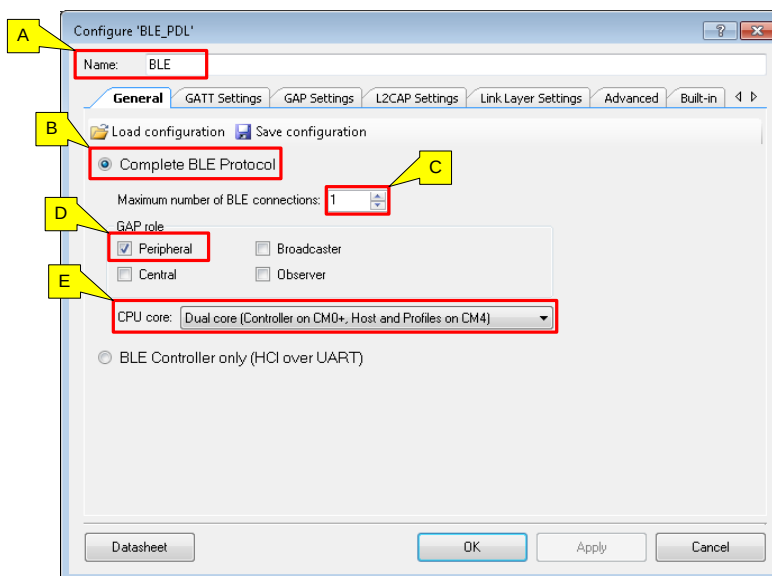


5. Set the general BLE options.

Double-click the BLE Component placed on the schematic to open the configuration window. Set the **General** properties as shown in Figure 24. Except for the Component name and the stack operation, this application uses default general properties.

- Change the **Name** to “BLE”.
- Confirm that **Complete BLE Protocol** is selected.
- Change **Maximum number of BLE connections** to 1. This will configure the BLE stack appropriately.
- Confirm that **Peripheral** is selected as the **GAP role**. This sets the device to act as a BLE Peripheral device and respond to Central device requests.
- Select **Dual core (Controller on CM0+, Host and Profiles on CM4)** option for **CPU core**. This will split the BLE stack to work on both the cores. The CM0+ core runs the BLE controller portion of the stack and is responsible for maintaining the BLE connection. The BLE Host runs on the CM4 core and performs application-level tasks. The main advantage of this dual-CPU setup is that the CM4 core can go into Deep Sleep low-power mode when there are no BLE-related tasks pending.

Figure 24. BLE Component General Configuration



6. Specify the Generic Attribute (GATT) settings.

In this step, you set the BLE profile as shown in Figure 25.

- A. Click the **GATT Settings** tab to display GATT options.
- B. Click the **Add Profile** drop-down menu.
- C. Select the **Find Me > Find Me Target (GATT Server)** option. This sets the GAP Peripheral role profile. When the menu disappears, notice that a new service “**Immediate Alert**” appears, as shown in Figure 26.

Figure 25. BLE Component GATT Settings

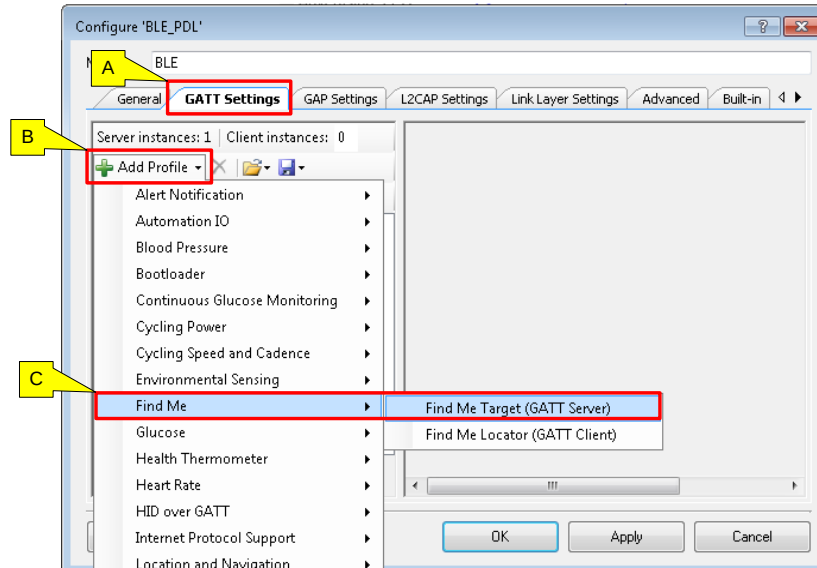
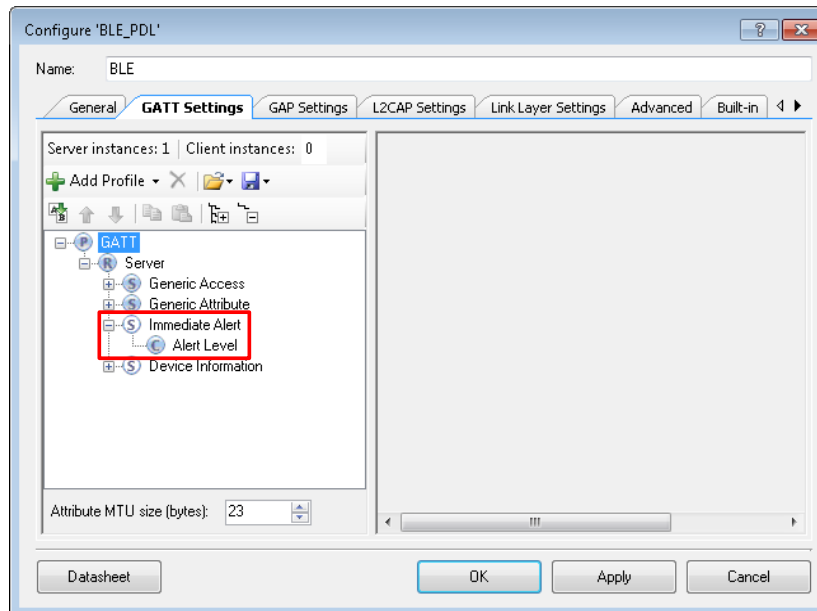


Figure 26. BLE Component Immediate Alert Service Added



Note: The code example has a **Device Information Service** also added in the GATT Settings to identify the device and read the firmware version. This service is not needed for **Immediate Alert** to work.

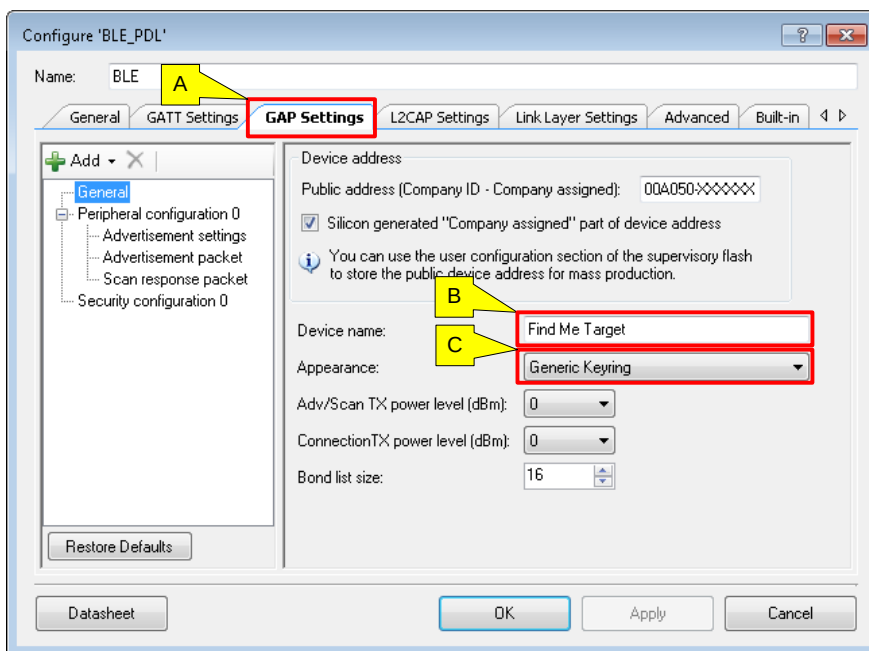
7. Specify the Generic Access Profile (GAP) general settings.

There is a series of panels to cover GAP settings. The left menu provides access to all the panels. See [Figure 27](#).

- A. Click the **GAP Settings** tab to display GAP options. The **General** panel appears by default.
- B. Enter **Find Me Target** as the **Device name**.
- C. Set the **Appearance** to **Generic Keyring**.

All other general settings use default values. This includes that the device uses **Silicon generated "Company assigned" part of device address**. This configures the device name and type that appears when a Host device attempts to discover your device, and then assigns a unique BLE device address to your device.

Figure 27. BLE Component General GAP Settings



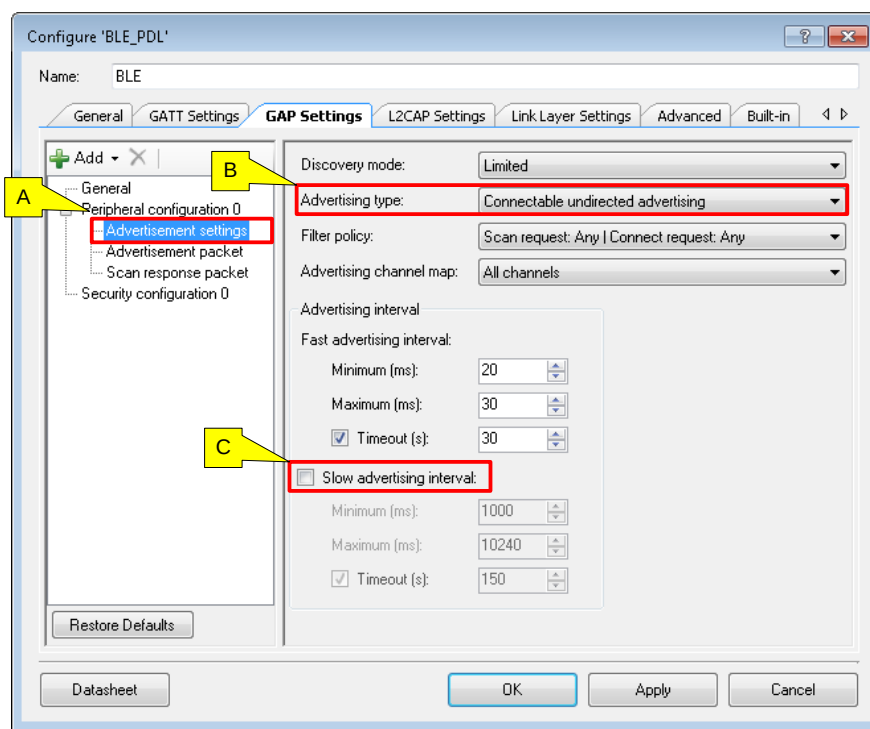
8. Specify the GAP advertisement settings.

See Figure 28 for help with this step.

- A. Click the **Advertisement settings** item in the left menu. The panel appears.
- B. Set **Advertising type** to **Connectable undirected advertising**.
- C. Deselect the **Slow advertising interval** checkbox.

Other than that, default values work for this application. It uses limited discovery mode with an advertising timeout of 30 seconds and a fast advertising interval of 20 to 30 ms. Fast advertising allows quick discovery and connection but consumes more power due to increased RF advertisement packets.

Figure 28. BLE Component GAP Advertisement Settings



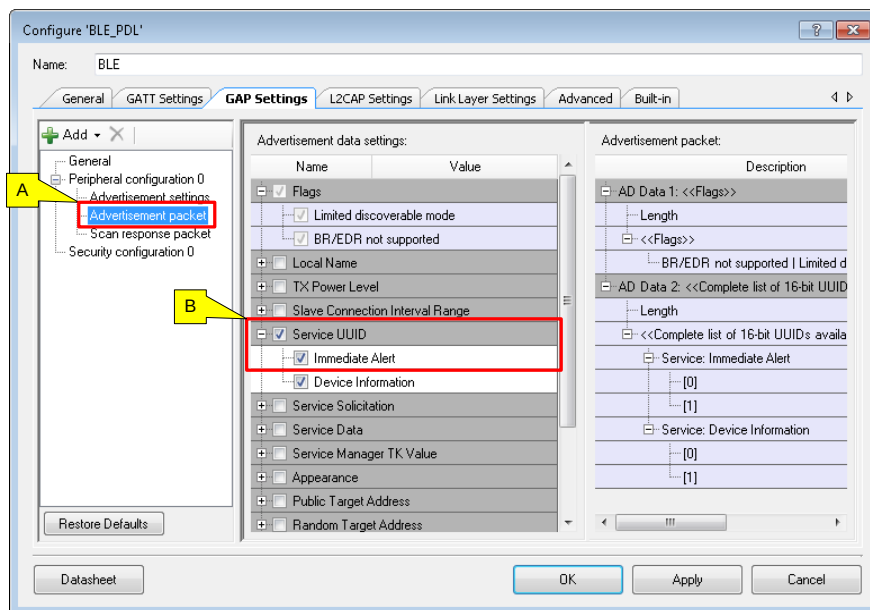
9. Specify the GAP advertisement packet settings.

In this step, you enable the device for the Immediate Alert Service (IAS). See [Figure 29](#).

- A. Click the **Advertisement packet** item in the left menu. The panel appears.
- B. Expand the **Service UUID** item, and select **Immediate Alert**.

This configures the device to notify BLE Central devices that the IAS is available. As you add items, the structure and content of the advertisement packet appears to the right of the configuration panel.

Figure 29. BLE Component GAP Advertisement Packet Settings

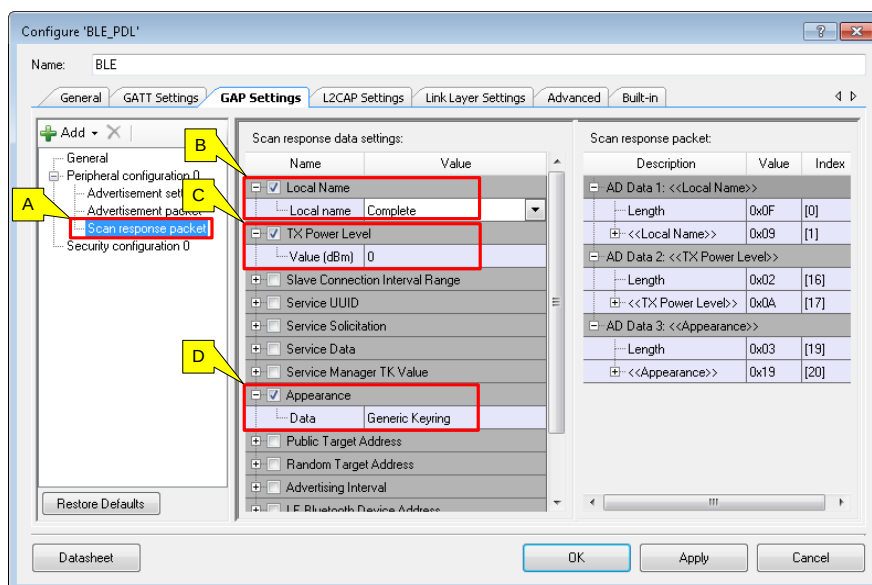


10. Specify scan response packet settings.

In this step, you specify the configuration for the Scan response packet. Figure 30 shows the result. Note that as you add values, the structure and content of the scan response packet appears to the right of the configuration panel.

- Click the **Scan response packet** item in the left menu. The panel appears.
- Select **Local Name** to include that item in the response. The default setting of **Complete** is **OK**.
- Select **TX Power Level** to include that item in the packet.
- Select **Appearance** to include that item in the packet.

Figure 30. BLE Component GAP Scan Response Packet

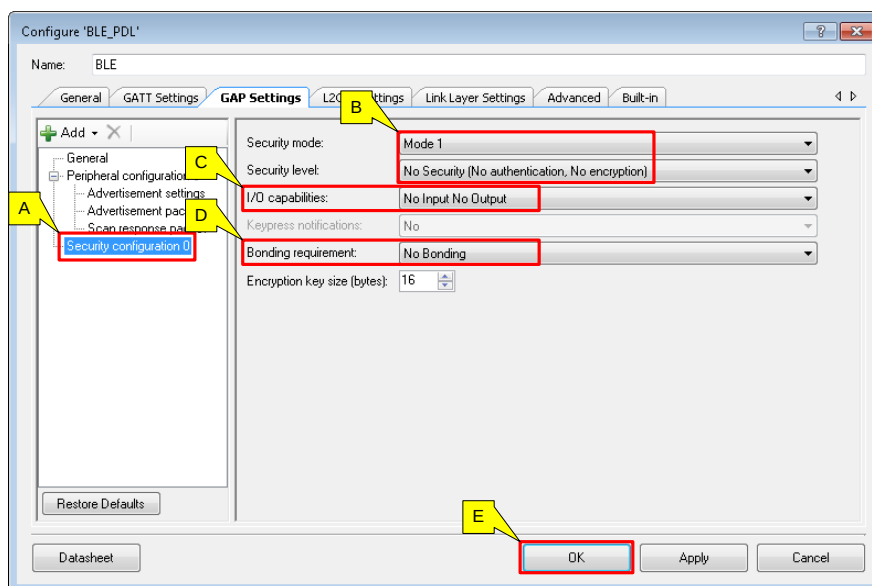


11. Specify security configuration settings.

In this step, you configure security settings for the device. It uses a configuration that does not require authentication, encryption, or authorization for data exchange. See [Figure 31](#).

- A. Click the **Security configuration 0** item in the left menu. The panel appears.
- B. Confirm that **Security mode** is **Mode 1** and **Security level** is **No Security**. If not, modify the settings.
- C. Set **IO capabilities** to **No Input No Output**.
- D. Set **Bonding requirement** to **No Bonding**.
- E. Click **OK** to complete the configuration of the BLE Component.

Figure 31. BLE Component GAP Security Settings



In this design, all other settings use default values, including all options in the **LDCAP Settings**, **Link Layer Settings**, and **Advanced** tabs.

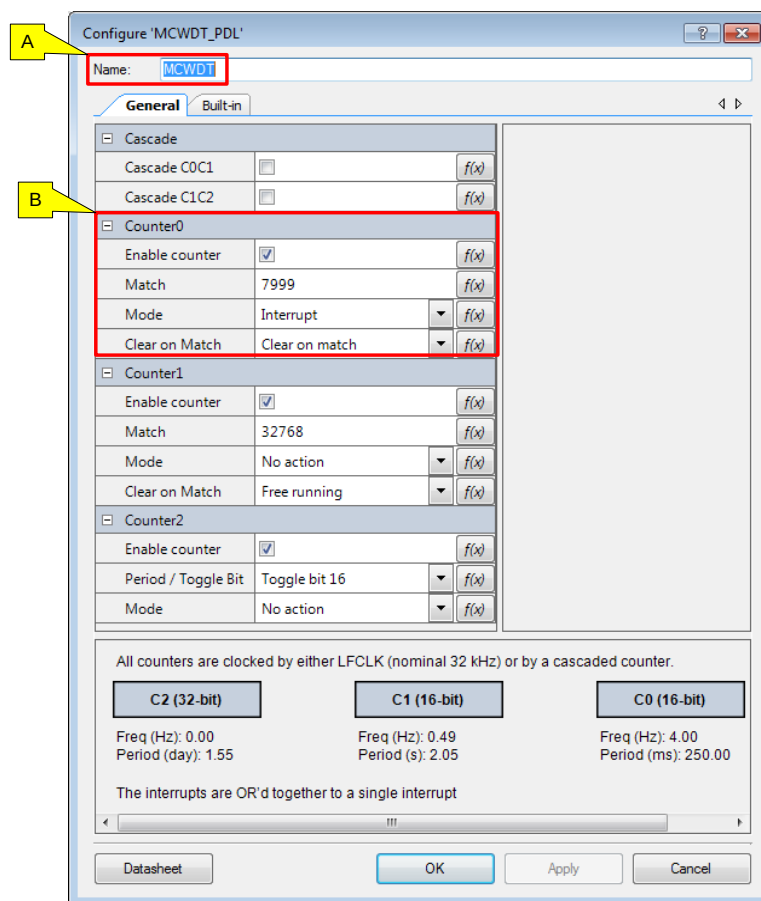
See the Component datasheet to learn the significance of each setting.

12. Configure the MCWDT Component to trigger an interrupt.

In this step, you configure the Multi-Counter Watchdog (MCWDT) Component to trigger an interrupt every 250 ms (4 Hz). The clock source of the MCWDT is the low frequency clock (LFCLK). The LFCLK's source is the Internal Low Speed Oscillator (ILO) by default. The design will use this interrupt to blink the Alert LED at 2 Hz when a MILD alert is received. See [Figure 32](#). Double click the Component placed on the schematic and configure as below.

- Change the **Name** to **MCWDT**.
- For Counter0, change the **Match** value to **7999**, **Mode** to **Interrupt**. Set the **Clear on Match** field to **Clear on match**.
- Click **OK** to complete the configuration of the MCWDT Component.

Figure 32. MCWDT_PDL Settings

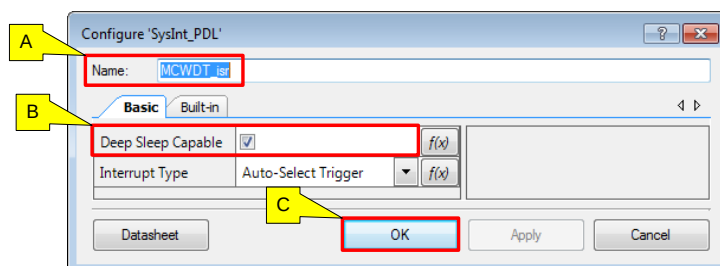


13. Configure the interrupt Component to wake up the CM4 CPU in Deep Sleep mode.

In this step, you configure the SysInt Component to wake up the CM4 CPU. See [Figure 33](#).

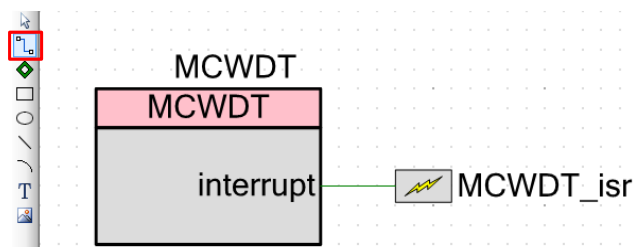
- A. Change the **Name** to **MCWDT_isr**.
- A. Select the interrupt to be **Deep Sleep Capable**.
- B. Click **OK** to complete the configuration of the SysInt Component.

Figure 33. SysInt_PDL Settings



As a final step, connect the interrupt output of the MCWDT Component to MCWDT_isr Component input. This routes the watchdog interrupt to the CPU (the selection of the CM4 CPU for this interrupt will be set in the system interrupt configuration in a later step). In the schematic, use the wire tool button or press the **W** key to start wiring the Components.

Figure 34. Connect MCWDT Peripheral Interrupt to CM4 CPU



14. Set the physical pins for each pin Component.

One task remains to complete the design. You must associate each Component with the required physical pins on the device. The choice of which pin to use is driven by the board design. You can find this information in the kit schematic. Figure 35 shows the end result of this step.

To set a pin, type either the port number or pin number in the corresponding field, or use the drop-down menu to pick the port or pin. Typically, the port number is used instead of the pin number since these names are independent of the specific package being used.

- A. Open the pin selector.

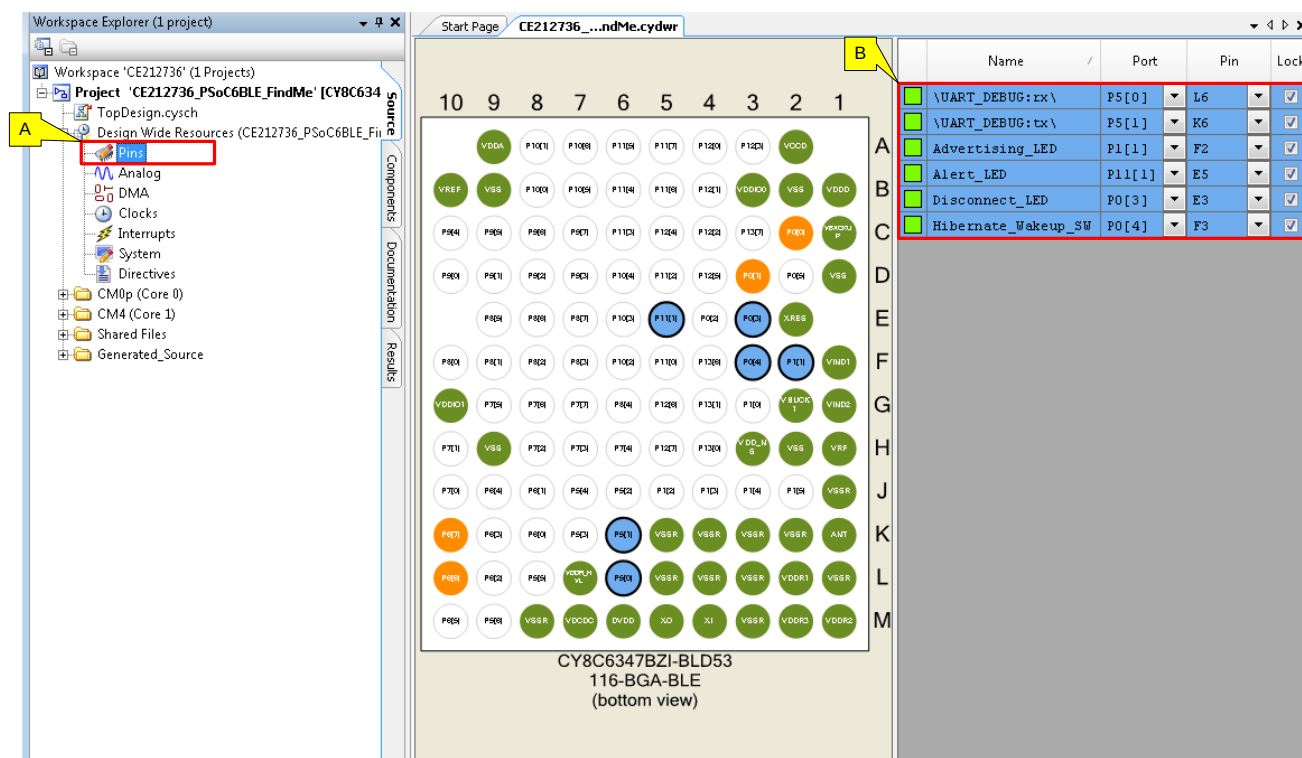
In the **Workspace Explorer** pane, double-click the **Pins** item under the Design Wide Resources. The pin selector for this device appears.

- B. Set each pin as shown in Table 1.

Table 1. Physical Pin Assignments for CY8CKIT-062-BLE

Pin Component Name	Port Name
UART_DEBUG:rx	P5[0]
UART_DEBUG:tx	P5[1]
Advertising_LED	P1[1]
Alert_LED	P11[1]
Disconnect_LED	P0[3]
Hibernate_Wakeup_SW	P0[4]

Figure 35. Pin Assignment



Name	Port	Pin	Lock
\UART_DEBUG:rx\	P5[0]	L6	☒
\UART_DEBUG:tx\	P5[1]	K6	☒
Advertising_LED	P1[1]	F2	☒
Alert_LED	P11[1]	E5	☒
Disconnect_LED	P0[3]	E3	☒
Hibernate_Wakeup_SW	P0[4]	F3	☒

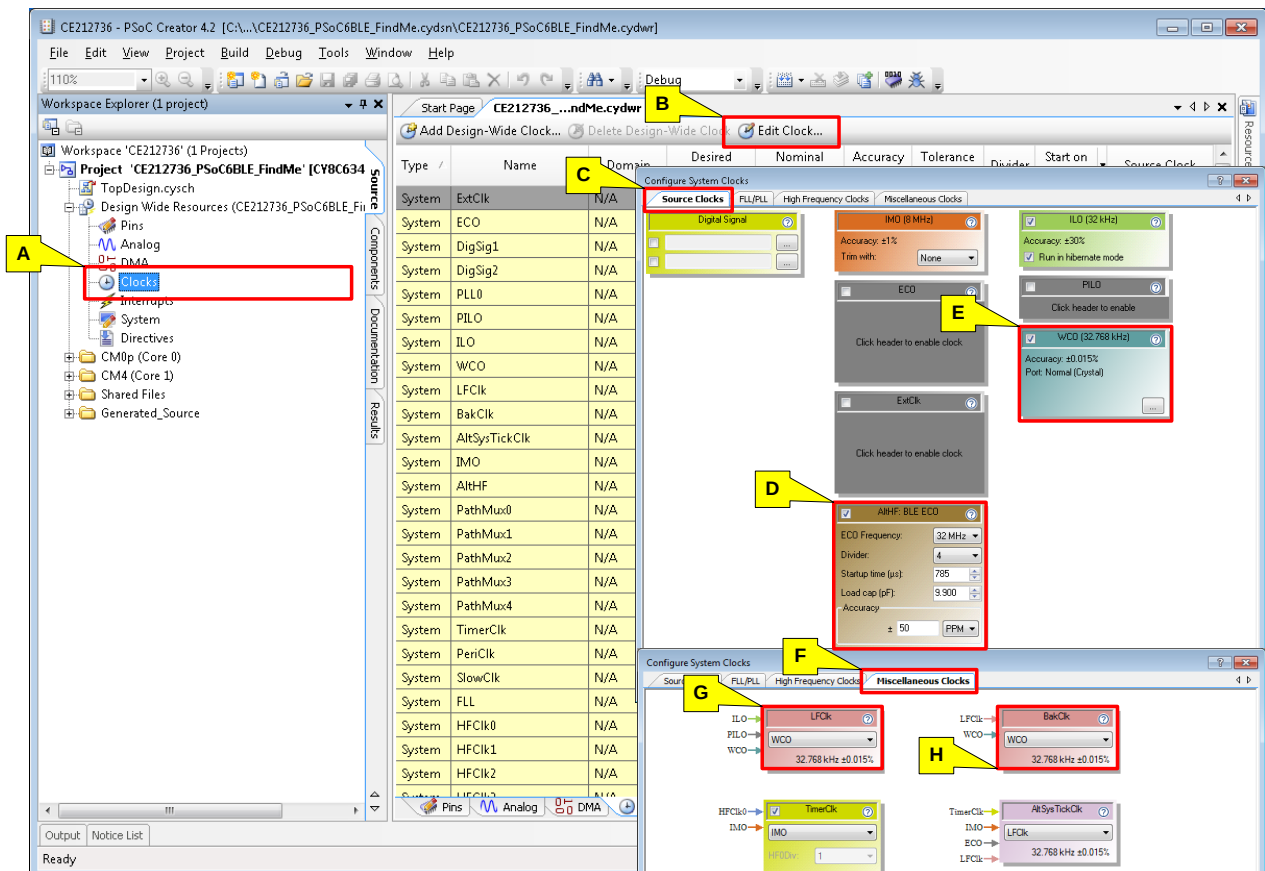
15. System Clock Configuration

The design uses default values for the high frequency system clock settings. Although you do not modify high frequency clocks for this design, you should know how PSoC Creator manages them. If you are working with your own board, you may need to modify these clocks.

In this step, you set the low frequency clock source to be the accurate watch crystal oscillator (WCO) on the board. This clock is used by the BLE Subsystem (BLESS) for timing purposes.

- In the **Workspace Explorer** pane, double-click the **Clocks** item under **Design Wide Resources (CE212736.cydw)**. The list of clocks appears.
- Click **Edit Clock...** and the **Configure System Clocks** dialog appears.
 Here you can see the clock tree, and modify the clocks as required. Note that there are tabs for different types of clocks such as **Source Clocks**, **FLL/PLL**, **High Frequency Clocks**, and **Miscellaneous Clocks**.
- Click the **Source Clocks** tab.
- Enable the BLE ECO by selecting the checkbox in the **AltHF BLE ECO** block. The parameters should match the crystal used on the board. For the CY8CKIT-062-BLE kit, the **ECO Frequency** is **32 MHz**, and **Accuracy** is **± 50 ppm**. There are no load caps on the board and hence use the minimum specified **Load cap (pF)** of **9.900**. Ensure that the **Startup Time (µs)** is **785 µs** for a quick startup of the ECO crystal.
- Enable the WCO clock by selecting the checkbox in the **WCO (32.768 kHz)** block.
- Click the **Miscellaneous Clocks** tab.
- Select **WCO** to be the source for **LFCIk**.
- Select **WCO** to be the source for **BakCik**. See [Figure 36](#).

Figure 36. Clock Configuration



16. System Interrupt Configuration

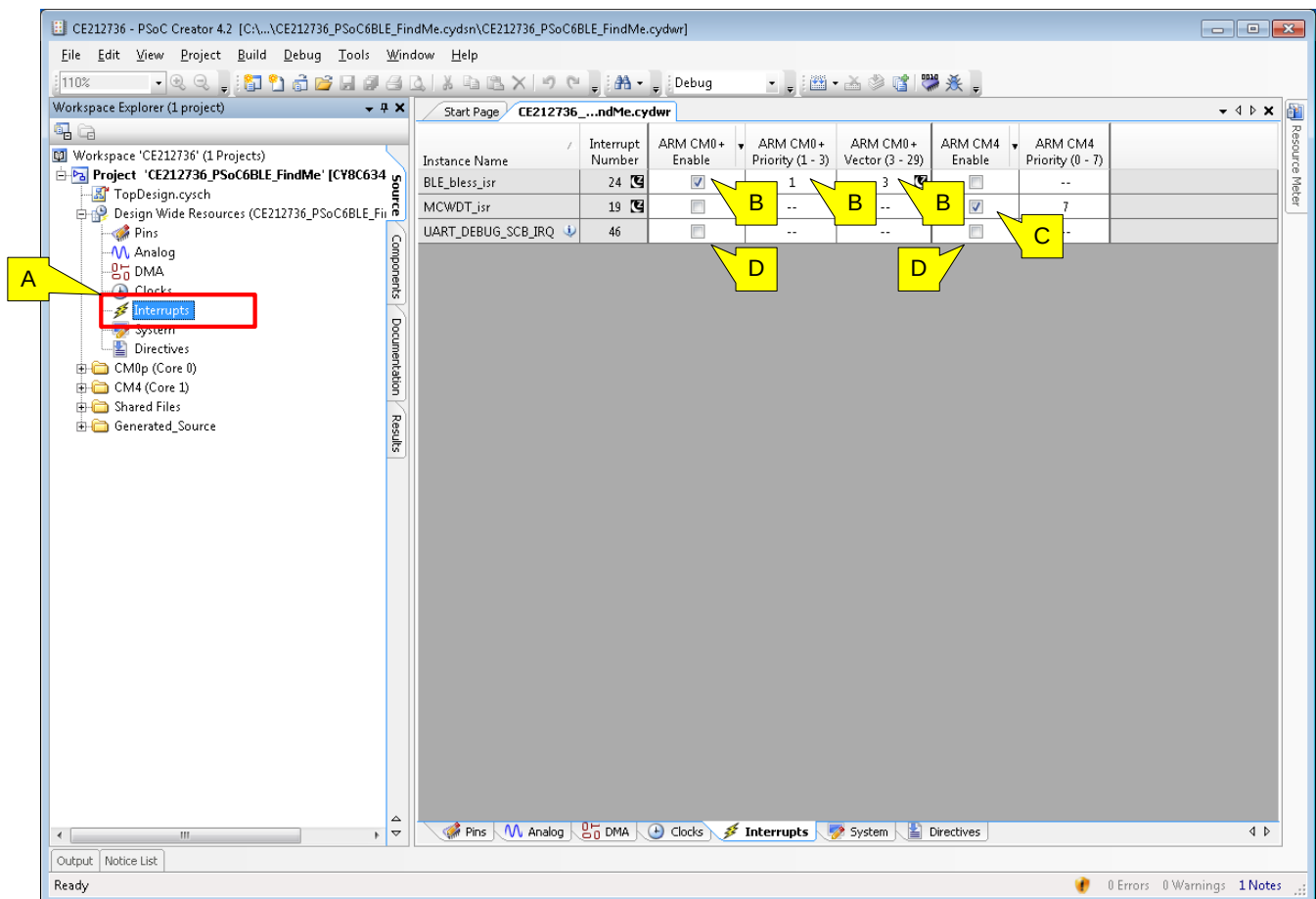
In this step, you configure the system interrupts. See [Figure 37](#).

- In the **Workspace Explorer** pane, double-click the **Interrupts** item under **Design Wide Resources**. The list of interrupts appears.
- Confirm that the **BLE_bless_isr** is enabled for the CM0+ CPU, the priority is set to **1**, and vector is set to **3**. This ensures that the BLE controller interrupts are handled by CM0+ at the highest priority, and in Deep Sleep mode as well.
- Enable **MCWDT_isr** for CM4.
- Disable the **UART_DEBUG_SCB_IRQ** interrupt for both cores.

Deselect the corresponding checkboxes. You can ignore the interrupt related to UART_DEBUG Component because the design does not use it.

The interrupt numbers are generated automatically by PSoC Creator when you generate the code in [Part 3: Generate Source Code](#).

Figure 37. Interrupt Configuration



The next part in the development process is to generate code.

Note: This exercise does not detail how to export your work to a target IDE. However, if you wish to use a target IDE this is the point in the workflow where you would ensure that the correct target IDE is selected, before you generate code. See [Support for Other IDEs](#).

5.6 Part 3: Generate Source Code

PSoC Creator generates source code based upon the design. The recommended workflow is to generate code before writing firmware. PSoC Creator will automatically create macros, constants, and API calls that you may then use in your firmware.

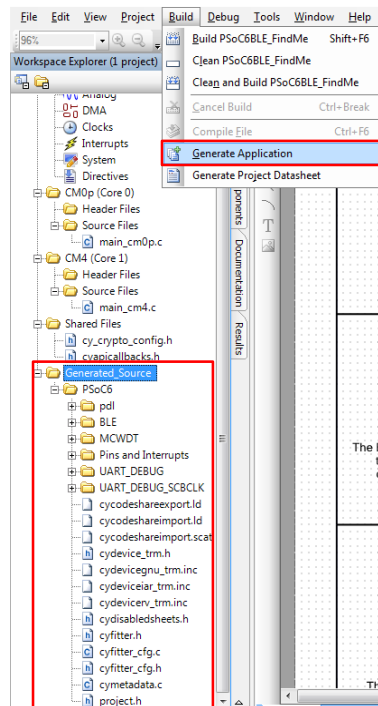
This part of the exercise is very simple, and the path is the same for everyone.

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform the one step.	Perform the one step.	Perform the one step.

1. Generate the application.

Choose **Build > Generate Application**. PSoC Creator generates source code based on the design and puts the files in the *Generated_Source* folder. See [Figure 38](#). PSoC Creator will alert you to errors or problems that may occur. If you are working from scratch and encounter errors, revisit the configuration steps in [Part 2: Implement the Design](#) to ensure you have performed them correctly.

Figure 38. Generate Application

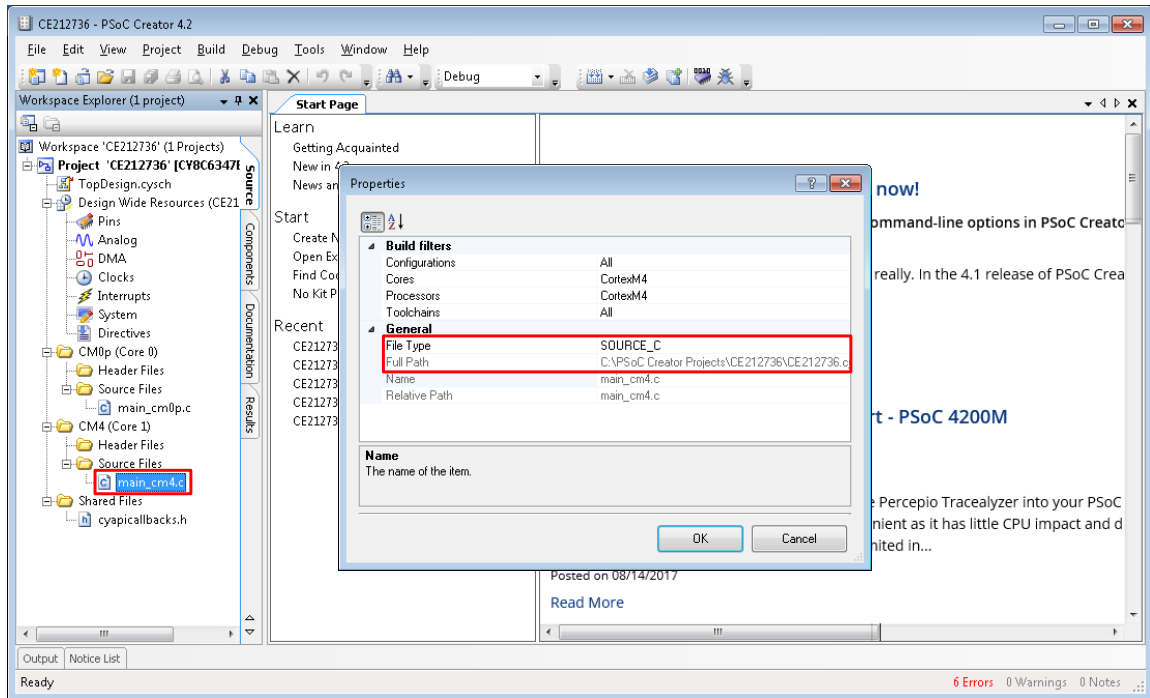


Background: PSoC 6 BLE is a dual-CPU platform. You can target firmware to run either on CM4 or CM0+. You set this at the source file level by accessing the file properties. Right-click a source file and select **Properties**. Figure 39 shows the **Properties** dialog window. This code example targets the CM4 core.

By default, the *main_cm0p.c* file is targeted to CM0+ and the *main_cm4.c* file is targeted to CM4. You do not need to modify the properties for any other file. They are already set in the code example.

By convention, files targeted to run on the CM0+ are in the *CM0p* folder and files targeted to run on CM4 are in the *CM4* folder, but the properties must also be set appropriately – just putting a file in the correct folder does not cause it to run on a specific core.

Figure 39. Setting Target Processor for a Source C File



5.7 Part 4: Write the Firmware

At this point in the development process you have created a project, implemented a hardware design, and generated code. In this part, you examine the firmware that implements BLE functionality in the application.

The firmware must accomplish several tasks to implement a BLE standard profile application, including:

- Perform system initialization
- Implement a BLE stack event handler
- Implement a BLE service-specific event handler
- Provide the main loop
- Implement low-power performance (optional)

The steps in this part discuss the firmware for the design that you configured in [Part 2: Implement the Design](#). The steps do not examine every single line of code, but point out important elements in the code that implement significant functionality.

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform all steps.	Skip step one. Perform all other steps.	Skip this part if you wish. Jump to Part 5: Build the Project, Program the Device

The code example has all the required code. If you are working from scratch, in step one you copy the source files from the code example project. If you are using the code example, those files are already in your project, so you can skip step one.

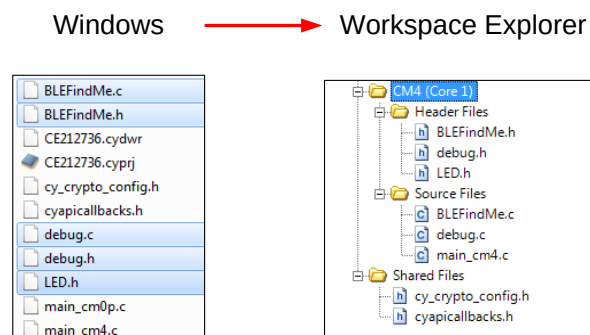
1. Add files to your project.

If you are using the code example, you can skip this step. The code example already has the required source files.

If you are working from scratch, the required source code files are not in your project.

- A. Locate the *CE212736.cydsn* folder, which contains the source files for the code example. The folder is in the Code Example workspace archive that you downloaded earlier.
- B. Copy these files from the *CE212736.cydsn* folder to your project's *.cydsn* folder. Replace any existing files.
 - *BLEFindMe.h*
 - *debug.h*
 - *LED.h*
 - *BLEFindMe.c*
 - *debug.c*
 - *main_cm0p.c*
 - *main_cm4.c*
- C. Add these files to your project. You can do this by dragging them from the *Windows* folder onto the Workspace explorer, and dropping them in the *CM4* folder location in the workspace. See [Figure 40](#).
 - *BLEFindMe.h*
 - *debug.h*
 - *LED.h*
 - *BLEFindMe.c*
 - *debug.c*

Figure 40. Add Files to Your Project



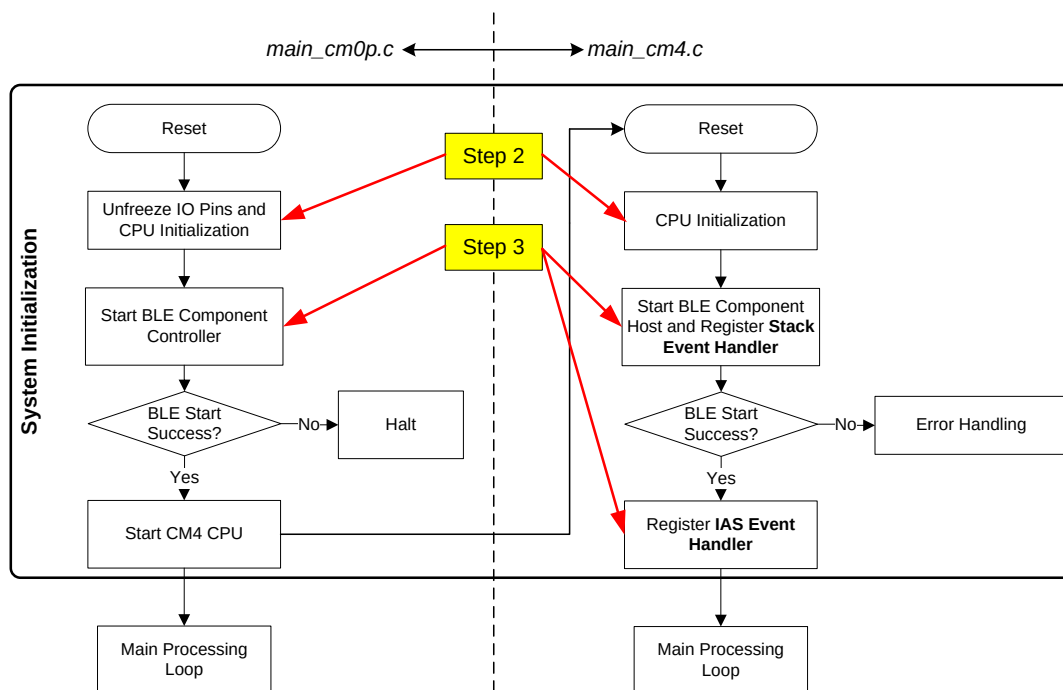
You do not have to add *main_cm0p.c* or *main_cm4.c*. The project has these files by default. You just replaced them in the *project* folder, so the project will use the newer version you just copied.

2. Initialize the system.

In the remaining steps, we examine code in the *main_cm0p.c* and *main_cm4.c* file. The code snippets frequently have the debugging print statements removed for clarity. See the actual source file for a complete understanding of the code.

Figure 41 shows the steps in the process of initializing the system. When the PSoC 6 BLE device is reset, the firmware first performs system initialization, which includes setting up the CPU cores for execution, enabling global interrupts, and enabling other Components used in the design. The initialization is split across the CPU cores. The CM0p CPU comes out reset and attempts to start the BLE controller part. If it is successful, the CM0p CPU then enables CM4 CPU. The CM4 CPU will start the BLE host part and register the necessary application side handler functions.

Figure 41. System Initialization Flowchart – CM4



The code in *main_cm0p.c* declares a local variable to hold the return value from BLE API calls. The key task is to enable the BLE controller, and set up the CM4 for the application code to run. In the main loop, the CM0p CPU processes the BLE events pending on the controller. In case of no pending events, the CM0p enters Deep Sleep mode.

```

int main(void)
{
    cy_en_ble_api_result_t      apiResult;
    __enable_irq(); /* Enable global interrupts. */
    /* Unfreeze IO if device is waking up from hibernate */
    if(Cy_SysPm_GetIoFreezeStatus())
    {
        Cy_SysPm_IoUnfreeze();
    }

    /* Start the Controller portion of BLE. Host runs on the CM4 */
    apiResult = Cy_BLE_Start(NULL);
    if(apiResult == CY_BLE_SUCCESS)
    {
        /* Enable CM4 only if BLE Controller started successfully.
         * CY_CORTEX_M4_APPL_ADDR must be updated if CM4 memory layout
         * is changed. */
        Cy_SysEnableCM4(CY_CORTEX_M4_APPL_ADDR);
    }
    else
    {
        /* Halt CPU */
        CY_ASSERT(0u != 0u);
    }

    for(;;)
    {
        /* Place your application code here. */
        /* Put CM0p to deep sleep. */
        Cy_SysPm_DeepSleep(CY_SYSPM_WAIT_FOR_INTERRUPT);

        /* Cy_Ble_ProcessEvents() allows BLE stack to process
         pending events */

        /* The BLE Controller automatically wakes up host if required */
        Cy_BLE_ProcessEvents();
    }
}

```

The code in `main_cm4.c` initializes the key Components to be used by the CM4 and continuously runs a BLE application process. The `BleFindMe_Init()` routine initializes and starts all the Components, including setting up the CM4 interrupt. It performs the key task of enabling the BLE host.

In the application process, the CM4 CPU processes the BLE events pending on the host. If there are no events pending, the CM4 enters Deep Sleep low-power mode.

```

int main(void)
{
    __enable_irq(); /* Enable global interrupts. */

    /* Initialize BLE */
}

```

```

BleFindMe_Init();

for(;;)
{
    BleFindMe_Process();
}

```

3. Start the BLE Component and register the event handlers.

After the CPUs are initialized, the firmware initializes the BLE Component, which sets up the complete BLE subsystem. The `BleFindMe_Init()` subroutine handles the work. To focus on the key tasks, debug print statements have been removed. Examine the source file to see the full code.

As a part of the BLE Component initialization, you must pass the event handler function, which will be called by the BLE stack to notify of pending events. If the BLE Component initializes successfully, the firmware registers a second event handler for events specific to the IAS.

The code uses PDL API function calls to configure the application. First it starts the BLE Component. The parameter is the address of the stack event handler function.

The code also gets the stack version. In case the debug port is enabled, the version is printed in the serial communication window.

It then registers the IAS event handler to handle Immediate Alert Service related events. Finally, it configures and enables the MCWDT to trigger interrupts once every 250 ms.

```

void BleFindMe_Init(void)
{
    cy_en_ble_api_result_t      apiResult;
    cy_stc_ble_stack_lib_version_t  stackVersion;

    /* Configure switch SW2 as hibernate wake up source */
    Cy_SysPm_SetHibWakeupSource(CY_SYSPM_HIBPIN1_LOW);

    /* Start BLE component and register generic event handler */
    apiResult = Cy_BLE_Start(StackEventHandler);

    apiResult = Cy_BLE_GetStackLibraryVersion(&stackVersion);

    /* Register IAS event handler */
    Cy_BLE_IAS_RegisterAttrCallback(IasEventHandler);

    /* Enable 4 Hz free-running MCWDT counter 0 */
    /* MCWDT_config structure is defined by the MCWDT_PDL component based on
       parameters entered in the customizer. */
    Cy_MCWDT_Init(MCWDT_HW, &MCWDT_config);
    Cy_MCWDT_Enable(MCWDT_HW, CY_MCWDT_CTR0, 93 /* 2 LFCLK cycles */);
    /* Unmask the MCWDT counter 0 peripheral interrupt */
    Cy_MCWDT_SetInterruptMask(MCWDT_HW, CY_MCWDT_CTR0);

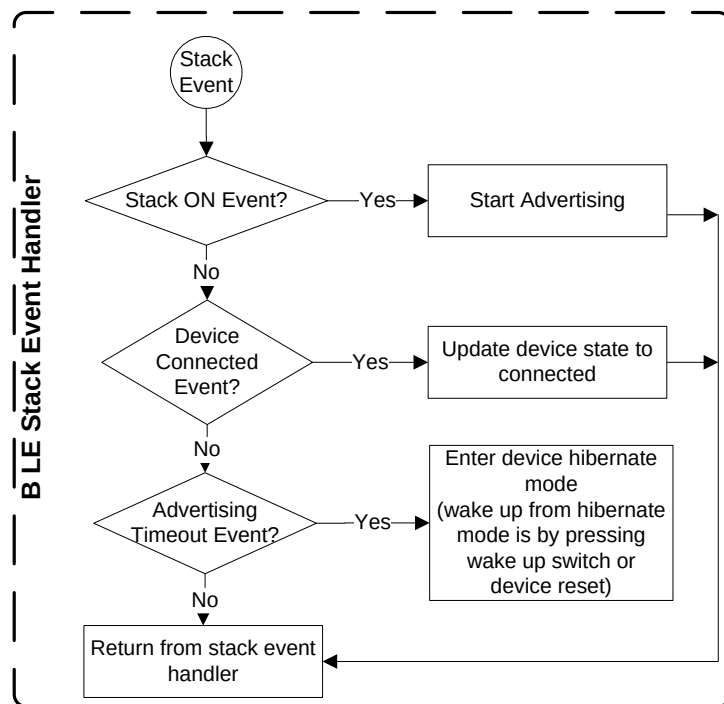
    /* Configure ISR connected to MCWDT interrupt signal */
    /* MCWDT_isr_cfg structure is defined by the SYSINT_PDL component based on
       parameters entered in the customizer. */
    Cy_SysInt_Init(&MCWDT_isr_cfg, &MCWDT_Interrupt_Handler);
    /* Clear CM4 NVIC pending interrupt for MCWDT */
    NVIC_ClearPendingIRQ(MCWDT_isr_cfg.intrSrc);
    /* Enable CM4 NVIC MCWDT interrupt */
    NVIC_EnableIRQ(MCWDT_isr_cfg.intrSrc);
}

```

4. Implement the stack event handler.

The BLE stack within the BLE Component generates events. These events provide status and data to the application firmware through the BLE stack event handler. Figure 42 shows a simplified flowchart representing certain events.

Figure 42. BLE Stack Event Handler Flowchart



The event handler must handle a few basic events from the stack. For the Find Me Target application in this code example, the BLE stack event handler must process the events described in Table 2. The actual code recognizes and responds to additional events, but they are not mandatory for this application.

Table 2. BLE Stack Events

BLE Stack Event Name	Event Description	Event Handler Action
CY_BLE_EVT_STACK_ON	BLE stack initialization is completed successfully.	Start advertisement and reflect the advertisement state on the LED.
CY_BLE_EVT_GAP_DEVICE_DISCONNECTED	BLE link with the peer device is disconnected.	Restart advertisement and reflect the advertisement state on the LED.
CY_BLE_EVT_GAP_DEVICE_CONNECTED	BLE link with the peer device is established.	Update the BLE link state on the LED.
CY_BLE_EVT_GAPP_ADVERTISEMENT_START_STOP	BLE stack advertisement start/stop event	Shutdown the BLE stack.
CY_BLE_EVT_HARDWARE_ERROR	BLE hardware error	Update the LED status to reflect a hardware error and halt the CPU.
CY_BLE_EVT_STACK_SHUTDOWN_COMPLETE	BLE stack has been shut down.	Configure the device in Hibernate mode and wait for event on wakeup pin.

The code snippets show two examples of how the event handler responds to an identified event. See the actual source code for a complete understanding.

In this snippet, the handler responds to the “advertisement start/stop” event. The code toggles the LEDs appropriately. If advertisement has started, the advertisement LED turns on. The disconnect LED turns off, because the device started advertisement and is ready for a connection. If advertising is stopped, the code sets the LEDs appropriately, and sets a flag to enter Hibernate mode.

```

/* This event indicates peripheral device has started/stopped advertising */
case CY_BLE_EVT_GAPP_ADVERTISEMENT_START_STOP:
    DEBUG_PRINTF("CY_BLE_EVT_GAPP_ADVERTISEMENT_START_STOP: ");
    if(Cy_BLE_GetAdvertisementState() == CY_BLE_ADV_STATE_ADVERTISING)
    {
        DEBUG_PRINTF("Advertisement started \r\n");
        Cy_GPIO_Write(Advertising_LED_0_PORT, Advertising_LED_0_NUM, LED_ON);
        Cy_GPIO_Write(Disconnect_LED_0_PORT, Disconnect_LED_0_NUM, LED_OFF);
    }
    else if(Cy_BLE_GetAdvertisementState() == CY_BLE_ADV_STATE_STOPPED)
    {
        DEBUG_PRINTF("Advertisement stopped \r\n");
        Cy_GPIO_Write(Advertising_LED_0_PORT, Advertising_LED_0_NUM, LED_OFF);
        Cy_GPIO_Write(Disconnect_LED_0_PORT, Disconnect_LED_0_NUM, LED_ON);

        /* Advertisement event timed out before connection, shutdown BLE
         * stack to enter hibernate mode and wait for device reset event
         * or SW2 press to wake up the device */
        Cy_BLE_Stop();
    }
    break;

```

In this snippet, the handler responds to the “disconnected” event. It sets the LEDs correctly, and sets the Hibernate flag.

```

/* This event is generated when disconnected from remote device or
   failed to establish connection. */

case CY_BLE_EVT_GAP_DEVICE_DISCONNECTED:
    if(Cy_BLE_GetConnectionState(appConnHandle) ==
    CY_BLE_CONN_STATE_DISCONNECTED)
    {
        DEBUG_PRINTF("CY_BLE_EVT_GAP_DEVICE_DISCONNECTED %d\r\n",
        CY_BLE_CONN_STATE_DISCONNECTED);
        alertLevel = CY_BLE_NO_ALERT;

        Cy_GPIO_Write(Advertising_LED_0_PORT, Advertising_LED_0_NUM, LED_OFF);
        Cy_GPIO_Write(Disconnect_LED_0_PORT, Disconnect_LED_0_NUM, LED_ON);

        /* Enter into discoverable mode so that remote device can search it */
        apiResult = Cy_BLE_GAPP_StartAdvertisement(CY_BLE_ADVERTISING_FAST,
        CY_BLE_PERIPHERAL_CONFIGURATION_0_INDEX);

        if(apiResult != CY_BLE_SUCCESS)
        {
            DEBUG_PRINTF("Start Advertisement API Error: %d \r\n", apiResult);
            ShowError();
            /* Execution does not continue beyond this point */
        }
        else
        {
            DEBUG_PRINTF("Start Advertisement API Success: %d \r\n", apiResult);
            Cy_GPIO_Write(Advertising_LED_0_PORT, Advertising_LED_0_NUM, LED_ON);
            Cy_GPIO_Write(Disconnect_LED_0_PORT, Disconnect_LED_0_NUM, LED_OFF);
        }
    }
    break;

```

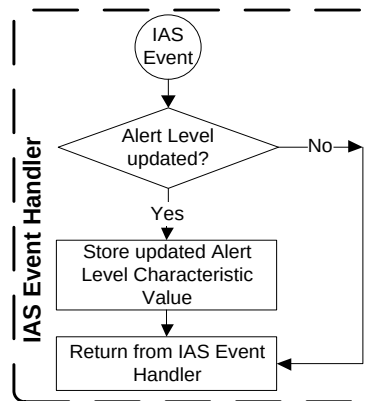
These snippets give you a sense for how the event handler responds to events. Examine the actual function to see how each event is handled.

5. Implement the service-specific event handler.

The BLE Component also generates events corresponding to each of the services supported by the design. For the Find Me Target application, the BLE Component generates IAS events that let the application know that the Alert Level characteristic has been updated with a new value. The event handler gets the new value and stores it in the variable `alertLevel`. The main loop toggles the alert LED based on the current alert level.

Figure 43 shows the IAS event handler flowchart.

Figure 43. BLE IAS Event Handler Flowchart



The code snippet shows how the firmware accomplishes this task.

```

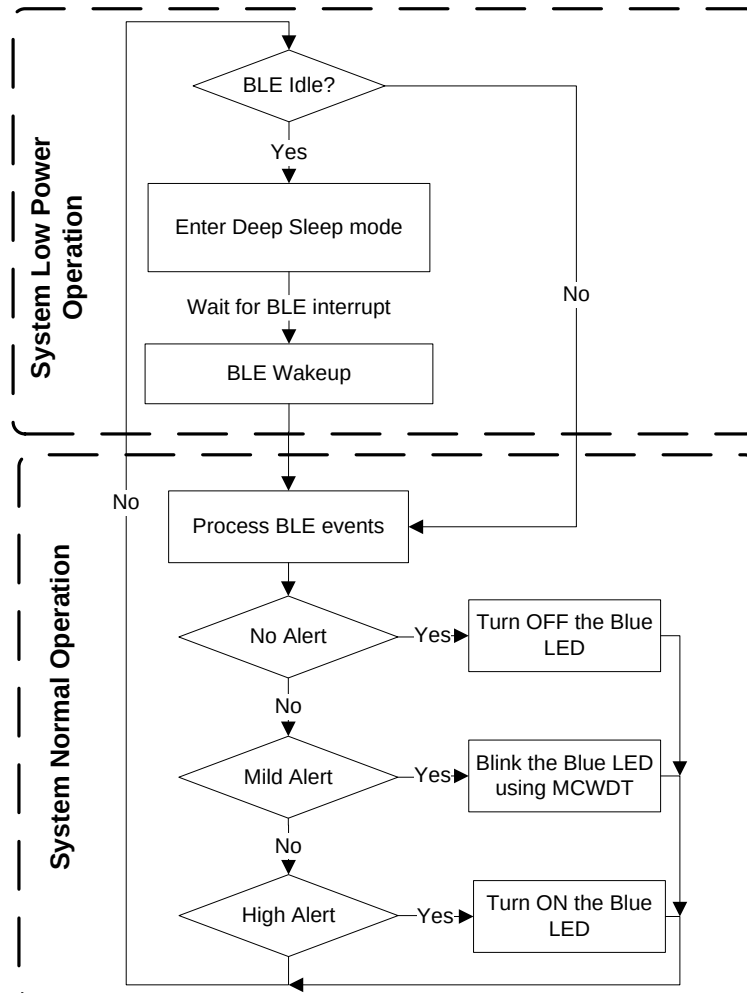
void IasEventHandler(uint32 event, void *eventParam)
{
    /* Alert Level Characteristic write event */
    if(event == CY_BLE_EVT_IASS_WRITE_CHAR_CMD)
    {
        /* Read the updated Alert Level value from the GATT database */
        Cy_BLE_IASS_GetCharacteristicValue(CY_BLE_IAS_ALERT_LEVEL,
            sizeof(alertLevel), &alertLevel);
    }

    /* To remove unused parameter warning */
    eventParam = eventParam;
}
  
```


6. Process events as they occur (main loop).

The main loop simply calls `BleFindMe_Process()`. Figure 44 shows the `BleFindMe_Process()` flowchart.

Figure 44. Firmware Main Loop Flowchart



If there are no pending BLE host events and there is no active interaction, the application goes into Low-Power mode. It then tells the BLE to process events, and updates the LEDs based on the alert level.

```

/* The call to EnterLowPowerMode also causes the device to enter hibernate
mode if the BLE is disconnected. */
EnterLowPowerMode();
/* Cy_Ble_ProcessEvents() allows BLE stack to process pending events */
Cy_BLE_ProcessEvents();

/* Update Alert Level value on the Blue LED */
switch(alertLevel)
{
    case CY_BLE_NO_ALERT:
        /* Disable MCWDT interrupt at NVIC */
        NVIC_DisableIRQ(MCWDT_isr_cfg.intrSrc);
        /* Turn the Blue LED OFF in case of no alert */
        Cy_GPIO_Write(Alert_LED_0, LED_OFF);
        break;

```

```

/* Use the MCWDT to blink the Blue LED in case of mild alert */
case CY_BLE_MILD_ALERT:
    /* Enable MCWDT interrupt at NVIC */
    NVIC_EnableIRQ(MCWDT_isr_cfg.intrSrc);
    /* The MCWDT interrupt handler will take care of LED blinking */
    break;

case CY_BLE_HIGH_ALERT:
    /* Disable MCWDT interrupt at NVIC */
    NVIC_DisableIRQ(MCWDT_isr_cfg.intrSrc);
    /* Turn the Blue LED ON in case of high alert */
    Cy_GPIO_Write(Alert_LED_0, LED_ON);
    break;

/* Do nothing in all other cases */
default:
    break;
}

```

This completes the summary of how the firmware works in the code example. Feel free to explore the source files for a deeper understanding.

5.8 Part 5: Build the Project, Program the Device

This section shows how to program the PSoC 6 BLE device. If you are using a development kit with a built-in programmer (the [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#), for example), connect the board to your computer using the USB cable. If you are developing on your own hardware, you may need a hardware programmer/debugger; for example, a Cypress [CY8CKIT-002 MiniProg3](#).

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform all steps.		

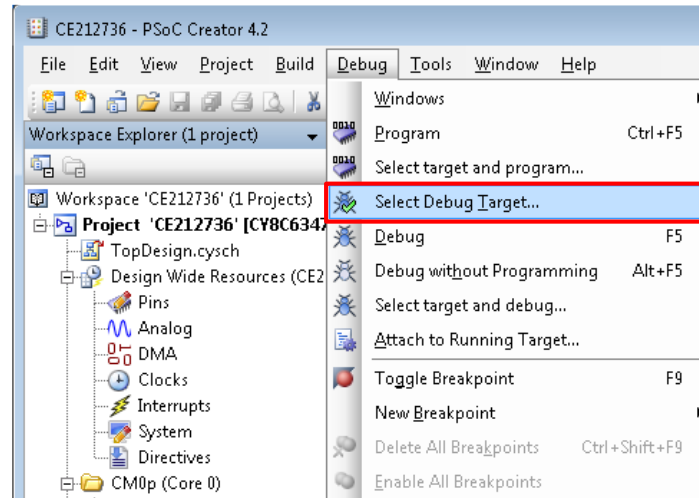
If you are working from scratch and encounter errors, revisit prior steps to ensure that you accomplished all the required tasks. You can work to resolve errors or switch to the code example for these final steps.

1. Select the debug target.

PSoC Creator can debug one core at a time.

- A. In PSoC Creator, choose **Debug > Select Debug Target**, as Figure 45 shows.

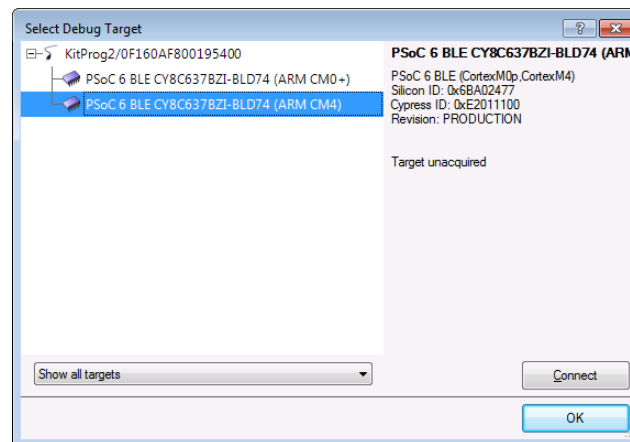
Figure 45. Selecting Debug Target



- B. Connect to the board.

In the **Select Debug Target** dialog box, select the CM4 target, then click **OK** or **Connect**, as Figure 46 shows.

Figure 46. Connecting to a Device

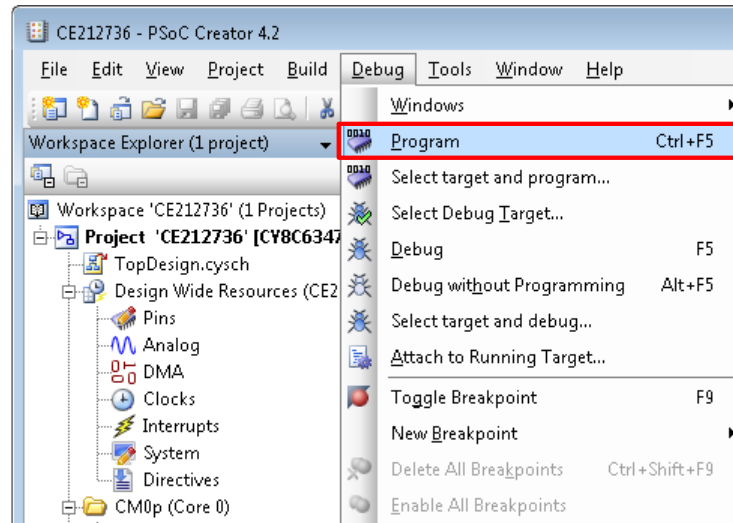


TIP: For programming the board you can pick either target. The cores share the same memory space. Programming either core programs both cores. However, if you are debugging this choice matters. The debugger will see only the core you connect to. These instructions do not use the debugger.

2. Program the board.

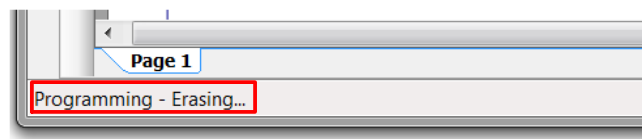
Choose **Debug > Program** to program the device with the project, as Figure 47 shows.

Figure 47. Programming the Device



You can view the programming status in the lower left corner of the window PSoC Creator window, as Figure 48 shows.

Figure 48. Programming Status



In a dual core application, the linker files put each executable at the correct location in memory. Execution begins on the CM0+ core, which enables the CM4 core.

When programming is complete, the application runs. The LED turns green, indicating that the target is advertising. After the advertising timeout occurs it turns red, indicating that it is disconnected.

TIP: The **Debug > Debug** command also programs the board. If any code needs to be generated or rebuilt, that happens automatically when you issue a **Program** or **Debug** command. You can also debug without programming the board. However, these instructions do not use the debugger.

NOTE: The KitProg2 firmware on the kit might require an update. Please refer to the kit user guide for step-by-step instructions on updating the firmware.

5.9 Part 6: Test Your Design

This section describes how to test your BLE design using either the [CySmart Mobile App](#) or the [CySmart Host Emulation Tool](#). The setup for testing your design using the BLE Pioneer Kit is shown in [Figure 8](#).

Path	Working from Scratch Code Example as Reference Only	Using Code Example New to PSoC Creator or BLE	Using Code Example Familiar with PSoC Creator and BLE
Actions	Perform either Step 1 or Step 2.		

1. Test using the CySmart Mobile App.

- Turn ON Bluetooth on your iOS or Android device.
- Launch the CySmart app.
- Press the reset switch on the BLE Pioneer Kit to start BLE advertisements from your design. The green LED must be ON for the CySmart app to see the device.
- Pull down the CySmart app home screen to start scanning for BLE Peripherals. The Find Me target appears as a BLE device in the CySmart app home screen. Tap to establish a BLE connection. If the phone does not find the target, press the reset button again, or try the CySmart Host Emulation tool (step 2).
- Select the “Find Me” Profile from the carousel view.
- Select an **Alert Level** value on the **Find Me** Profile screen and watch the state of the blue LED on your device change per your selection.

[Figure 49](#) shows this process using the iOS app. [Figure 50](#) shows the process using the Android app.

Figure 49. Testing with CySmart iOS App

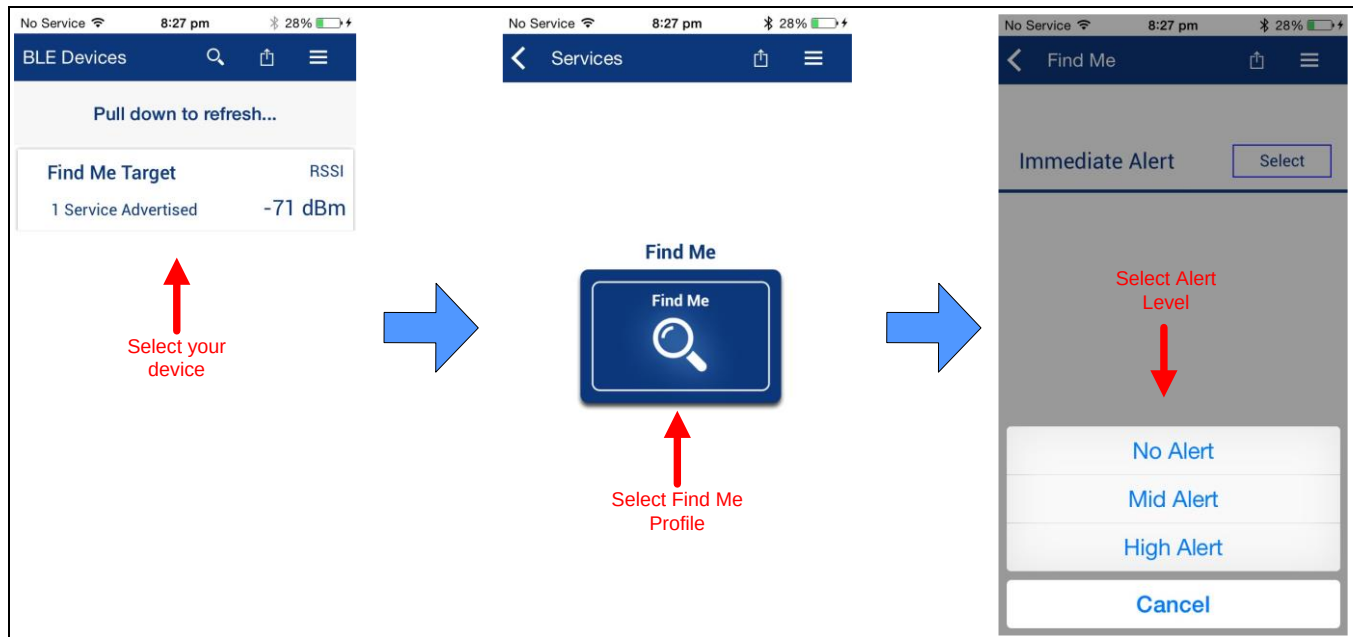
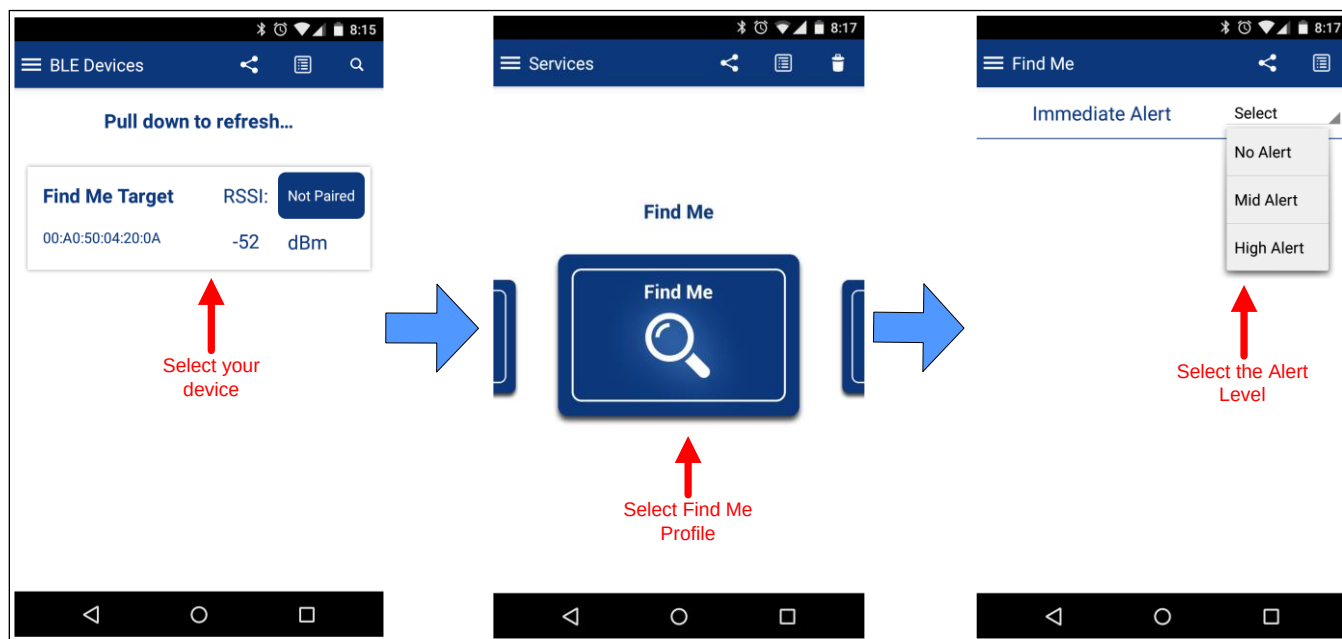


Figure 50. Testing with CySmart Android App



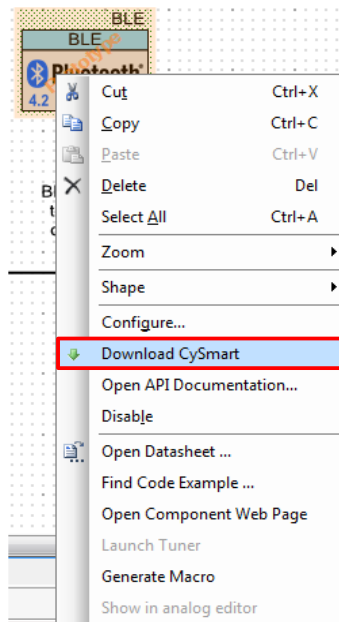
2. Test using the CySmart Host Emulation Tool.

As an alternative to the CySmart mobile app, you can use the CySmart Host Emulation Tool to establish a BLE connection with your design and perform read or write operations on BLE characteristics.

- A. If not already installed, install the CY Smart Host Emulation Tool.

Right-click the BLE Component symbol on the Top Schematic and select **Download CySmart** as shown in Figure 51. Follow the installer directions to install the tool.

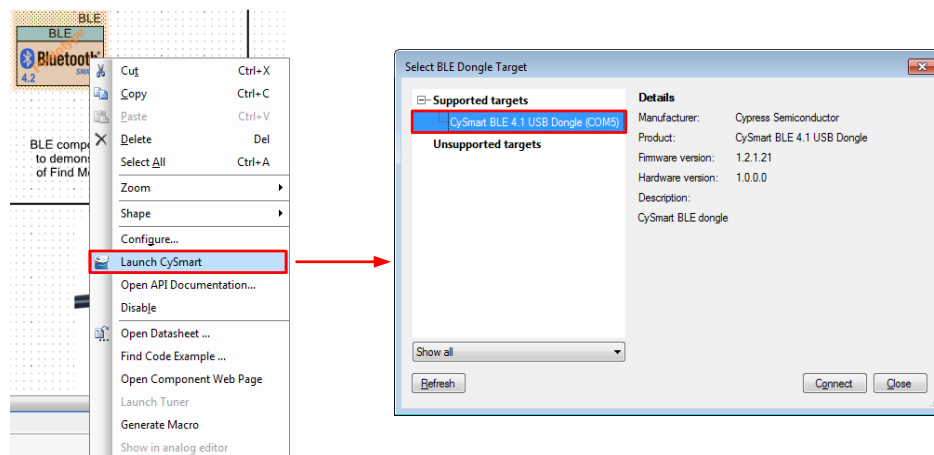
Figure 51. Download CySmart



- B. Connect the BLE dongle to your Windows personal computer. Wait for the driver installation to be completed.
- C. Launch the CySmart Host Emulation Tool.

The tool automatically detects the BLE dongle. Click **Refresh** if the BLE dongle does not appear in the **Select BLE Dongle Target** pop-up window. Click **Connect**, as shown in Figure 52.

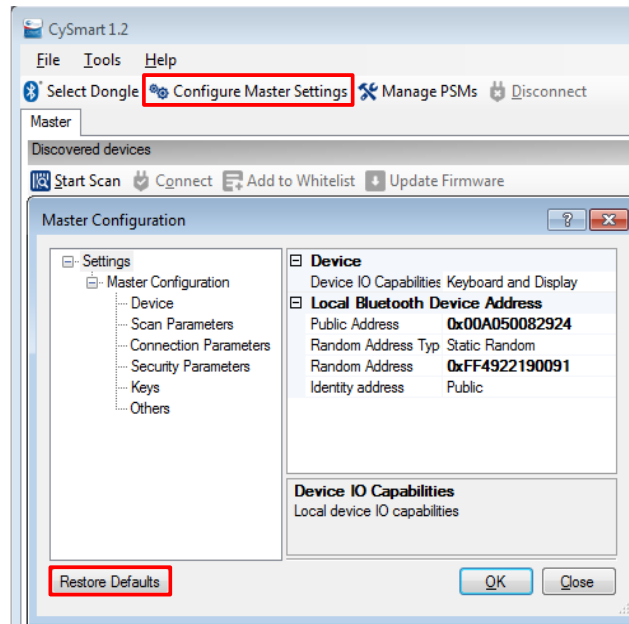
Figure 52. CySmart BLE Dongle Selection



Note: If the dongle firmware is outdated, you will be alerted. You must upgrade the firmware before you can complete this step. Follow the instructions in the window to update the dongle firmware.

- D. Click **Configure Master Settings** and then click **Restore Defaults**, as shown in Figure 53. Then, click **OK**.

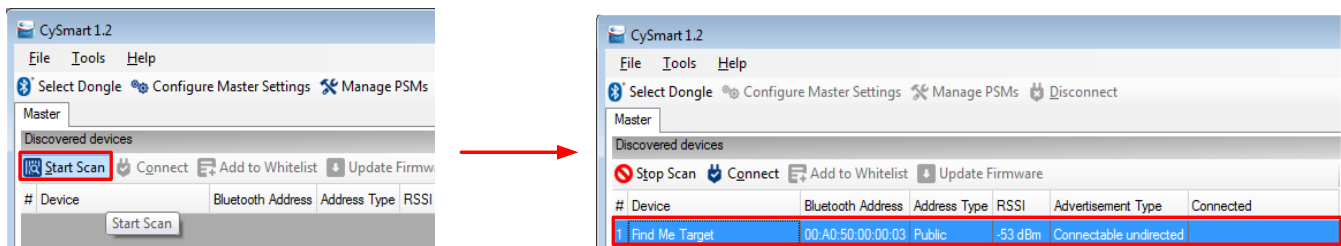
Figure 53. CySmart Master Settings Configuration



- E. Press the reset switch on the BLE Pioneer Kit to start BLE advertisements from your design. The LED turns green to indicate you are advertising.
- F. On the CySmart Host Emulation Tool, click **Start Scan**. Your device name (configured as **Find Me Target**) should appear in the **Discovered devices** list, as shown in Figure 54.

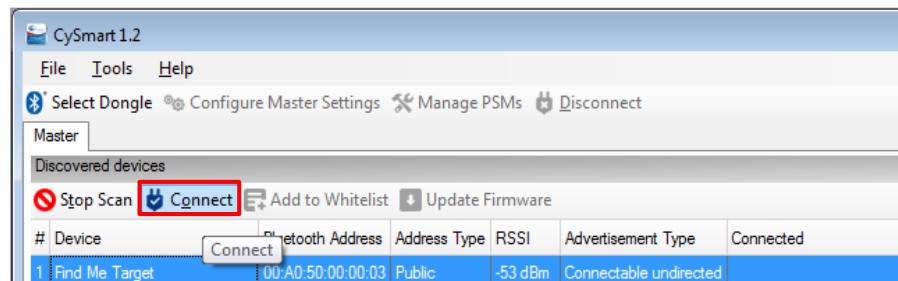
Note: if the scan process times out without finding the target, the LED turns red. Click the reset button again to resume advertising.

Figure 54. CySmart Device Discovery



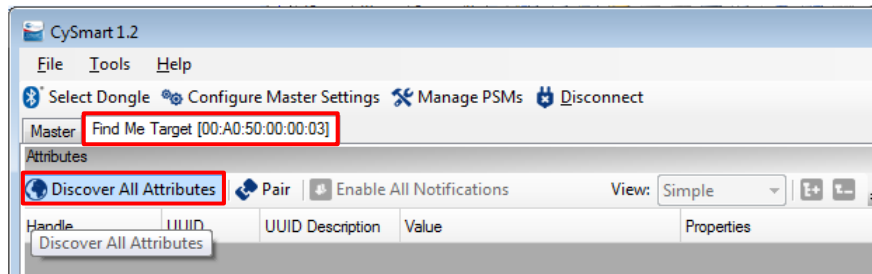
- G. Select **Find Me Target** and click **Connect** to establish a BLE connection between the CySmart Host Emulation Tool and your device, as shown in Figure 55.

Figure 55. CySmart Device Connection



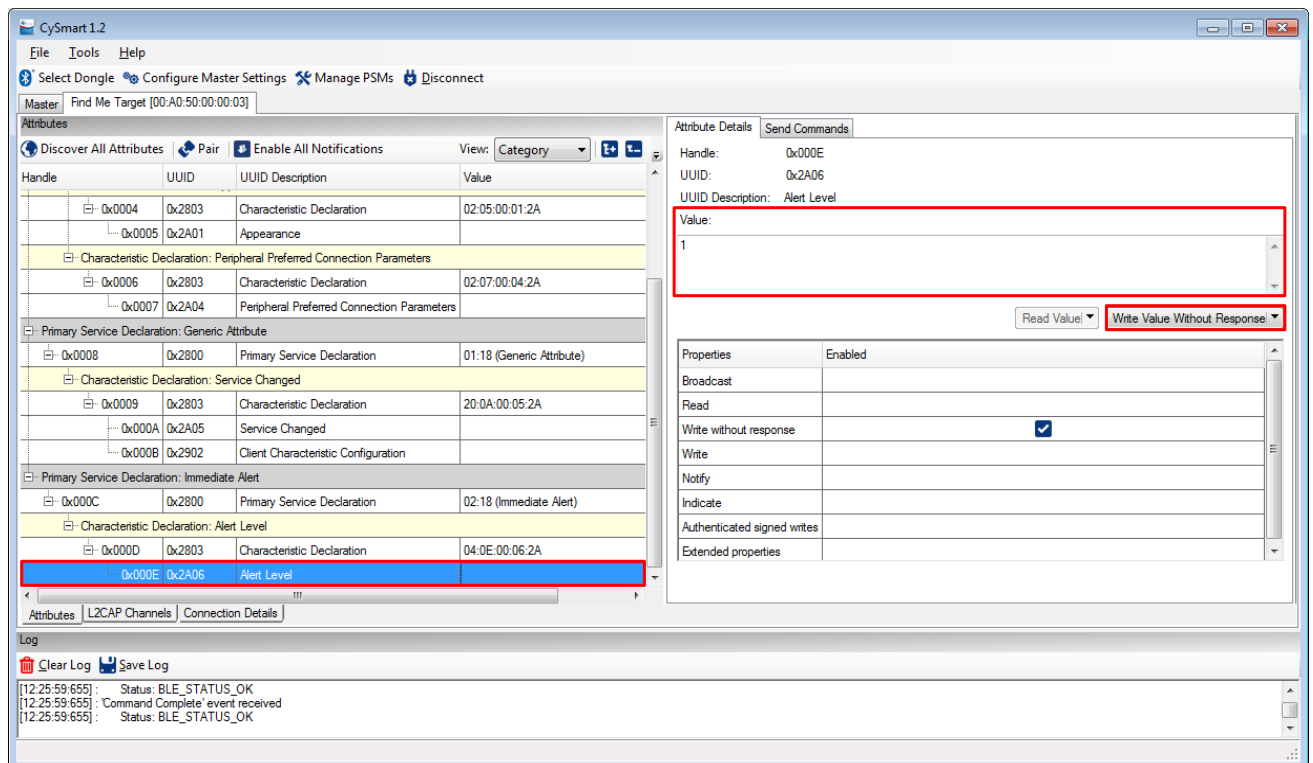
- H. Once connected, switch to the **Find Me Target** device tab and discover all the attributes on your design from the CySmart Host Emulation Tool, as shown in [Figure 56](#).

Figure 56. CySmart Attribute Discovery



- I. Scroll down the **Attributes** window and locate the **Immediate Alert** Service fields. Write a value of 0, 1, or 2 to the **Alert Level** characteristic under the **Immediate Alert** Service, as [Figure 57](#) shows. Observe the state of the LED on your device change per your Alert Level characteristic configuration.

Figure 57. Testing with CySmart Host Emulation Tool



- J. When you are finished exploring, click the Disconnect button in the CySmart application. The LED turns red to indicate you are disconnected.

You can repeat this process by pressing the reset button on the board to resume advertising.

6 Summary

This application note explored the PSoC 6 BLE device architecture and the associated development tools. PSoC 6 BLE is a truly programmable embedded system-on-chip, integrating low-power BLE radio, configurable analog and digital peripheral functions, memory, and a dual-CPU CPU system on a single chip. The integrated features and low-power modes make PSoC 6 BLE an ideal choice for battery-operated wearable, health, and fitness BLE applications.

7 Related Application Notes and Code Examples

For a complete and updated list of PSoC 6 MCU code examples, please visit our [code examples webpage](#). For more PSoC 6 MCU related documents, visit our [PSoC 6 MCU](#) product webpage.

Table 3 lists the system-level and general application notes that are recommended for the next steps in learning about PSoC 6 BLE and PSoC Creator.

Table 3. General and System-Level Application Notes, Code Examples

Document	Document Name
AN221774	Getting Started with PSoC 6 MCU
CE221773	PSoC 6 MCU Hello World Example
AN218241	PSoC 6 MCU Hardware Design Considerations
AN219434	PSoC 6 MCU Importing Generated Code into an IDE
AN219528	PSoC 6 MCU Low-Power Modes and Power Reduction Techniques

Table 4 lists the application notes and code examples (CE) for specific peripherals and applications of the device.

Table 4. Documents Related to PSoC 6 BLE Features

Document	Document Name
Bluetooth Smart	
AN91162	Creating a BLE Custom Profile
AN91445	Antenna Design and RF Layout Guidelines
AN92584	Designing for Low Power and Estimating Battery Life for BLE Applications
CE218463	Bluetooth Low Energy (BLE) Alert Notification Client/Server
CE218464	Bluetooth Low Energy (BLE) Phone Alert Client/Server
System Resources, CPU, and Interrupts	
AN215656	PSoC 6 MCU Dual-CPU System Design
AN217666	PSoC 6 MCU Interrupts
CE216795	PSoC 6 MCU Dual-CPU Basics
CE216825	PSoC 6 MCU Real-Time Clock Basics
CE218129	PSoC 6 MCU Wake up from Hibernate Using Low-Power Comparator
CE218541	PSoC 6 MCU Fault-Handling Basics
CE218542	PSoC 6 Custom Tick Timer Using RTC Alarm Interrupt
CE218552	PSoC 6 MCU UART to Memory Buffer Using DMA
CE218964	PSoC 6 MCU RTC Daily Alarm
CE219339	PSoC 6 MCU MCWDT and RTC Interrupts (Dual Core)
CE219521	PSoC 6 MCU GPIO Interrupt
CE219881	PSoC 6 MCU Switching Power Modes
CE220060	PSoC 6 MCU Watchdog Timer
CE220061	PSoC 6 MCU Multi-Counter Watchdog Interrupts
CE220120	PSoC 6 MCU Blocking Mode Flash Write
CE220169	PSoC 6 MCU Periodic Interrupt Using TCPWM

Document	Document Name
GPIO	
CE219490	PSoC 6 Breathing LED Using SMART IO
CE219506	PSoC 6 Clock Buffer Using SMART IO
CE220263	PSoC 6 MCU GPIO Pins Example
CapSense	
AN92239	Proximity Sensing with CapSense
AN85951	PSoC 4 and PSoC 6 MCU CapSense Design Guide
Bootloader	
AN213924	MCU Bootloader Software Development Kit (SDK) Guide
CE213903	PSoC 6 MCU Basic Bootloaders
Communications	
CE220541	PSoC 6 MCU SCB EzI2C
Audio	
CE218636	PSoC 6 MCU Inter-IC Sound (I2S) Example
CE219431	PSoC 6 MCU PDM-to-PCM Example
RTOS	
CE217911	PSoC 6 FreeRTOS™ Example Project
Security	
CE220465	PSoC 6 MCU Cryptography – AES Demonstration
CE220511	PSoC 6 MCU Cryptography – SHA Demonstration

Appendix A. Glossary

This section lists the most commonly used terms that you might encounter while working with Cypress' PSoC family of devices.

Component Customizer: Simple GUI in PSoC Creator that is embedded in each Component. It is used to customize the Component parameters and is accessed by right-clicking a Component.

Components: Components are used to integrate multiple ICs and system interfaces into one PSoC Component that is inherently connected to the MCU via the main system bus. For example, the BLE Component creates Bluetooth Smart products in minutes. Similarly, you can use the Programmable Analog Components for sensors.

MiniProg3: Programming hardware for development that is used to program PSoC devices on your custom board or PSoC development kits that do not support a built-in programmer.

PSoC: A programmable, embedded design platform that includes one or more CPUs, such as the 32-bit CM4, with both analog and digital programmable blocks. It accelerates embedded system design with reliable, easy-to-use solutions, such as touch sensing, and enables low-power designs.

PSoC Creator: PSoC 3, PSoC 4, PSoC 5LP, and PSoC 6 BLE IDE software that installs on your PC and allows concurrent hardware and firmware design of PSoC systems, or hardware design followed by export to other popular IDEs.

Peripheral Driver Library: The Peripheral Driver Library (PDL) simplifies software development for the PSoC 6 MCU architecture. The PDL reduces the need to understand register usage and bit structures, thus easing software development for the extensive set of peripherals available.

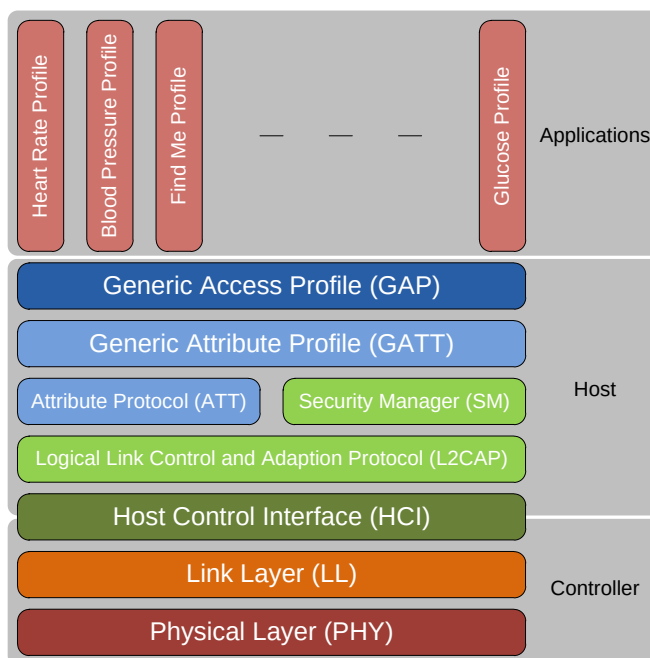
PSoC Programmer: A flexible, integrated programming application for programming PSoC devices. PSoC Programmer is integrated with PSoC Creator to program PSoC 3, PSoC 4, PRoC, PSoC 5LP, and PSoC 6 MCU designs.

Appendix B. BLE Protocol

B.1 Overview

BLE, also known as Bluetooth Smart, was introduced by the Bluetooth SIG as a low-power wireless standard operating in the 2.4-GHz ISM band. [Figure 58](#) shows the BLE protocol stack.

Figure 58. BLE Architecture



The BLE stack can be subdivided into three groups:

- **Controller:** A physical device that encodes the packet and transmits it as radio signals. On reception, the controller decodes the radio signals and reconstructs the packet.
- **Host:** A software stack consisting of various protocols and Profiles (Security Manager, Attribute Protocol, and so on) that manages how two or more devices communicate with one another.
- **Application:** A use case that uses the software stack and the controller to implement a particular functionality.

The following sections provide an overview of the multiple layers of the BLE stack, using the standard Heart Rate and Battery Service as examples. For a detailed BLE architecture description, see the Bluetooth 4.2 specification or the training videos on the [Bluetooth Developer](#) website.

B.2 Physical Layer (PHY)

The physical layer transmits or receives digital data at 1 Mbps using Gaussian frequency-shift keying (GFSK) modulation in the 2.4-GHz ISM band. The BLE physical layer divides the ISM band into 40 RF channels with a channel spacing of 2 MHz, 37 of which are data channels and 3 are advertisement channels.

B.3 Link Layer (LL)

The link layer implements key procedures to establish a reliable physical link (using an acknowledgement and flow-control-based architecture) and features that help make the BLE protocol robust and low-power. Some link layer functions include:

- Advertising, scanning, creating, and maintaining connections to establish a physical link
- 24-bit CRC and AES-128-bit encryption for robust and secure data exchange
- Establishing fast connections and low-duty-cycle advertising for low-power operation
- Adaptive Frequency Hopping (AFH), which changes the communication channel used for packet transmission so that the interference from other devices is reduced

At the link layer, two roles are defined:

- **Master:** A smartphone is an example that configures the link layer in the master configuration.
- **Slave:** A heart-rate monitor device is an example that configures the link layer in the slave configuration.

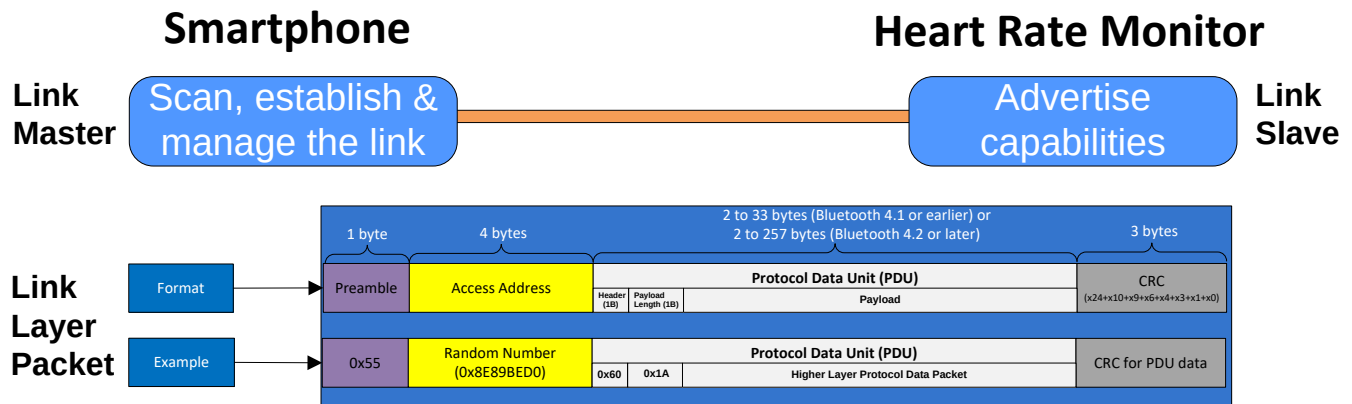
PSoC 6 BLE devices can operate in either configuration.

The link-layer slave is the one that advertises its presence to another link-layer master. A link-layer master receives the advertisement packets and can choose to connect to the slave based on the request from an application (see [Figure 59](#)). In this example implementation of a heart-rate monitor application, a heart-rate monitor device acts as the slave and sends the data to a smartphone, which acts as the master. A smartphone app then can display the reading on the smartphone.

PSoC 6 BLE devices implement the time-critical and processor-intensive parts of the link layer such as advertising, CRC, and AES encryption in hardware. Link-layer control operations such as entering the advertisement state and starting encryption are implemented in firmware.

[Figure 59](#) shows the BLE link-layer packet structure and sizes of the individual fields in the link-layer packet. The link-layer packet carries all upper layer data in its payload field. It has a 4-byte access address that is used to uniquely identify communications on a physical link, and ignore packets from a nearby BLE device operating in the same RF channel. 24-bit CRC provides data robustness.

Figure 59. BLE Link Layer Protocol



B.4 Host Control Interface (HCI)

The HCI is the standard-defined interface between the host and the controller. It allows the host and the controller to exchange information such as commands, data, and events over different physical transports such as USB or UART. The HCI requires a physical transport only when the controller and the host are different devices.

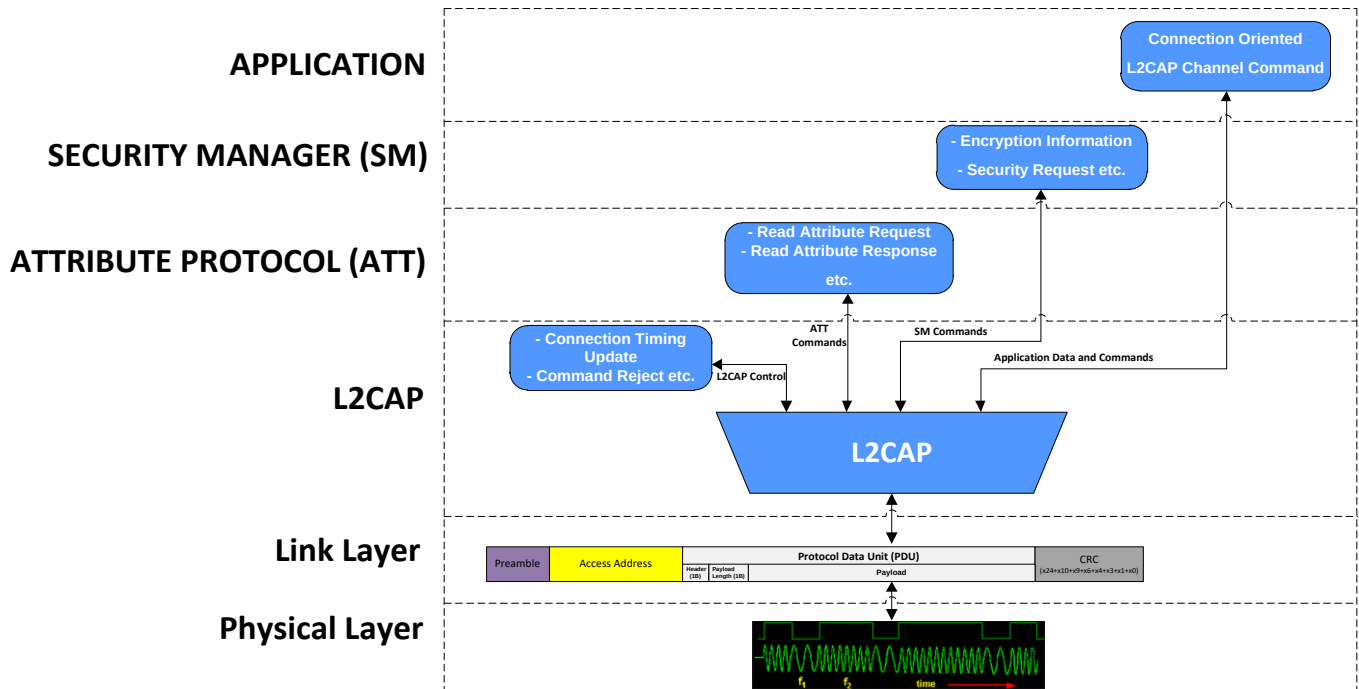
In PSoC 6 BLE devices, the HCI is just a firmware protocol layer that passes the messages and events between the controller and the host.

B.5 Logical Link Control and Adaptation Protocol (L2CAP)

L2CAP provides protocol multiplexing, segmentation, and reassembly services to upper-layer protocols. Segmentation breaks the packet received from the upper layer into smaller packets that the link layer can transmit, while reassembly combines the smaller packets received from the link layer into a meaningful packet. The L2CAP layer supports three protocol channel IDs for [Attribute Protocol \(ATT\)](#), [Security Manager \(SM\)](#), and L2CAP control, as shown in [Figure 60](#). Bluetooth 4.2 allows direct data channels through the L2CAP connection-oriented channels on top of these protocol channels.

The L2CAP and the layers above it are implemented in firmware in PSoC 6 BLE.

Figure 60. BLE L2CAP Layer



B.6 Security Manager (SM)

The SM layer defines the methods used for pairing, encryption, and key distribution.

- **Pairing** is the process to enable security features. In this process, two devices are authenticated, the link is encrypted, and then the encryption keys are exchanged. This enables the secure exchange of data over the BLE interface without being snooped on by a silent listener on the RF channel.
- **Bonding** is the process in which the keys and the identity information exchanged during the pairing process are saved. After devices are bonded, they do not have to go through the pairing process again when reconnected.

BLE uses 128-bit [AES](#) for data encryption.

B.7 Attribute Protocol (ATT)

There are two GATT roles in BLE that you should know to understand the ATT and GATT layers:

- **GATT Server**: A GATT Server contains the data or information. It receives requests from a GATT Client and responds with data. For example, a heart-rate monitor GATT Server contains heart-rate information; a BLE HID keyboard GATT Server contains user key press information.
- **GATT Client**: A GATT Client requests and/or receives data from a GATT Server. For example, a smartphone is a GATT Client that receives heart-rate information from the heart-rate GATT Server; a laptop is a GATT Client that receives key-press information from a BLE keyboard.

ATT forms the basis of BLE communication. This protocol enables the GATT Client to find and access data or attributes on the GATT Server. For more details about the GATT Client and Server architecture, see [Generic Attribute Profile \(GATT\)](#).

An attribute is the fundamental data container in the ATT/GATT layer, which consists of the following:

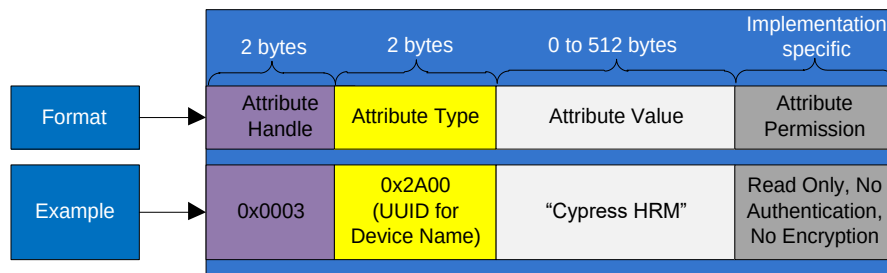
- **Attribute Handle:** The 16-bit address used to address and access an attribute.
- **Attribute Type:** This specifies the type of data stored in an attribute. It is represented by a 16-bit UUID defined by the Bluetooth SIG.

For example, the 16-bit UUID of the Heart-Rate Service is 0x180D; the UUID for the Device Name Attribute is 0x2A00. Visit the Bluetooth [webpage](#) for a list of 16-bit UUIDs assigned by the SIG.

- **Attribute Value:** This is the actual data stored in the attribute.
- **Attribute Permission:** This specifies the attribute access, authentication, and authorization requirements. Attribute permission is set by the higher layer specification and is not discoverable through the Attribute protocol.

Figure 61 shows the structure of a Device Name Attribute as an example.

Figure 61. Attribute Format Example



B.7.1 Attribute Hierarchy

Attributes are the building blocks for representing data in ATT/GATT. Attributes can be broadly classified into the following two groups to provide hierarchy and abstraction of data:

- **Characteristic:** A collection of attributes that exposes the system information or meaningful data. A Characteristic consists of the following attributes:
 - Characteristic Declaration Attribute: This defines the beginning of a Characteristic.
 - Characteristic Value Attribute: This holds the actual data.
 - Characteristic Descriptor Attributes: These are optional attributes, which provide additional information about the characteristic value.

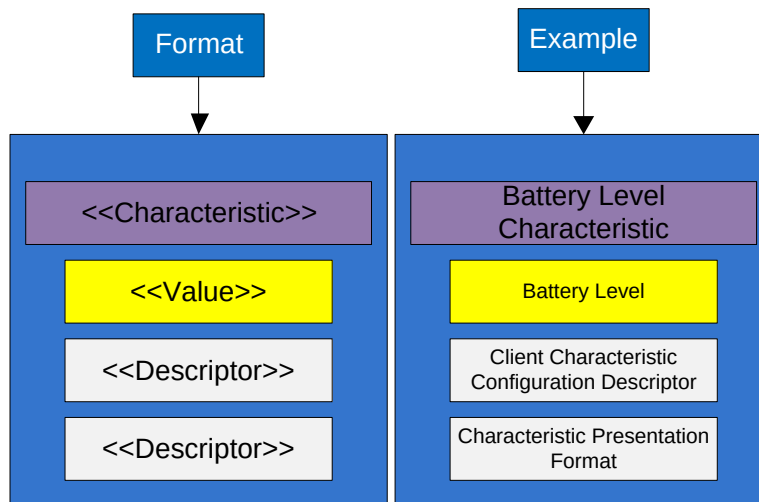
"Battery Level" is an example of a characteristic in the Battery Service (BAS). Representing the battery level in percentage values is an example of a characteristic descriptor.

Figure 62 shows the structure of a characteristic with Battery Level as an example.

- The first part of a characteristic is the declaration of the characteristic (it marks the beginning of a characteristic) indicated by the Battery Level Characteristic in [Figure 62](#).
- Next is the actual characteristic value or the real data, which in the case of the Battery Level Characteristic is the current battery level. The battery level is expressed as a percentage of full scale, for example "65," "90," and so on.
- Characteristic descriptors provide additional information that is required to make sense of the characteristic value. For example, the Characteristic Presentation Format Descriptor for Battery Level indicates that the battery level is expressed as a percentage. Therefore, when "90" is read, the GATT Client knows this is 90 percent and not 90 mV or 90 mAh. Similarly, the Valid Range Characteristic descriptor (not shown in [Figure 62](#)) indicates that the battery level range is between 0 and 100 percent.
- A Client Characteristic Configuration Descriptor (CCCD) is another commonly used Characteristic descriptor that allows a GATT Client to configure the behavior of a Characteristic on the GATT Server. When the GATT Client writes a value of 0x01 to the CCCD of a Characteristic, it enables asynchronous notifications (described

in the next section) to be sent from the GATT Server. In the case of a Battery Level Characteristic, writing 0x01 to the Battery Level CCCD enables the Battery Service to notify its battery level periodically or on any change in battery-level value.

Figure 62. Characteristic Format and Example

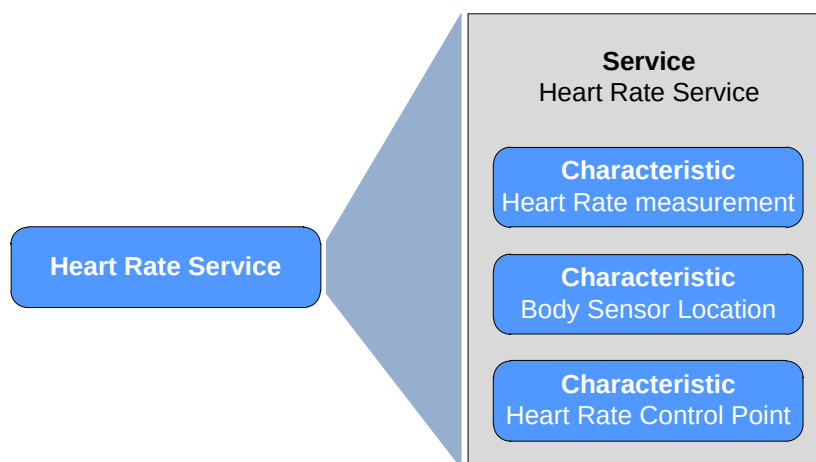


- **Service:** The type of attribute that defines a function performed by the GATT Server. A service is a collection of characteristics and can include other services. The concept of a service is used to establish the grouping of relative data and provide a data hierarchy. See [Figure 63](#) for an example of a Heart Rate Service (HRS).

A service can be of two types: A primary service or a secondary service. A primary service exposes the main functionality of the device, while the secondary service provides additional functionality. For example, in a heart-rate monitoring device, the HRS is a primary service and BAS is a secondary service.

A service can also include other services that are present on the GATT Server. The entire included services become part of the new service.

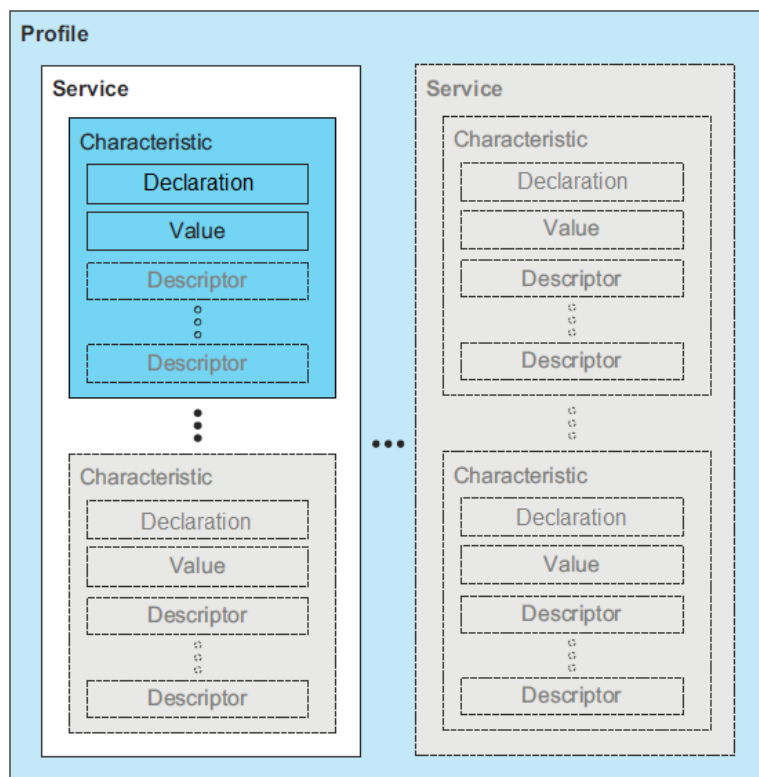
Figure 63. BLE Heart Rate Service Example



The word “Profile” in BLE is a collection of services and their behavior that together perform a particular end application. A Heart Rate Profile (HRP) is an example of a BLE Profile that defines all the required services for creating a heart-rate monitoring device. See the [Generic Access Profile \(GAP\)](#) section for details.

[Figure 64](#) shows the data hierarchy using attributes, characteristics, services, and profiles defined previously in this section.

Figure 64. BLE Data Hierarchy*



* Image courtesy of Bluetooth SIG

B.7.2 Attribute Operations

Attributes defined in the previous section are accessed using the following five basic methods:

- **Read Request:** The GATT Client sends this request to the GATT Server to read an attribute value. For every request, the GATT Server sends a response to the GATT Client. A smartphone reading the Battery-Level Characteristic of a heart-rate monitor device (see [Figure 62](#)) is an example of a Read Request.
- **Write Request:** The GATT Client sends this request to the GATT Server to write an attribute value. The GATT Server responds to the GATT Client, indicating whether the value was written. A smartphone writing a value of 0x01 to the CCCD of a Battery Level characteristic to enable notifications is an example of a Write Request.
- **Write Command:** The GATT Client sends this command to the GATT Server to write an attribute value. The GATT Server does not send any response to this command. For example, the BLE Immediate Alert Service (IAS) uses a Write Command to trigger an alert (turn on an LED, ring a buzzer, drive a vibration motor, and so on) on an IAS Target device (for example, a BLE key fob) from an IAS locator (for example, a smartphone).
- **Notification:** The GATT Server sends this to the GATT Client to notify it of a new value for an attribute. The GATT Client does not send any confirmation for a notification. For example, a heart-rate monitor device sends heart-rate measurement notifications to a smartphone when its CCCD is written with a value of 0x01.
- **Indication:** The GATT Server sends this type of message. The GATT Client always confirms it. For example, a BLE Health Thermometer Service (HTS) uses indications to reliably send the measured temperature value to a health thermometer collector, such as a smartphone.

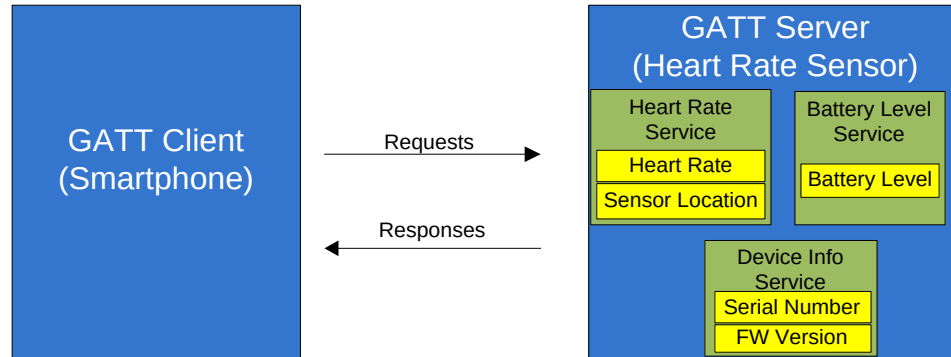
B.8 Generic Attribute Profile (GATT)

The GATT defines the ways in which attributes can be found and used. The GATT operates in one of two roles:

- **GATT Client:** The device that requests the data (for example, a smartphone).
- **GATT Server:** The device that provides the data (for example, a heart-rate monitor)

Figure 65 shows the client-server architecture in the GATT layer using a heart-rate monitoring device as an example. The heart-rate monitoring device exposes multiple services (HRS, BAS, and Device Information Service); each service consists of one or more characteristics with a characteristic value and descriptor, as shown in Figure 62.

Figure 65. GATT Client-Server Architecture



After the BLE connection is established at the link-layer level, the GATT Client (which initially knows nothing about the connected BLE device) initiates a process called “service discovery.” As part of the service discovery, the GATT Client sends multiple requests to the GATT Server to get a list of all the available services, characteristics, and attributes in the GATT Server. When service discovery is complete, the GATT Client has the required information to modify or read the information exposed by the GATT Server using the attribute operations described in the previous section.

B.9 Generic Access Profile (GAP)

The GAP layer provides device-specific information such as the device address; device name; and the methods of discovery, connection, and bonding. The Profile defines how a device can be discovered, connected, the list of services available, and how the services can be used. Figure 67 shows an example of a Heart Rate Profile.

The GAP layer operates in one of four roles:

- **Peripheral:** This is an advertising role that enables the device to connect with a GAP Central. After a connection is established with the Central, the device operates as a slave. For example, a heart-rate sensor reporting the measured heart-rate to a remote device operates as a GAP Peripheral.
- **Central:** This is the GAP role that scans for advertisements and initiates connections with Peripherals. This GAP role operates as the master after establishing connections with Peripherals. For example, a smartphone retrieving heart-rate measurement data from a Peripheral (heart-rate sensor) operates as a GAP Central.
- **Broadcaster:** This is an advertising role that is used to broadcast data. It cannot form BLE connections and engage in data exchange (no request/response operations). This role works similar to a radio station in that it sends data continuously whether or not anyone is listening; it is a one-way data communication. A typical example of a GAP Broadcaster is a beacon, which continuously broadcasts information but does not expect any response.
- **Observer:** This is a listening role that scans for advertisements but does not connect to the advertising device. It is the opposite of the Broadcaster role. It works similar to a radio receiver that can continuously listen for information but cannot communicate with the information source. A typical example of a GAP Observer is a smartphone app that continuously listens for beacons.

Figure 66 shows a generic BLE system with Cypress' BLE Pioneer Kit as the Peripheral and a smartphone as the Central device. The interaction between BLE protocol layers and their roles on the Central and the Peripheral devices are also shown.

Figure 66. BLE System Design

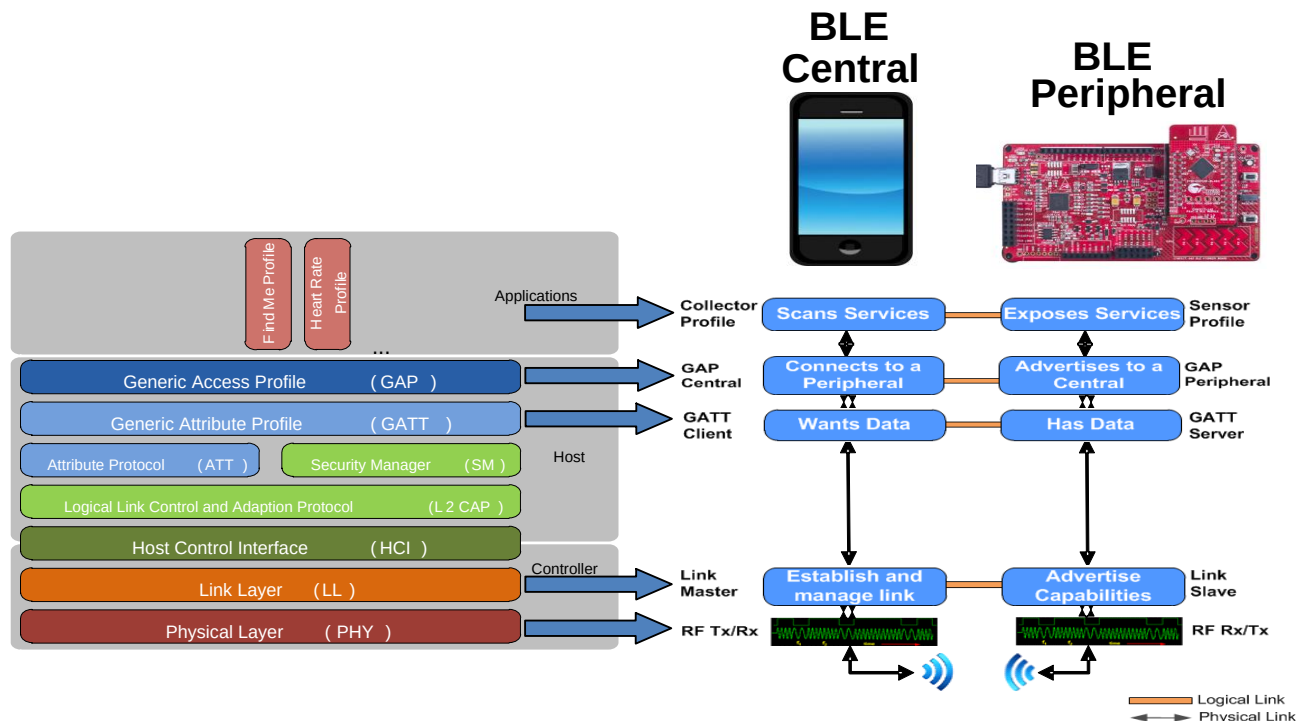
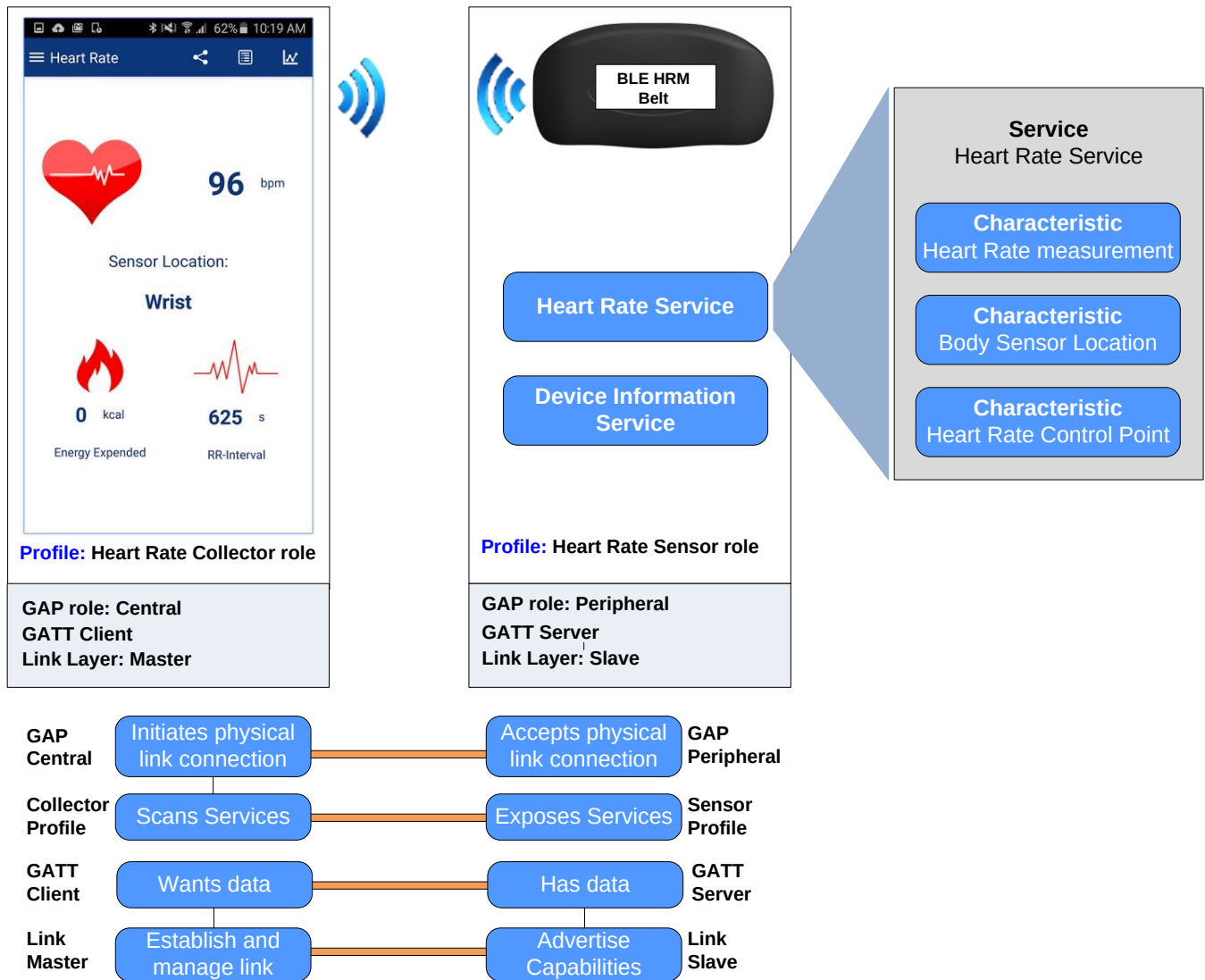


Figure 67 shows an example where a smartphone with a heart-rate app operates as a Central and a heart-rate sensor operates as a Peripheral. The heart-rate monitoring device implements the Heart-Rate Sensor Profile, while the smartphone receiving the data implements the Heart-Rate Collector Profile.

In this example, the Heart-Rate Sensor Profile implements two standard services. The first is a Heart Rate Service that comprises three characteristics (the Heart Rate Measurement Characteristic, the Body Sensor Location Characteristic, and the Heart Rate Control Point Characteristic). The second service is a Device Information Service. At the link layer, the heart-rate measurement device is the slave and the smartphone is the master. See the Bluetooth developer portal for a detailed description of the Heart Rate [Service](#) and [Profile](#).

Figure 67. BLE Heart-Rate Monitor System



Appendix C. Device Features

C.1 System Wide Resources

C.1.1 CPU Subsystem: CM4 and CM0

The CPU subsystem in PSoC 6 BLE consists of two Cortex cores: CM4 with a single-precision floating-point unit capable of operating at a maximum frequency of 150 MHz; CM0+ capable of operating at a maximum frequency of 100 MHz. There is a memory protection unit (MPU) available in both the cores. Additionally, there are protection units attached to peripherals called Peripheral Protection Unit (PPUs) and Shared Memory Protection Units (SMPUs) for shared memory regions.

The CM0+ also provides a secure boot function. This allows system integrity to be checked and privileges enforced prior to the execution of the user application.

C.1.2 IPC

Inter-processor communication (IPC) provides the functionality for the two cores to communicate and synchronize their activities. IPC hardware is implemented using register structures in PSoC 6 BLE. These register structures are used to synchronize events, and trigger “notify” or “release” events of an IPC channel. PSoC 6 BLE supports up to 16 channels, which allows message passing between CPU cores and supports locks for mutual exclusion.

C.1.3 Memory System

The CPU cores have a fixed memory address map that enables shared access to memory and peripherals. Code can be executed from both the flash and RAM on both cores.

The PSoC 6 BLE family has up to 1 MB of flash memory and an additional 32 KB of flash that can be used for EEPROM emulation. There is also an additional 32 KB of supervisory flash. In addition, the flash supports Read-While-Write (RWW) operation so that the flash can be written to when the CPU is actively executing instructions. There is also a 128-KB ROM that contains boot and configuration routines. This will ensure Secure Boot operation if authentication of user flash is required for end applications.

PSoC 6 BLE has up to 288 KB of SRAM memory, which can be fully retained or retained in increments of user-designated 32-KB blocks.

C.1.4 DMA

The CPU subsystem includes two independent DMA controllers, each capable of running 32 channels. The controllers support independent accesses to the peripherals using the Arm standard Advanced Microcontroller Bus Architecture (AMBA) High-Performance Bus (AHB).

The DMA transfers data to and from memory, peripherals, and registers. These transfers occur independent of the CPU. The DMA channels support the following:

- 8-bit, 16-bit, and 32-bit data widths at both source and destination
- Four priority levels on each channel
- Configurable interrupts on each DMA descriptor
- Descriptor chaining

C.1.5 Clocking System

PSoC 6 BLE has the following clock sources:

- **Internal main oscillator (IMO):** The IMO is the primary source of internal clocking in PSoC 6 BLE. The CPU and all high-speed peripherals can operate from the IMO or an external crystal oscillator (ECO). PSoC 6 BLE has multiple peripheral clock dividers operating from either the IMO or the ECO, which generate clocks for high-speed peripherals. The IMO can generate an 8 MHz clock with an accuracy of ± 1 percent and is available only in Active mode.
- **External crystal oscillator (ECO):** The PSoC 6 MCU device contains an oscillator to drive an external 4-MHz to 33.33-MHz crystal for an accurate clock source.

In addition, the external crystal oscillator on the BLE subsystem with a built-in tunable crystal load capacitance is used to generate a highly accurate 32-MHz clock. It is primarily used to clock the BLE subsystem that generates the RF clocks. The high-accuracy ECO clock can also be used as a clock source for the PSoC 6 BLE device's high-frequency clock (CLK_HF) and is designated as the AltHF clock.

- **External clock (EXTCLK):** The external clock is a megahertz-range clock that can be sourced from a signal on a designated I/O pin. This clock can be used as the source clock for either the PLL or FLL, or it can be used directly by the high-frequency clocks.
- **Internal low-speed oscillator (ILO):** The ILO is a very-low-power 32-kHz oscillator, which primarily generates clocks for low-speed peripherals operating in all power modes.
- **Precision internal low-speed oscillator (PILO):** PILO is an additional source that can provide a more accurate 32.768-kHz clock than ILO. PILO works in Deep Sleep and higher modes.
- **Watch crystal oscillator (WCO):** The 32.768-kHz WCO is used as one of the sources for low frequency clock tree (CLK_LF) along with ILO/PILO. WCO is used to accurately maintain the time interval for BLE advertising and connection events. Similar to ILO, WCO is also available in all modes except the Hibernate and Stop modes.

The PSoC BLE clock generation system has phase-locked loop (PLL) and frequency-locked loop (FLL) blocks that can be used to generate high-frequency clocks (CLK_HF). These high-frequency clocks in turn drive the CPU core clocks and the peripheral clock dividers.

PSoC 6 BLE has five high-frequency root clocks (CLK_HF[0-4]). Each CLK_HF has a destination on the device such as peripherals like serial memory interface.

PSoC 6 BLE has clock supervisors on high-frequency clock path 0 (CLK_HF[0]) and WCO to detect if the clock has been stopped and can trigger an interrupt or a system reset or both.

C.1.6 System Interrupts

PSoC 6 BLE supports interrupts and exceptions on both the CPU cores: CM4 and CM0+. The cores provide their own vector table for handling interrupts/exceptions. PSoC 6 BLE can support up to 139 interrupts on CM4 and 32 interrupts on CM0+. Up to 33 interrupts can wake the device from Deep Sleep power mode.

C.1.7 Power Supply and Monitoring

The PSoC 6 BLE device family supports an operating voltage of 1.71 V to 3.6 V. It integrates a single-input multiple-output (SIMO) buck converter to power the blocks within the device. The core operating voltage is user selectable between 0.9 V and 1.1 V. The device family supports multiple power supply rails – V_{DD} , V_{DDA} , V_{DDIO} , and V_{BACKUP} . Additionally, there are power supply rails for BLE radio operation – V_{DDR} . The availability of various supply rails/pins for an application will depend on the device package selected.

The device includes a V_{BACKUP} supply pin to power a small set of peripherals such as RTC and WCO. This rail is independent of all other rails and can exist even when other rails are absent. Because the power supply to these blocks comes from a dedicated V_{BACKUP} pin, these blocks continue to operate even when the device power is disconnected or held in reset. The RTC present in the backup domain provides an option to wake up the device from any power modes.

The PSoC 6 BLE family supports power-on reset (POR), brownout detection (BOD), overvoltage protection (OVP), and low-voltage detection (LVD) circuits for power supply monitoring and to implement fail-safe recovery.

For more information on the power supplies in PSoC 6 BLE, see the [PSoC 6 MCU: PSoC 63 with BLE Architecture Technical Reference Manual](#).

C.1.8 Power Modes

The power modes supported by PSoC 6 BLE, in the order of decreasing power consumption, are:

- **Active mode:** This is the primary mode of operation. In this mode, all peripherals are active and are available
- **Low-Power Active mode:** This mode is akin to the Active mode with most peripherals operating with limited capability; CPU cores are available. The performance tradeoffs include reduced operating clock frequency, high-frequency clock sources limited in frequency, and lower core operating voltage.
- **Sleep mode:** In this mode, the CPU cores are in Sleep mode, SRAM is in retention, and all peripherals are available. Any interrupt wakes up either of the CPUs and returns the system to Active mode. CM4 and CM0+ both support their own CPU Sleep modes, and each CPU can be in Sleep independent of the state of the other CPU. The device is said to be in Sleep mode when both the cores are in CPU sleep.
- **Low-Power Sleep mode:** Most peripherals operate with limited capability; CPU cores are not available.
- **Deep Sleep mode:** In Deep Sleep mode, all high-speed clock sources are turned OFF. This in turn makes high-speed peripherals unusable in Deep Sleep. Peripherals that operate on low-frequency clocks only are available.
- **Hibernate mode:** Device and GPIO states are frozen, and the device resets on wakeup.

You can use a combination of Sleep, Deep Sleep, and Hibernate modes in a battery-operated BLE system to achieve best-in-class system power with longer battery life. Table 5 shows the dependency between PSoC 6 BLE system power modes and BLESS power modes. A check mark in a cell of Table 5 indicates that the BLESS can perform the specified task when the system is in a given power mode. For example, BLESS can be in Deep Sleep mode while the system is in Low-Power Active mode. The retention label indicates that the BLESS operating context is retained when the system switches to Deep Sleep mode.

Table 5. PSoC 6 BLE Power Modes

BLESS Modes	PSoC 6 BLE System Power Modes					
	Active	Low-Power Active	Sleep	Low-Power Sleep	Deep Sleep	Hibernate
Transmit	✓	✓	✓	✓	retention	OFF
Receive	✓	✓	✓	✓	retention	OFF
Idle	✓	✓	✓	✓	retention	OFF
Deep Sleep	✓	✓	✓	✓	retention	OFF

C.2 Secure Boot

Secure booting involves authenticating the application flash images using a key-based security protocol defined by a market/application-specific standard. The secure boot process is implemented in SROM and a separate supervisory flash in the PSoC 6 BLE device. The boot code computes a checksum of the boot code and compares it to a value in eFuse. If these values do not match, the boot process fails. The boot code also enforces debug access restrictions as specified in eFuse. Secure boot is an optional feature and needs to be enabled by the end-user.

C.3 Programmable Digital Peripherals

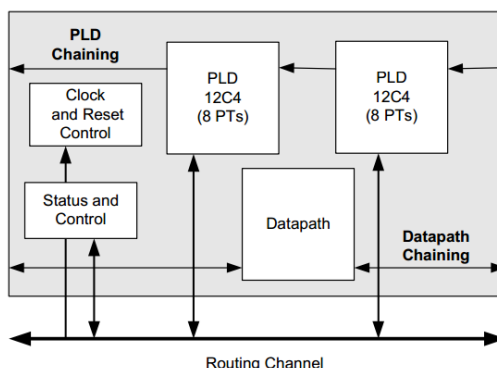
C.3.1 UDB

UDBs are programmable logic blocks that provide functionalities similar to CPLD and FPGA blocks, as Figure 68 shows. UDBs allow you to create a variety of digital functions such as timer, counter, PWM, pseudo random sequence (PRS), CRC, shift register, SPI, UART, I²S, and custom combinational and sequential logic circuits.

Each UDB has two programmable logic devices (PLDs), each with 12 inputs and 8 product terms. PLDs can form registered or combinational sum-of-products logic. Additionally, an 8-bit single-cycle arithmetic logic unit (ALU), known as a “datapath,” is present in each UDB. The datapath helps with the efficient implementation of functions such as timer, counter, PWM, and CRC.

UDBs also provide a switched digital signal interconnect (DSI) fabric that allows signals from peripherals and ports to be routed to and through the UDBs for communication and control.

Figure 68. Universal Digital Block Diagram



You do not necessarily need to know any hardware description language (HDL) to use UDBs. PSoC Creator, Cypress’ development tool for PSoC 6 BLE, can generate the required function for you from a schematic. If required, advanced users can implement custom logic on UDBs using Verilog.

PSoC 6 BLE has up to 12 UDBs. For more information on UDBs, see the following application notes:

- [AN62510 – Implementing State Machines with PSoC 3, PSoC 4, and PSoC 5LP](#)
- [AN82156 – PSoC 3, PSoC 4, and PSoC 5LP – Designing PSoC Creator Components with UDB Datapaths](#)
- [AN82250 – PSoC 3, PSoC 4, and PSoC 5LP – Implementing Programmable Logic Designs with Verilog](#)

C.3.2 Programmable TCPWM

PSoC 6 BLE has 32 programmable TCPWM blocks. Each TCPWM can implement a timer, counter, PWM, or quadrature decoder. TCPWMs provide dead band programmable complementary PWM outputs and selectable start, reload, stop, count, and capture event signals. The PWM mode supports center-aligned, edge, and pseudorandom operations. It also has a Kill input to force outputs to a predetermined state.

For more information, refer to the PSoC 6 BLE TCPWM Component datasheet.

C.3.3 SCB

PSoC 6 BLE has up to nine independent run-time programmable SCBs with I²C, SPI, or UART. The SCB supports the following features:

- Standard SPI master and slave functionality with Motorola®, Texas Instruments® Secure Simple Pairing (SSP), and National Semiconductor® Microwire protocols
- Standard UART functionality (up to 1-Mbps baud rate) with smart-card reader, single-wire local interconnect network (LIN) interface, SmartCard (ISO7816), and Infrared Data Association (IrDA) protocols
- Standard I2C master and slave functionality with operating speeds up to 1 Mbps
- EzSPI and EzI2C mode, which allows operation without CPU intervention
- One SCB can be configured to operate in Deep Sleep mode with an external clock. The low-power (Deep Sleep) mode of operation is supported on the SPI and I2C protocols (using an external clock) in slave mode only.

For more information, see the PSoC 6 BLE SCB Component datasheet.

C.3.4 BLESS

PSoC 6 BLE incorporates a Bluetooth Smart subsystem that implements the BLE link layer and physical layer as specified in the Bluetooth 4.2 specification. The BLE subsystem contains the physical layer (PHY) and link layer engine with an embedded AES-128 security engine. The subsystem supports all Bluetooth SIG-adopted BLE profiles.

The physical layer consists of a digital PHY and RF transceiver compliant with the Bluetooth 4.2 specification. The transceiver transmits and receives GFSK packets at 1 Mbps over the 2.4-GHz ISM band. The baseband controller is a composite hardware/firmware implementation that supports both master and slave modes. The key protocol elements such as HCI and link control are implemented in firmware, while time-critical functions such as encryption, CRC, data whitening, and access code correlation are implemented in hardware.

The BLESS is Bluetooth 4.2 compliant with support for all the features of the Bluetooth 4.0 specification and some additional features of the Bluetooth 4.2 specification such as low-duty-cycle advertising, LE ping, L2CAP connection-oriented channels, link layer privacy, link layer data length extension, and LE secure connection. The BLESS block also contains an ECO and WCO that are required for generating an accurate RF frequency and keeping the time between successive connection intervals on the BLE link respectively.

The BLE subsystem supports up to four simultaneous connections. It supports its own four functional power modes: Deep Sleep, Idle, Transmit, and Receive.

Note: The power modes discussed in this section are specific to the BLESS block. For PSoC 6 BLE system power modes, see the section [Power Modes](#).

C.3.4.1 Deep Sleep Mode

Deep Sleep mode is the lowest power functional mode supported by the BLESS. In this mode, the radio is off. This mode is entered for maximum power saving during an advertising or connection interval after the packet transmission and reception is complete. The ECO can be turned off in this mode for power saving; the WCO, which is the low-frequency clock, is on for maintaining the BLE link layer timing reference logic. The application firmware controls the entry to and exit from this state.

C.3.4.2 Sleep Mode

In Sleep mode, the radio is off. The block maintains all the configurations. The ECO and WCO are turned on, but the clock to the core BLESS logic is turned off. The application firmware controls the entry to and exit from this state.

C.3.4.3 Idle Mode

The Idle mode is the preparation state for the transmit and receive states. In this state, the radio is turned off, but the link layer clock is enabled for the link layer logic so that the CPU starts the protocol state machines.

C.3.4.4 Transmit Mode

Transmit mode is the active functional mode; all the blocks within BLESS are powered on. The link layer clock is enabled to complete the logic within the link layer and RF-PHY. In this mode, RF-PHY gets up to 2 Mbps of serial data from the link layer and transmits the 2.4-GHz GFSK-modulated data to the antenna port. BLESS enters Transmit mode from Idle mode.

C.3.4.5 Receive Mode

This mode enables the BLESS to move into the receive state to perform BLE-specific receiver operations. RF-PHY translates the 1-Mbps data received from the RF analog block and forwards it to the link layer controller after demodulation. A summary of the BLESS power modes and operational sub-blocks is given in [Table 6](#).

Table 6. BLESS Power Modes

BLESS Power Mode	ECO	WCO	RF Tx	RF Rx	BLESS Core
Deep Sleep	OFF	ON	OFF	OFF	OFF
Sleep	ON	ON	OFF	OFF	OFF
Idle	ON	ON	OFF	OFF	ON
Transmit	ON	ON	ON	OFF	ON
Receive	ON	ON	OFF	ON	ON

C.3.5 Audio Subsystem

PSoC 6 BLE has an audio subsystem that consists of an I²S block and two PDM channels. The PDM channels interface to a digital microphone's bit-stream output. The PDM processing channel provides droop correction and can operate with clock speeds ranging from 384 kHz to 3.072 MHz and produce word lengths of 16 to 24 bits at audio sample rates of up to 48 ksps.

The I²S interface supports both master and slave modes with word clock rates of up to 192 ksps when 8-bit to 32-bit words are transmitted.

C.3.6 Serial Memory Interface

The Serial Memory Interface (SMIF) on PSoC 6 BLE is capable of interfacing with different types of memories and up to four memories. SMIF supports Octal-SPI (8 bits/cycle throughput), Dual Quad-SPI (8 bits/cycle throughput), Quad-SPI (4 bits/cycle throughput), Dual-SPI (2 bits/cycle throughput), and SPI (1 bit/cycle throughput). The block also supports execute-in-place (XIP) mode where the CPU cores can execute code directly from external memory. The SMIF block along with software modules developed in PSoC Creator enable you to use a qualified predetermined set of memory devices in your applications.

C.3.7 eFUSE

eFuse is a one-time programmable that is be used to program security-related settings. It can also be used to store your application settings that are programmed once and used later.

C.3.8 Segment LCD

PSoC 6 BLE has a segment LCD drive with the following features:

- Supports up to 8 common (COM) and 64 segment (SEG) electrodes
- Programmable GPIOs provide flexible selection of COM and SEG electrodes.
- Supports 14-segment and 16-segment alphanumeric display, 7-segment numeric display, dot matrix, and special symbols
- Two drive modes: digital correlation and PWM
- Operates in all system power modes except Hibernate
- Can drive a 3-volt display from 1.8-volt VDD
- Digital contrast control

Note: The number of commons and segments supported by a PSoC 6 BLE device varies based on the device family and device package. See the respective device datasheet for details.

C.4 Programmable Analog Peripherals

C.4.1 Continuous Time Block Opamps

PSoC 6 BLE devices have a pair of Continuous Time Block (CTBm) based opamps that have their inputs and outputs connected to fixed location pins. The opamps support all power modes except Hibernate. However, the opamps operate with reduced gain bandwidth product in Deep Sleep mode. The outputs of these opamps in typical usage can be used as buffers for the SAR inputs.

C.4.2 Low-Power Comparator

PSoC 6 BLE devices have a pair of low-power comparators that can also operate in Deep Sleep and Hibernate modes. The comparators consume less than 300 nA of current in low-power modes. In a power-sensitive design, when the device goes into low-power modes, you can use the low-power comparator to monitor analog inputs and generate an interrupt that can wake up the system.

For more information, refer to the PSoC 6 BLE Low-Power Comparator Component datasheet.

C.4.3 SAR ADC

PSoC 6 BLE has a 12-bit, 1-Msps successive approximation register (SAR) ADC with input channels that support programmable resolution and single-ended or differential input options. The number of GPIOs limits the number of ADC input channels that can be implemented. The SAR ADC does not operate in Deep Sleep and Hibernate modes as it requires a high-speed clock.

The SAR ADC has a hardware sequencer that can perform an automatic scan on as many as eight channels without CPU intervention. The SAR ADC can be connected to a fixed set of pins through an 8-input sequencer. The sequencer cycles through the selected channels autonomously (sequencer scan) and does so with zero switching overhead. It also supports preprocessing operations such as accumulation and averaging of the output data on these eight channels.

You can trigger a scan with a variety of methods, such as firmware, timer, pin, or UDB, giving you additional design flexibility.

To improve the performance in noisy conditions, it is possible to provide an external bypass on a fixed location pin for the internal reference amplifier. For more information on the SAR ADC, see the PSoC 6 BLE SAR ADC Component datasheet.

PSoC 6 BLE has an on-chip temperature sensor that can be used to measure temperature. The temperature sensor can be connected to the SAR ADC, which digitizes the reading and produces a temperature value by using Cypress-supplied software Component that includes calibration and linearization.

C.4.4 DAC

PSoC 6 BLE has a 12-bit voltage mode continuous time DAC (CTDAC), which has a settling time of 2 μ s. The 12-bit DAC provides continuous time output without the need for an external sample and hold (S/H) circuit. The DAC control interface provides an option to control the DAC output through the CPU and DMA. This includes a double-buffered DAC voltage control register, clock input for programmable update rate, interrupt on DAC buffer empty to CPU, and trigger to DMA. The DAC may hence be driven by the DMA controllers to generate user-defined waveforms.

For more information on the DAC, see the PSoC 6 BLE DAC Component datasheet.

C.4.5 CapSense

The fourth-generation CapSense in the PSoC 6 BLE device supports self-capacitance and mutual capacitance based touch sensing. CapSense is supported on all pins.

Capacitive touch sensors use human-body capacitance to detect the presence of a finger on or near a sensor. Capacitive sensors are aesthetically superior, easy to use, and have long lifetimes. The CapSense feature in PSoC 6 BLE offers best-in-class SNR; best-in-class liquid tolerance; and a wide variety of sensor types such as buttons, sliders, track pads, and proximity sensors.

A Cypress-supplied software Component makes capacitive sensing design very easy; the Component supports an automatic hardware-tuning feature called SmartSense and provides a gesture recognition library for trackpads and proximity sensors.

For more information, see the [AN85951 - PSoC 4 and PSoC 6 MCU CapSense Design Guide](#).

The CapSense block has two 7-bit IDACs, which can be used for general purposes if CapSense is not using them. A (slow) 10-bit slope ADC may be realized by using one of the IDACs. Refer to the PSoC 6 BLE CapSense Component datasheet for more information on how to use the slope ADC.

C.5 Programmable GPIOs

The I/O system provides an interface between the CPU cores, the peripherals, and the external devices. PSoC 6 BLE has up to 104 programmable GPIO pins. You can configure the GPIOs for CapSense, LCD, analog, or digital signals. PSoC 6 BLE GPIOs support multiple drive modes, drive strengths, and slew rates.

PSoC 6 BLE offers an intelligent routing system that gives multiple choices for connecting an internal signal to a GPIO. This flexible routing simplifies circuit design and board layout.

Additionally, PSoC 6 BLE includes up to two Smart I/O ports, which can be used to perform Boolean operations on signals going to and coming from the GPIO pin. Smart I/O ports are also operational in Deep-Sleep mode.

Appendix D. Cypress IoT Development Tools

D.1 CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit

The PSoC 6 BLE Pioneer Kit shown in [Figure 69](#) is a BLE development kit from Cypress that supports the PSoC 6 BLE family of devices.

Following are the features of the PSoC 6 BLE Pioneer kit baseboard:

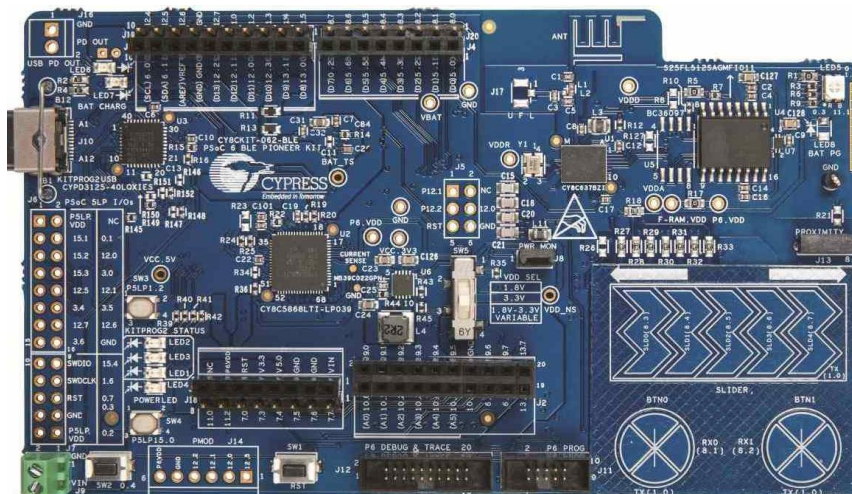
- Can be powered by a coin-cell battery or through the Type-C USB interface. The Type-C USB interface also supports up to 12 V, 3 A power delivery (PD) consumer and provider profiles.
- Enables development of battery-operated low-power BLE designs that work in conjunction with standard, Arduino Uno connector-compliant shields or the onboard PSoC 6 BLE device capabilities, such as the CapSense user interface and serial memory interface.
- Supports third-party programming, debugging, and tracing with the Cortex Debug/ETM connector.
- Includes an additional header that supports interfacing with Pmod™ daughter cards from third-party vendors such as Digilent.
- Supports PDM-PCM microphone for voice-over-BLE functionality.
- Includes QSPI NOR flash and F-RAM.

The kit includes the following:

- A USB-BLE dongle that acts as a BLE link master and works with the CySmart Host Emulation Tool to provide a BLE host emulation platform on non-BLE Windows PCs
- An E-Link display

The kit consists of a set of BLE example projects and documentation that help you get started on developing your own BLE applications. Visit the [CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit](#) webpage to get the latest updates on the kit and download the kit design, example projects, and documentation files.

Figure 69. CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit



D.2 CySmart Host Emulation Tool

The CySmart Host Emulation Tool is a Windows application that emulates a BLE Central device using the PSoC 6 BLE Pioneer Kit's dongle; see [Figure 69](#). It is installed as part of the BLE Pioneer Kit installation and can be launched by right-clicking the BLE Component. It provides a platform for you to test your PSoC 6 BLE Peripheral implementation over GATT or L2CAP connection-oriented channels by allowing you to discover and configure the BLE services, characteristics, and attributes on your Peripheral.

Operations that you can perform with the CySmart Host Emulation Tool include, but are not limited to:

- Scan BLE Peripherals to discover available devices to which you can connect.

- Discover available BLE attributes including services and characteristics on the connected Peripheral device.
- Perform read and write operations on characteristic values and descriptors.
- Receive characteristic notifications and indications from the connected Peripheral device.
- Establish a bond with the connected Peripheral device using BLE Security Manager procedures.
- Establish a BLE L2CAP connection-oriented session with the Peripheral device and exchange data per the Bluetooth 4.2 specification.
- Perform over-the-air (OTA) firmware upgrade of Cypress BLE Peripheral devices.

Figure 70 and Figure 71 show the user interface of the CySmart Host Emulation Tool. For more information on how to set up and use this tool, see the CySmart user guide from the **Help** menu.

Figure 70. CySmart Host Emulation Tool Master Device Tab

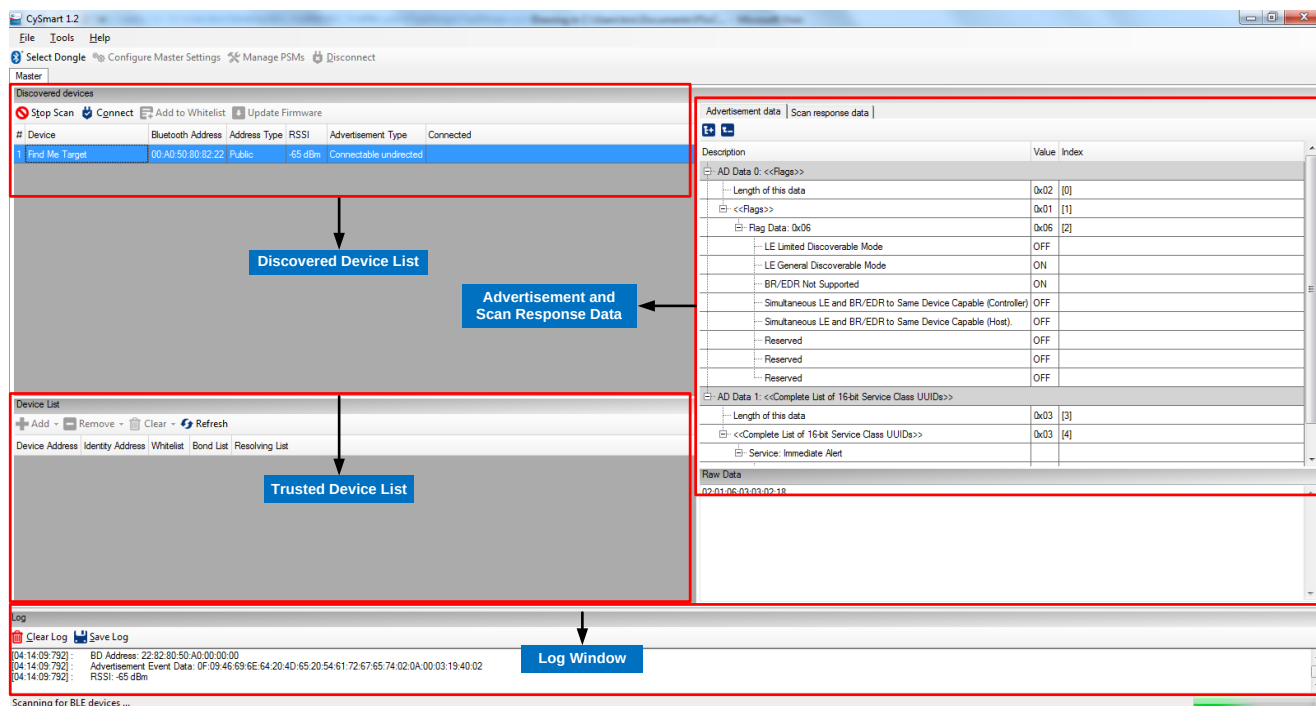
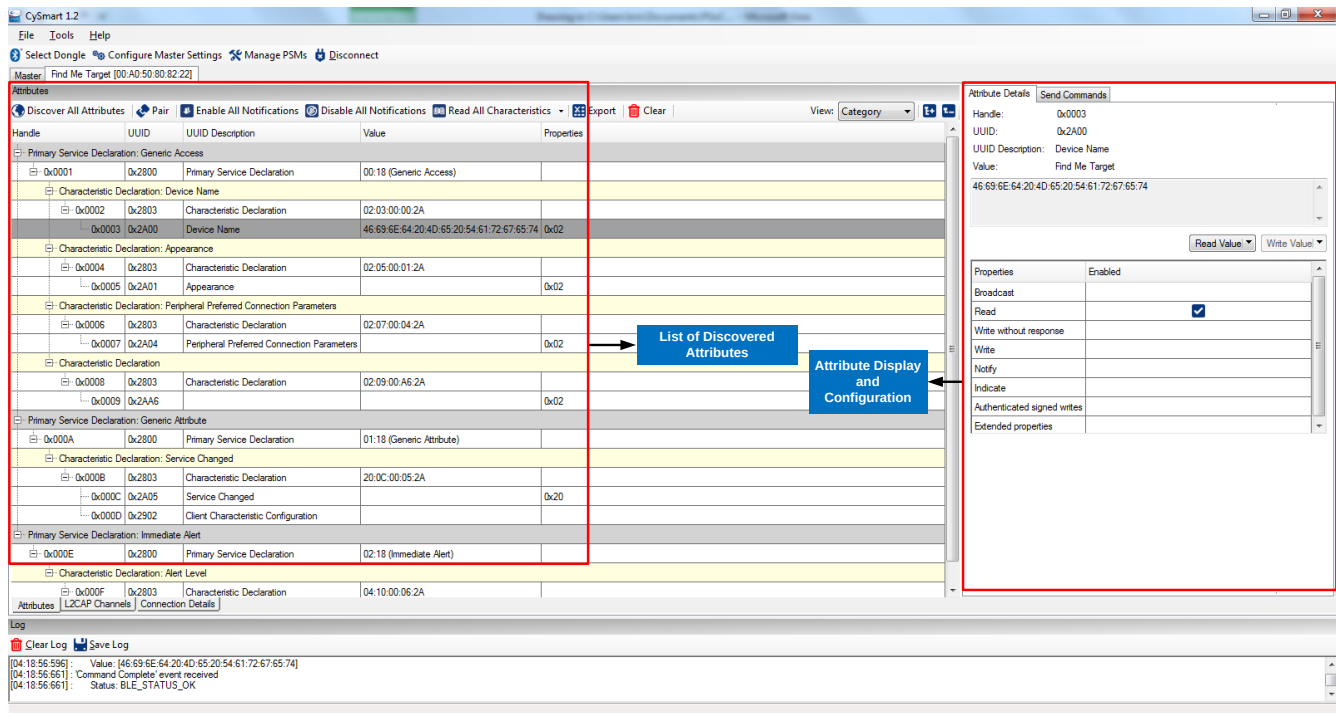


Figure 71. CySmart Host Emulation Tool Peripheral Device Attributes Tab



D.3 CySmart Mobile App

In addition to the PC tool, you can download the CySmart mobile app for iOS or Android from the respective app stores. This app uses the iOS Core Bluetooth framework and the Android built-in platform framework for BLE respectively. It configures your BLE-enabled smartphone as a Central device that can scan and connect to Peripheral devices.

The mobile app supports SIG-adopted BLE standard Profiles through an intuitive GUI and abstracts the underlying BLE service and characteristic details. In addition to the BLE standard profiles, the app demonstrates a custom Profile implementation using Cypress's LED and CapSense demo examples. Figure 72 and Figure 73 show a set of CySmart app screenshots for the Heart Rate Profile user interface. For a description of how to use the app with BLE Pioneer Kit example projects, see the BLE Pioneer Kit guide.

Figure 72. CySmart iOS App Heart Rate Profile Example

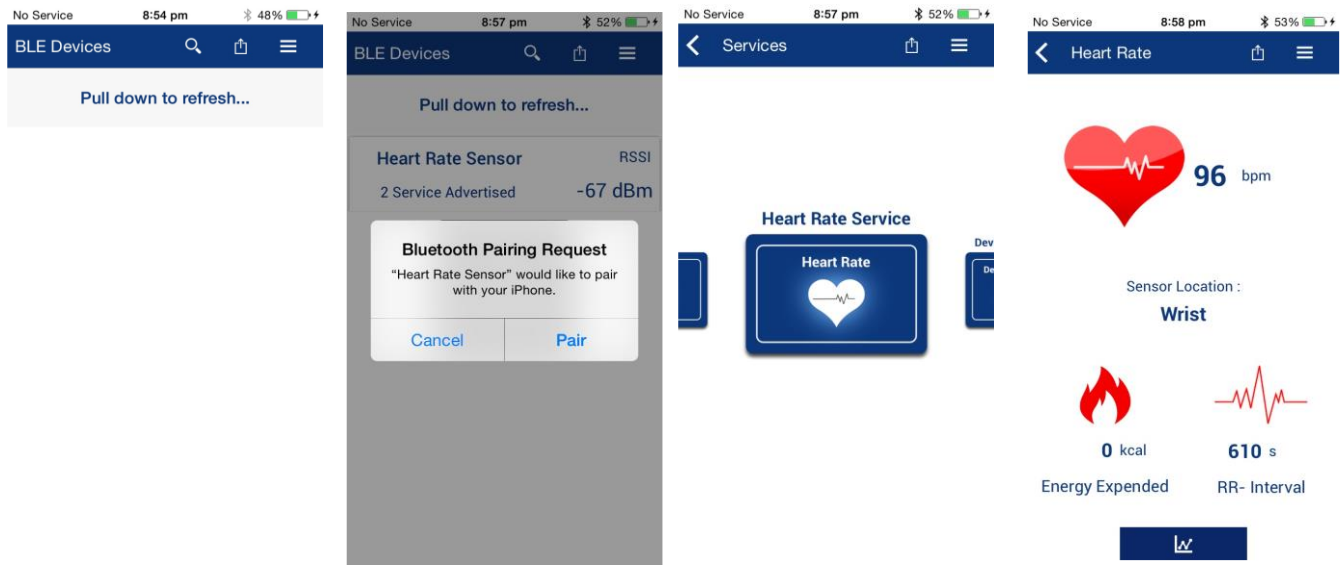
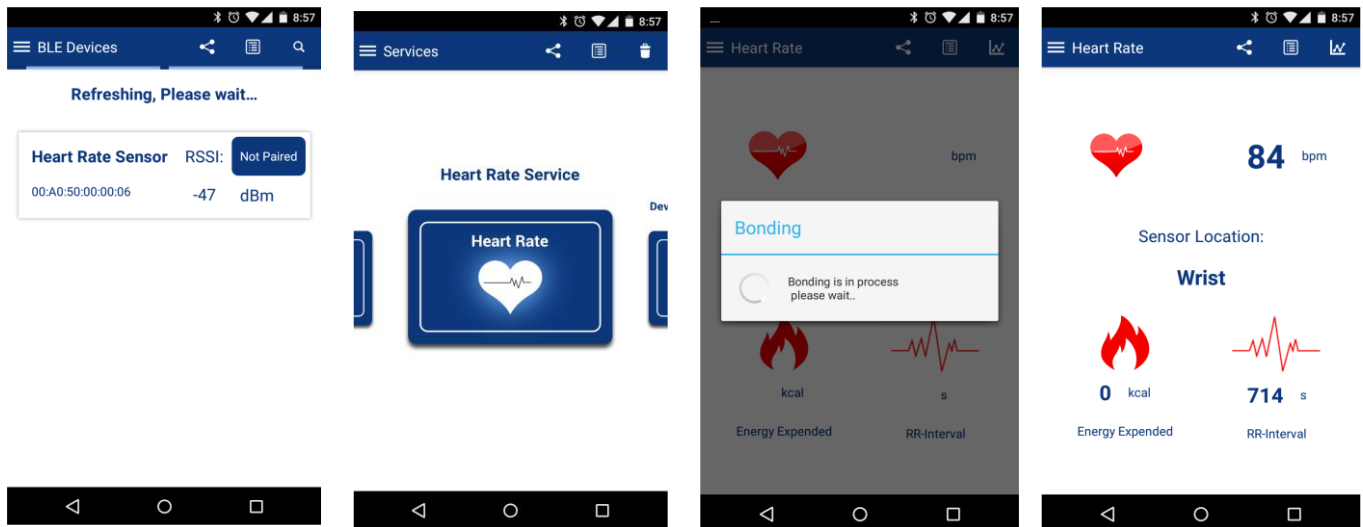


Figure 73. CySmart Android App Heart Rate Profile Example



Document History

Document Title: AN210781 – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity

Document Number: 002-10781

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	5567551	SNVN	12/27/2016	New application note
*A	5655157	SNVN/ JETT	03/09/2017	Rewrite of application note. Updated template.
*B	5859579	SNVN	08/31/2017	Updated title and figures.
*C	6152158	SNVN	04/24/2018	Partial rewrite of application note. Updated template, abstract, and figures.

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](#).

Products

Arm® Cortex® Microcontrollers	cypress.com/arm
Automotive	cypress.com/automotive
Clocks & Buffers	cypress.com/clocks
Interface	cypress.com/interface
Internet of Things	cypress.com/iot
Memory	cypress.com/memory
Microcontrollers	cypress.com/mcu
PSoC	cypress.com/psoc
Power Management ICs	cypress.com/pmic
Touch Sensing	cypress.com/touch
USB Controllers	cypress.com/usb
Wireless Connectivity	cypress.com/wireless

PSoC® Solutions

[PSoC 1](#) | [PSoC 3](#) | [PSoC 4](#) | [PSoC 5LP](#) | [PSoC 6 MCU](#)

Cypress Developer Community

[Forums](#) | [WICED IOT Forums](#) | [Projects](#) | [Videos](#) | [Blogs](#) | [Training](#) | [Components](#)

Technical Support

cypress.com/support

All other trademarks or registered trademarks referenced herein are the property of their respective owners.



Cypress Semiconductor
198 Champion Court
San Jose, CA 95134-1709

© Cypress Semiconductor Corporation, 2016-2018. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress does not assume any liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.